

TUTORIAL CLASS

Tutorial classes in B.Tech education offer supplemental learning opportunities to students beyond traditional lectures. Here are a few words highlighting their significance:

1. **Enhanced Understanding:** Tutorial classes provide a smaller group setting where students can delve deeper into complex topics, ask questions, and seek clarification on concepts covered in lectures. This fosters a better understanding of the subject matter.
2. **Interactive Learning:** Tutorials often involve more interactive sessions, discussions, and problem-solving activities. This active engagement encourages students to participate actively and reinforces their learning.
3. **Personalized Attention:** With fewer students in tutorial groups, instructors can provide more personalized attention to individual students. This allows for tailored guidance, addressing specific learning needs and concerns.
4. **Supplementary Support:** Tutorial classes complement lectures by reinforcing key concepts, offering additional explanations, and providing extra practice exercises or examples to solidify understanding.
5. **Peer Learning:** Collaborative learning is often encouraged in tutorials. Students can learn from their peers, exchange ideas, and work together on problem-solving tasks, enhancing their overall learning experience.
6. **Feedback and Assessment:** Tutorials may offer opportunities for instructors to assess students' progress more closely through quizzes, assignments, or discussions, providing timely feedback to improve learning outcomes.
7. **Improvement of Study Skills:** Tutorial classes can help students develop critical study skills, including analytical thinking, time management, and effective study habits, which are beneficial throughout their academic journey.

In essence, tutorial classes play a vital role in reinforcing knowledge, fostering a deeper understanding of topics, and providing a supportive environment for students to excel in their B.Tech studies.

VIMAL JYOTHI ENGINEERING COLLEGE, CHEMPERI**DEPARTMENT OF ELECTRONICS AND INSTRUMENTATION ENGINEERING****TUTORIAL LOG REGISTER 2021-2025 ADMISSIONS (S1)**

Sl. No	Date	Time	Name of Faculty Member	Batch	Topic	Signature of Faculty Member	Absentees	Proof Material Folder Link
1	12-10-2021	9.00 am to 10.00 am	SIJI.P	Full Class	Chain rule		Nil	https://drive.google.com/file/d/1CU8ODmAIeHc46Ca8LOwjSUWzmeu2Re8U/view?usp=sharing
2	14/1/2022	9.00 am to 10.00 am	SIJI.P	Full Class	Cartesian coordinates		Nil	https://drive.google.com/file/d/1CU8ODmAIeHc46Ca8LOwjSUWzmeu2Re8U/view?usp=sharing
3	28/1/2022	9.00 am to 10.00 am	SIJI.P	Full Class	Geometric series		4,18	https://drive.google.com/file/d/1Hi_BcxbjPWHWRxT8Bki3WG-IIFhtFvb/view?usp=sharing
4	02-11-2022	9.00 am to 10.00 am	SIJI.P	Full Class	Taylor series		14,18,20,24	https://drive.google.com/file/d/1yYK0E54ZkKmQmes6FPnH0GeURt0mijk4/view?usp=sharing
5	25/2/2022	9.00 am to 10.00 am	SIJI.P	Full Class	Fourier series		Nil	https://drive.google.com/file/d/1yYK0E54ZkKmQmes6FPnH0GeURt0mijk4/view?usp=sharing
6	03-04-2022	9.00 am to 10.00 am	SIJI.P	Full Class	Fourier series		3,16,17	https://drive.google.com/file/d/1yYK0E54ZkKmQmes6FPnH0GeURt0mijk4/view?usp=sharing

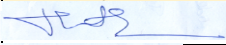
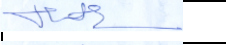
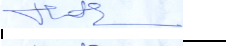
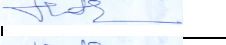
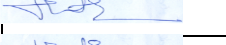
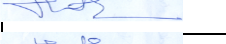
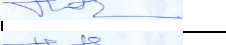
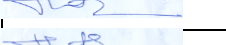
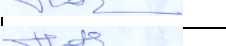
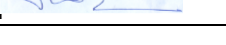
VIMAL JYOTHI ENGINEERING COLLEGE, CHEMPERI

DEPARTMENT OF ELECTRONICS AND INSTRUMENTATION ENGINEERING

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Sl. No	Date	Time	Name of Faculty Member	Batch	Topic	Signature of Faculty Member	Absentees	Proof Material Folder Link
1	08-12-2021	12.10 - 1.10 PM	Soumya John	Full Class	Laws of vibration		Nil	https://drive.google.com/file/d/1hoA2Pt4VXqj8ULK0H99N-4lAtuE6XYfP/view?usp=sharing
2	06-01-2022	12.10 - 1.10 PM	Soumya John	Full Class	Resolving & dispersive power		12,14,15,28,30,31	https://drive.google.com/file/d/1-zAtoYrQN79UT6EqarNnB1q5KrKtqAAAd/view?usp=sharing
3	27-01-2022	12.10 - 1.10 PM	Soumya John	Full Class	Nanotechnology		Nil	https://drive.google.com/file/d/15EizyBi5RI8gFtGFrobmhJW3aMXnrVix/view?usp=sharing
4	03-02-2022	12.10 - 1.10 PM	Soumya John	Full Class	Types of superconductors, BCS theory		Nil	https://drive.google.com/file/d/14W21WVfoOmtlaFYh50o8E4nmRuIEkLjN/view?usp=sharing
5	17-02-2022	12.10 - 1.10 PM	Soumya John	Full Class	Optic fibre sensors		Nil	https://drive.google.com/file/d/14W21WVfoOmtlaFYh50o8E4nmRuIEkLjN/view?usp=sharing










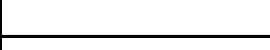
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Sl. No	Date	Time	Name of Faculty Member	Batch	Topic	Signature of Faculty Member	Absentees	Proof Material Folder Link
1	03.12.2021	11.10-12.10	Dr.S.Christopher Ezhil Singh	Full Class	equilibrium equations problems		5	https://drive.google.com/file/d/1vuhXjoewz3CIRHbZhASSq1dQfO-DUAL-/view?usp=sharing
3	17.12.2021	11.10-12.10	Dr.S.Christopher Ezhil Singh	Full Class	varignon's Theorem of moments problems		Nil	
5	14.01.2022	11.10-12.10	Dr.S.Christopher Ezhil Singh	Full Class	ladder Problem		Nil	
6	21.01.2022	11.10-12.10	Dr.S.Christopher Ezhil Singh	Full Class	resultant and equilibrium equations Problems		Nil	
7	28.01.2022	11.10-12.10	Dr.S.Christopher Ezhil Singh	Full Class	Centroid of composite areas problems		Nil	
8	04.02.2022	11.10-12.10	Dr.S.Christopher Ezhil Singh	Full Class	moment of inertia problems		Nil	
9	11.02.2022	11.10-12.10	Dr.S.Christopher Ezhil Singh	Full Class	Forces in space problems		Nil	
10	18.02.2022	11.10-12.10	Dr.S.Christopher Ezhil Singh	Full Class	D'Alembert's principle problems		Nil	
11	25.02.2022	11.10-12.10	Dr.S.Christopher Ezhil Singh	Full Class	projectile motion problem		Nil	
12	04.03.2022	11.10-12.10	Dr.S.Christopher Ezhil Singh	Full Class	Simple harmonic motion problem		Nil	

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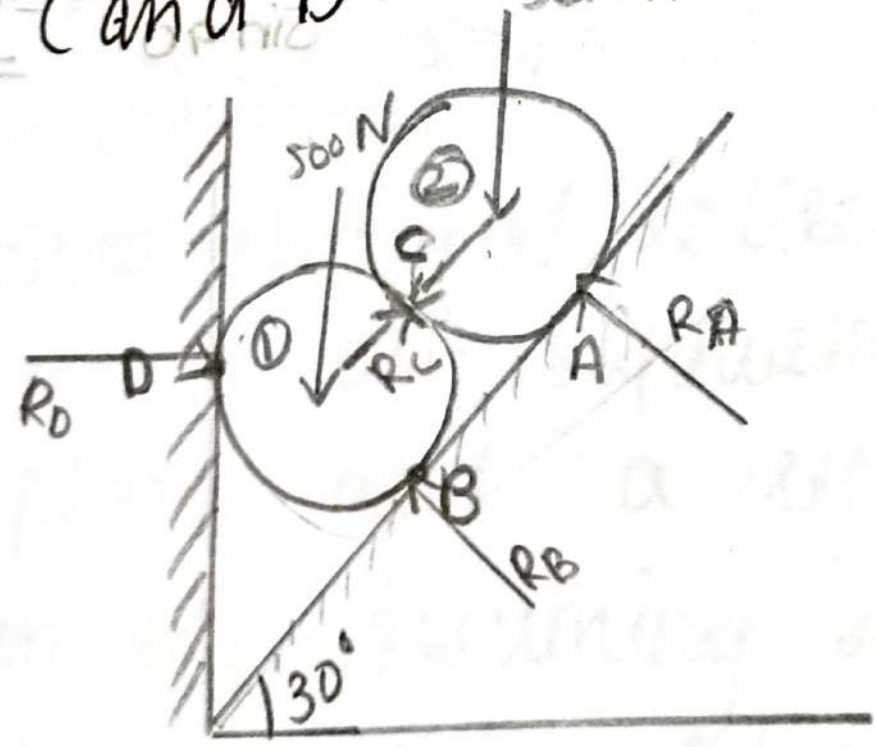
DEPARTMENT OF ELECTRICAL & ELECTRONICS

TUTORIAL LOG REGISTER 2021-2025 ADMISSIONS (S1)

Sl. No	Date	Time	Name of Faculty Member	Topic	Signature of Faculty Member	Presente	Proof Material Folder Link
1	03.12.2021	11.10-12.10	Dr.S.Christopher Ezhil Singh	equilibrium equations problems		5	
3	17.12.2021	11.10-12.10	Dr.S.Christopher Ezhil Singh	Varignon's Theorem of moments problems		Nil	
5	14.01.2022	11.10-12.10	Dr.S.Christopher Ezhil Singh	ladder Problem		Nil	
6	21.01.2022	11.10-12.10	Dr.S.Christopher Ezhil Singh	resultant and equilibrium equations Problems		Nil	
7	28.01.2022	11.10-12.10	Dr.S.Christopher Ezhil Singh	Centroid of composite areas problems		Nil	
8	04.02.2022	11.10-12.10	Dr.S.Christopher Ezhil Singh	moment of inertia problems		Nil	
9	11.02.2022	11.10-12.10	Dr.S.Christopher Ezhil Singh	Forces in space problems		Nil	
10	18.02.2022	11.10-12.10	Dr.S.Christopher Ezhil Singh	D'Alembert's principle problems		Nil	
11	25.02.2022	11.10-12.10	Dr.S.Christopher Ezhil Singh	projectile motion problem		Nil	
12	04.03.2022	11.10-12.10	Dr.S.Christopher Ezhil Singh	Simple harmonic motion problem		Nil	

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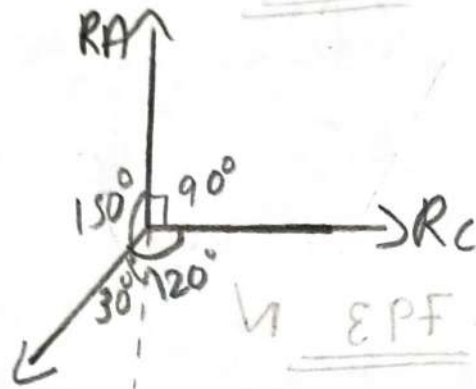
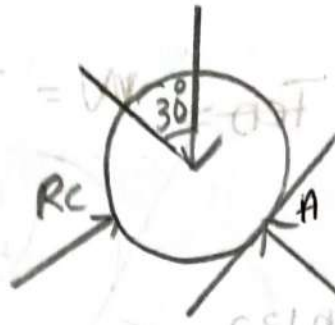
* Two identical rollers each of weight 500 N are supported by an inclined plane and a vertical wall as shown in fig. Assuming smooth surfaces. Find the reactions induced at the points A, B, C and D.



$$= \frac{R_A}{\sin 150} = \frac{500}{\sin 150}$$

① - roller

Roller ②

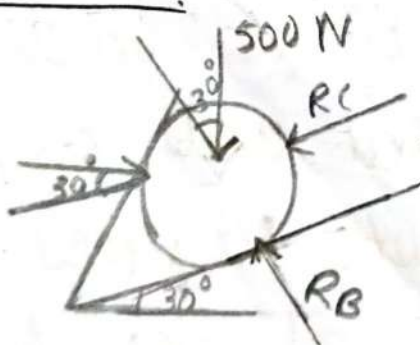


$$\frac{500}{\sin 90} = \frac{R_C}{\sin 150} = \frac{R_A}{\sin 120}$$

$$\frac{500}{\sin 90} = \frac{R_C}{\sin 150} \Rightarrow R_C = \frac{500 \times \sin 150}{\sin 90} = 250 \text{ N}$$

$$\frac{500}{\sin 90} = \frac{R_A}{\sin 120} \Rightarrow R_A = \frac{500 \times \sin 120}{\sin 90} = 433 \text{ N}$$

Roller-①



Equilibrium conditions for coplanar concurrent forces

$$\sum F_x = 0$$

$$\sum F_y = 0$$

consider the forces || to the plane.

$$-R_C - 500 \sin 30^\circ + R_D \cos 30^\circ = 0 \rightarrow \textcircled{1}$$

consider the forces Normal to the plane
(\perp)

$$R_B - 500 \cos 30^\circ + R_D \sin 30^\circ = 0 \rightarrow \textcircled{2}$$

~~250 - 500~~ substitute the value of R_C in

eq. $\textcircled{1}$

$$-250 - 500 \sin 30^\circ + R_D \cos 30^\circ = 0$$

$$\underline{R_D = 577 \text{ N}} \quad R_D = \underline{577 \text{ N}}$$

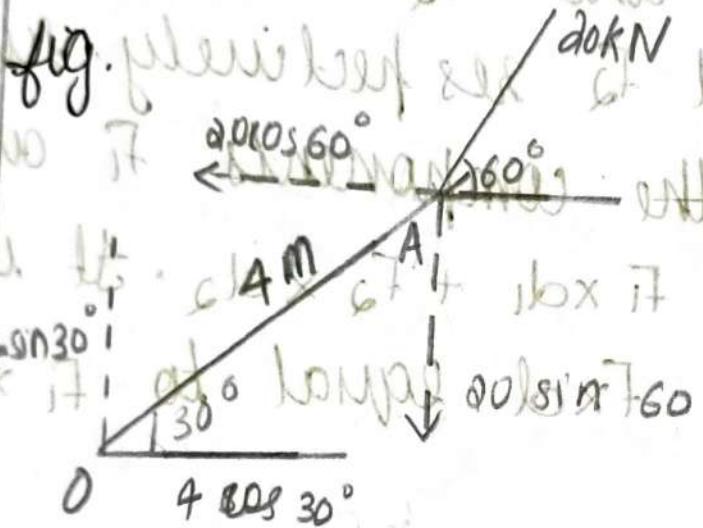
Value of R_D in eq. $\textcircled{2}$

$$R_B - 500 \cos 30^\circ - 577 \sin 30^\circ = 0$$

$$R_B = 500 \cos 30^\circ + 577 \sin 30^\circ$$

$$\underline{R_B = 721.5 \text{ N}}$$

* Calculate the moment of the given force F about point O as shown in



Moment about the point, O

clock wise direction
moment = +
anti clock wise direction
moment = -

Moment about point O ,

$$M_O = [20 \sin 60^\circ \times 4 \cos 30^\circ] - [20 \cos 60^\circ \times 4 \sin 30^\circ]$$

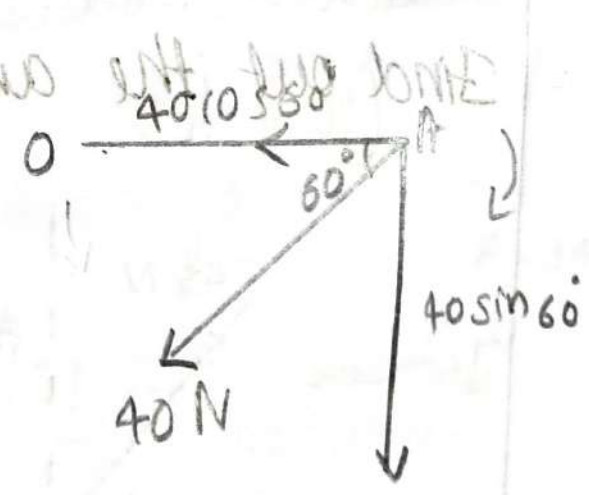
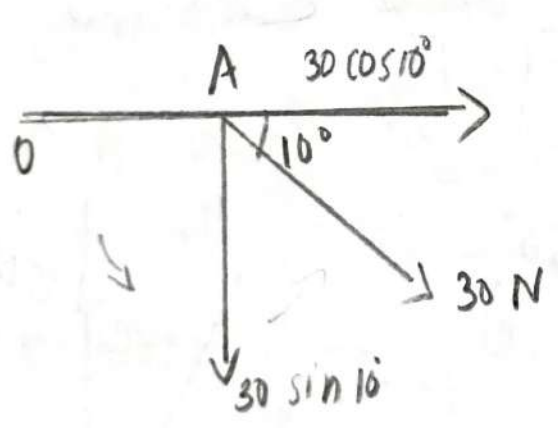
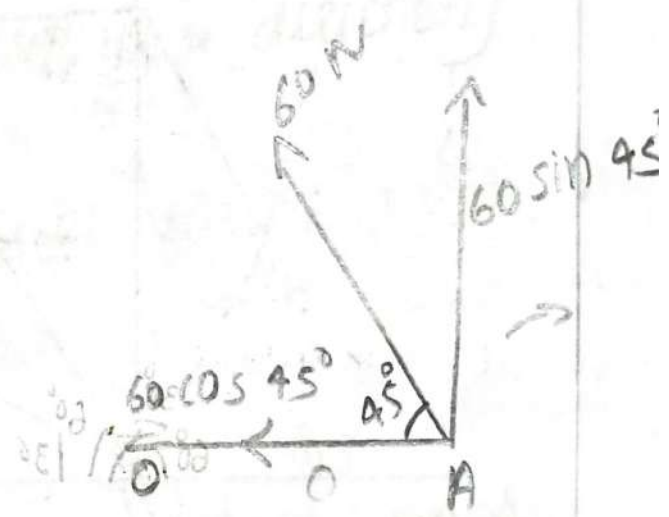
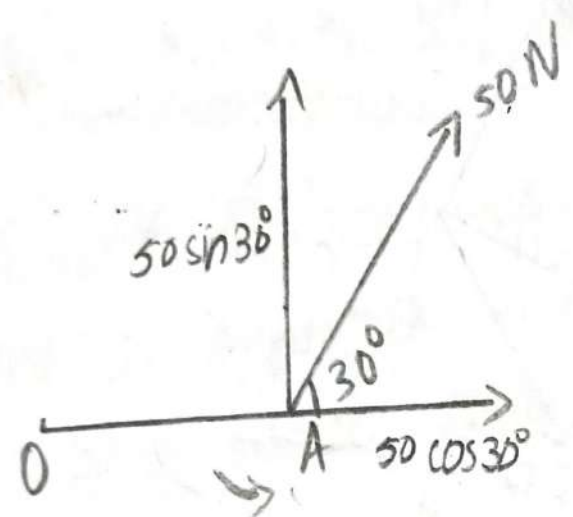
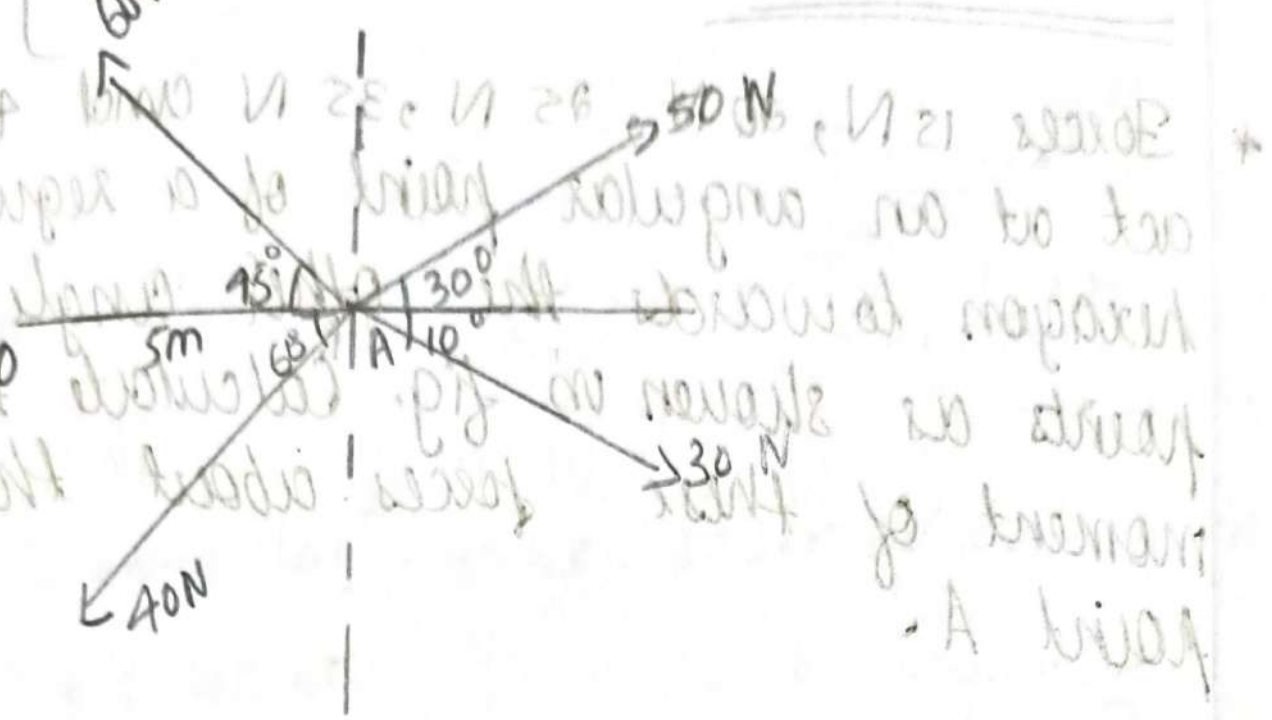
$$= 60 - 20$$

~~$M_O = 40$~~ $M_O = 40 \text{ kNm}$ (clock wise direction)

* Calculate the moment of the system shown in fig about the point

using Varignon's theorem

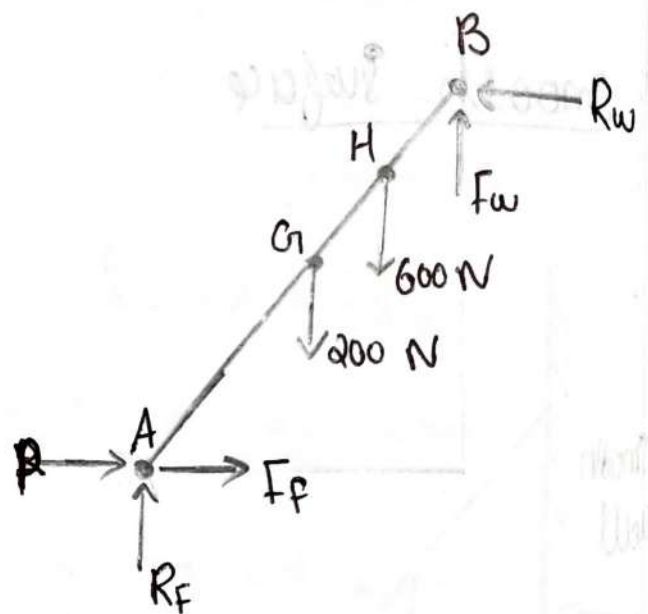
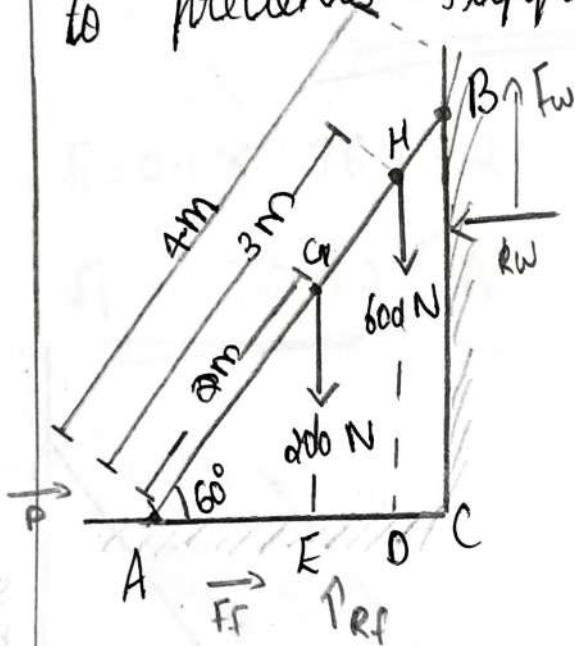
$\sum M_A = 0$



$$M_A = -50 \sin 30^\circ \times 5 + 30 \sin 10^\circ \times 5 + 60 \sin 45^\circ \times 5 + 40 \sin 60^\circ \times 5$$

$$\underline{M_0 = -137.8 \text{ Nm}} \quad (\text{Anticlockwise direction})$$

* A ladder of length 4 m, weight 200 N is placed against a vertical wall as shown in fig. μ b/w the wall & the ladder is 0.2 and that b/w floor & the ladder is 0.3. In addition to self weight the ladder has a support a man of weight 600 N at a distance of 3 m from A. Calculate the minimum horizontal force to be applied at A to prevent slipping.



$$\cos \theta = A/H, \quad \sin \theta = O/H$$

~~For~~ ΔADE ,

$$\cos 60^\circ = \frac{AE}{2}$$

$$AE = 2 \times \cos 66^\circ$$

$$\underline{AE = 1 \text{ m}}$$

ΔADH

$$\cos 60^\circ = \frac{AD}{3}$$

$$AD = 3 \times \cos 66^\circ$$

$$\underline{AD = 1.5 \text{ m}}$$

ΔABC

$$\sin 60^\circ = \frac{BC}{4} \Rightarrow BC = 4 \times \sin 60^\circ$$

$$\underline{BC = 3.464 \text{ m}}$$

Moment about point A

$$200 \times 1 + 600 \times 1.5 - F_w \times 2 - R_w \times 3.46 = 0$$

$$F_w = \mu R_w = \underline{0.2 R_w}$$

$$1100 - 0.4 R_w - 3.46 R_w = 0$$

$$1100 - 3.86 R_w = 0$$

$$1100 = 3.86 R_w$$

$$R_w = \frac{1100}{3.86}$$

$$\underline{R_w = 284.97}$$

$$\cos 66^\circ = \frac{AC}{4}$$

$$AC = 4 \times \cos 66^\circ$$

$$\underline{AC = 2 \text{ m}}$$

Equilibrium condition

$$\sum H = 0$$

$$F_f + P - RW = 0$$

$$\sum V = 0$$

$$R_f - 200 - 600 + f_w = 0$$

$$R_f - 200 - 600 + [0.2RW] = 0$$

$$R_f - 200 - 600 + 56.99 = 0$$

$$R_f - 800 + 56.99 = 0$$

$$R_f - = 743.01 = 0$$

$$\underline{R_f = 743.01 \text{ N}}$$

$$F_f = 0.3 \times R_f$$

$$[0.3 \times 743.01] = F_f$$

$$\underline{F_f = 222.90 \text{ N}}$$

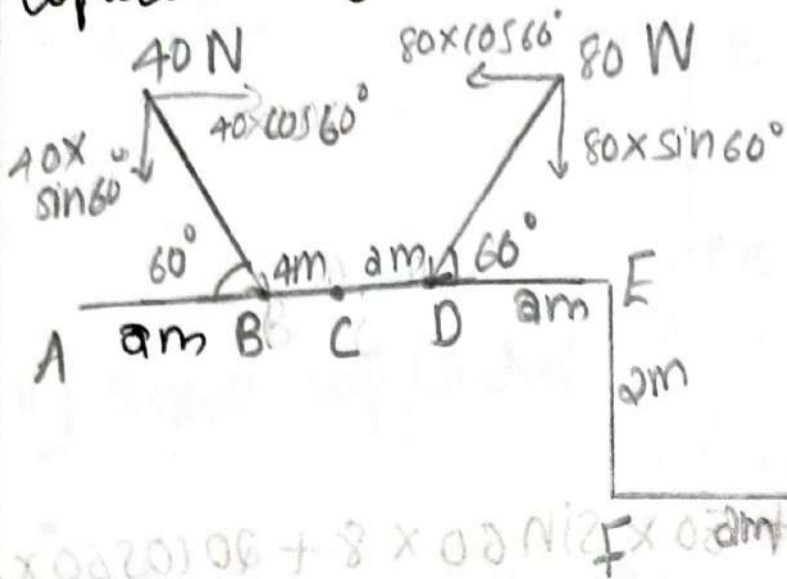
$$F_f + P - RW = 0$$

$$222.9 + P - 284.97 = 0$$

$$P = 284.97 - 222.9$$

$$\underline{P = 62 \text{ N}}$$

* Determine the resultant of a set of coplanar forces as shown in fig.



$$\rightarrow \sum V = 0$$

$$\sum H = 0$$

$$\sum H = 40 \times \cos 60^\circ - 80 \times \cos 60^\circ - 20 \times \cos 60^\circ$$

$$= 20 - 40 - 10$$

$$\underline{\underline{\sum H = -30}}$$

$$\sum V = 0$$

$$\sum V = -40 \times \sin 60^\circ - 80 \times \sin 60^\circ - 20 \times \sin 60^\circ$$

$$= -34.64 - 69.28 - 17.32$$

$$\underline{\underline{\sum V = -121.24}}$$

$$R = \sqrt{\sum H^2 + \sum V^2} = \sqrt{(-30)^2 + (-121.24)^2}$$

$$\underline{\underline{R = 124.89 \text{ N}}}$$

$$\tan \theta = \frac{\sum V}{\sum H} = \frac{121.24}{30}$$

$$\theta = \tan^{-1}(4.04)$$

$$\theta = \underline{\underline{76.09^\circ}}$$

$$\sum M_A = 0$$

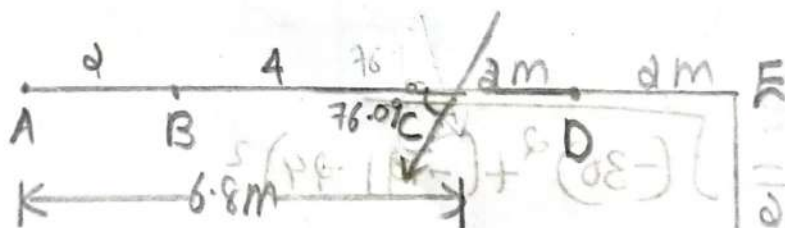
$$\sum M_A = 40 \times \sin 60^\circ \times 2 + 80 \times \sin 60^\circ \times 8 + 20 \cos 60^\circ \times 2 + 20 \sin 60^\circ \times 12$$

$$= 69.28 + 554.25 + 20 + 207.84 = 851.37 \text{ kNm}$$

$$\sum M_A = \underline{\underline{851.37 \text{ kNm [clockwise]}}}$$

$$\sum M_A = R_y \times X$$

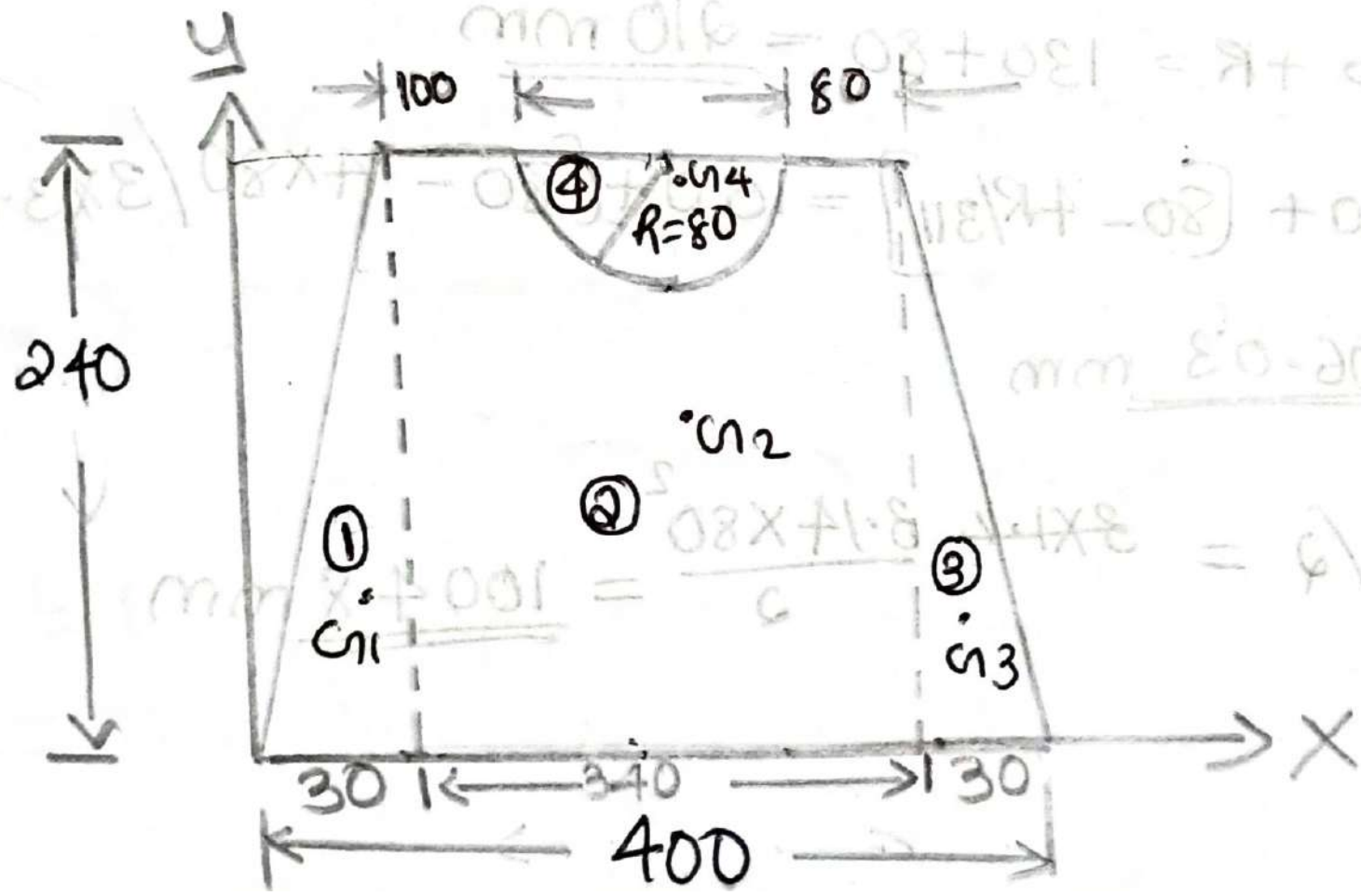
$$X = \frac{\sum M_A}{R_y} = \frac{851.37}{121.24} = \underline{\underline{6.8 \text{ m}}}$$



Handwritten signature and date: 20/12/21

* locate the centroid for the figure shown.

locate the centroid for the figure shown.



$$100 + 80 + 160 = 340$$

$$400 - 340 = 60$$

$$\frac{60}{2} = 30$$

Section-1

$$x_1 = \frac{2b}{3} = \frac{2}{3} \times 30 = \underline{\underline{20 \text{ mm}}}$$

$$y_1 = \frac{b}{3} \frac{h}{3} = \frac{240}{3} = \underline{\underline{80 \text{ mm}}}$$

$$a_1 = \frac{bh}{3} = \frac{30 \times 240}{2} = \underline{\underline{3600 \text{ mm}}}$$

Section-2

$$x_2 = 30 + b/2 = 30 + 340/2 = \underline{\underline{200 \text{ mm}}}$$

$$y_2 = h/2 = 240/2 = \underline{\underline{120 \text{ mm}}}$$

$$a_2 = bh = 340 \times 240 = \underline{\underline{81600 \text{ mm}}}$$

Section-3

$$x_3 = 370 + b/3 = 370 + 30/3 = \underline{\underline{380 \text{ mm}}}$$

$$y_3 = h/3 = 240/3 = \underline{\underline{80 \text{ mm}}}$$

$$a_3 = bh/2 = \frac{30 \times 240}{2} = \underline{\underline{3600 \text{ mm}}}$$

Section-4

$$x_4 = 130 + R = 130 + 80 = \underline{\underline{210 \text{ mm}}}$$

$$y_4 = 160 + \left[80 - \frac{4R}{3\pi} \right] = 160 + \left[80 - \frac{4 \times 80}{3 \times 3.14} \right]$$
$$= \underline{\underline{206.03 \text{ mm}}}$$

$$a_4 = \pi R^2 / 2 = \frac{3.14 \times 80^2}{2} = \underline{\underline{10048 \text{ mm}}}$$

$$\bar{x} = \frac{a_1x_1 + a_2x_2 + a_3x_3 - a_4x_4}{a_1 + a_2 + a_3 - a_4}$$

$$= \frac{[3600 \times 20] + [81600 \times 200] + [3600 \times 380] - [10048 \times 210]}{3600 + 81600 + 3600 - 10048}$$

$$= \frac{72000 + 16320000 + 1368000 - 2110080}{78752}$$

$$= \frac{15649920}{78752}$$

$$\bar{x} = 198.72 \text{ mm}$$

$$\bar{y} = \frac{a_1y_1 + a_2y_2 + a_3y_3 - a_4y_4}{a_1 + a_2 + a_3 - a_4}$$

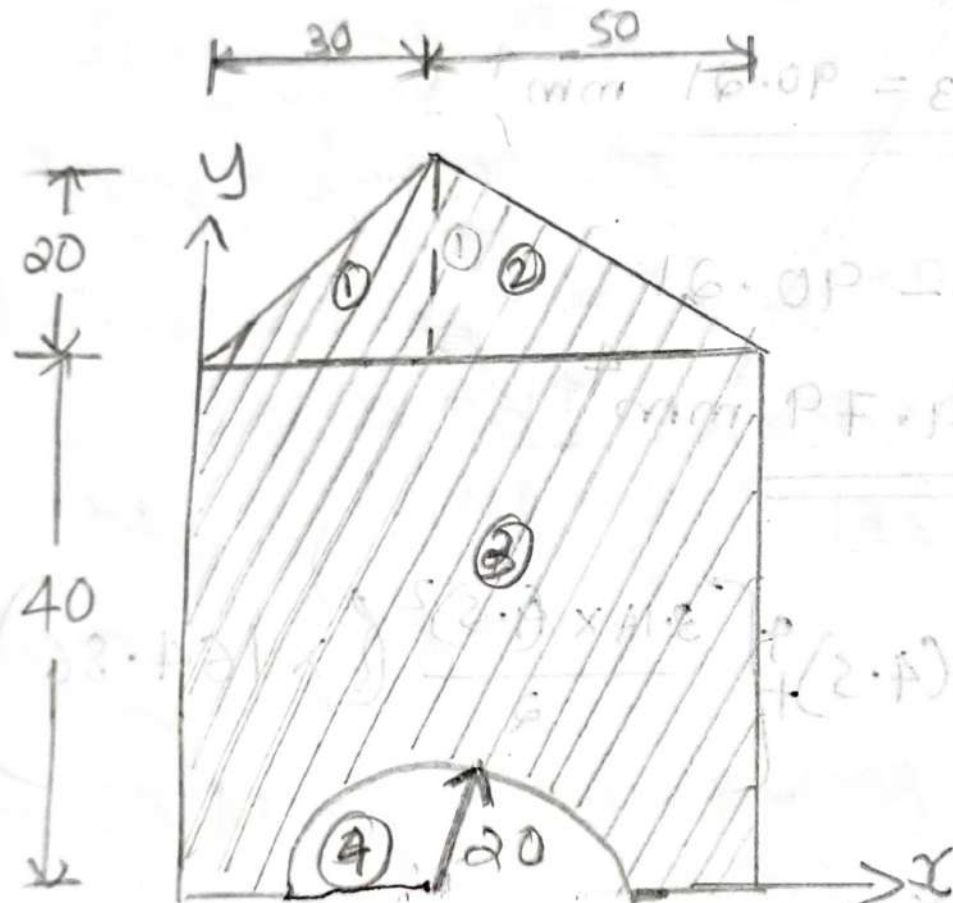
$$= \frac{[3600 \times 80] + [81600 \times 120] + [3600 \times 80] - [10048 \times 206.63]}{78752}$$

~~$$= \frac{288000 + 9792000 + 288000 - 2066300}{78752}$$~~

$$= \frac{8297810.56}{78752}$$

$$\bar{y} = 105.36 \text{ mm}$$

* Find the moment of inertia of the shaded portion



← 20 → 20 → ← 20 → 20 →

Section-1

$$x_1 = \frac{ab}{3} = \frac{2 \times 30}{3} = \underline{\underline{20 \text{ mm}}}$$

$$y_1 = \frac{h}{3} + 40 = \frac{20}{3} + 40 = \underline{\underline{46.66 \text{ mm}}}$$

$$a_1 = \frac{bh}{2} = \frac{20 \times 30}{2} = \underline{\underline{300 \text{ mm}^2}}$$

Section-2

$$x_2 = 30 + \frac{50}{3} = \underline{\underline{46.66 \text{ mm}}}$$

$$y_2 = \frac{h}{3} + 40 = \frac{20}{3} + 40 = \underline{\underline{46.66 \text{ mm}}}$$

$$a_2 = \frac{bh}{2} = \frac{20 \times 50}{2} = \underline{\underline{500 \text{ mm}^2}}$$

Section-3

$$x_3 = \frac{l}{2} = \frac{80}{2} = \underline{\underline{40 \text{ mm}}}$$

$$y_3 = \frac{h}{2} = \frac{40}{2} = \underline{\underline{20 \text{ mm}}}$$

$$a_3 = l \times h = 80 \times 40 = \underline{\underline{3200 \text{ mm}^2}}$$

Section-4

$$x_4 = 400 \text{ mm}$$

$$y_4 = \frac{4R}{3\pi} = \frac{4 \times 20}{3 \times 3.14} = \underline{\underline{8.492 \text{ mm}}}$$

$$y_4 = \frac{4R}{3\pi} = \frac{4 \times 20}{3 \times 3.14} = 8.492 \text{ mm}$$

$$a_4 = \frac{\pi R^2}{2} = \frac{3.14 \times 20^2}{2} = \underline{\underline{628 \text{ mm}^2}}$$

$$\bar{x} = \frac{a_3 x_3 - a_4 x_4 + a_1 x_1 + a_2 x_2}{a_3 - a_4 + a_1 + a_2}$$

$$= \frac{(3200 \times 40) - (628 \times 40) + (300 \times 0) + (500 \times 46.66)}{3200 - 628 + 300 + 500}$$

$$\bar{x} = 39.20 \text{ mm}$$

$$\bar{y} = \frac{a_3 y_3 - a_4 y_4 + a_1 y_1 + a_2 y_2}{a_3 - a_4 + a_1 + a_2}$$

$$= \frac{(3200 \times 20) - [628 \times 8.49] + (300 \times 46.66) + (500 \times 46.66)}{3200 - 628 + 300 + 500}$$

$$\bar{y} = 28.46 \text{ mm}$$

$$I_{c_{xx}} = I_{c_{xx3}} - I_{c_{xx4}} + I_{c_{xx1}} + I_{c_{xx2}}$$

$$I_{c_{xx3}} = \frac{bd^3}{12} + A_3 h_3^2$$

$$h_3 = \bar{y} \approx y_3$$

$$= 28.47 - 20$$

$$h_3 = 8.470 \text{ mm}$$

$$I_{xxx3} = \frac{bd^3}{12} + I_{xb} \times (8.47)^2$$

$$= \frac{80 \times 40^3}{12} + 40 \times 80 \times (8.47)^2$$

$$= \underline{\underline{656237.5 \text{ mm}^4}}$$

$$I_{xxx4} = 0.11R^4 + A_4h_4^2$$

$$h_4 = \bar{y} \approx y_2$$

$$= 28.468 - 8.49$$

$$= \underline{\underline{19.978 \text{ mm}}}$$

$$I_{xxx4} = 0.11(20)^4 + \left[\frac{\pi R^2}{2} \times 19.978^2 \right]$$

$$268247.664$$

$$= \underline{\underline{3046184 \text{ mm}^4}}$$

$$I_{xxx1} = \frac{2 \times bd^3}{12} + A_1h_1^2$$

$$h_1 = \bar{y} \approx y_2$$

$$= 46.66 - 28.47 = \underline{\underline{18.19 \text{ mm}}}$$

$$I_{xxx1} = \frac{80 \times (60)^3}{12} + \left[\frac{1}{2} \times 80 \times 60 \right] \times 18.19^2$$

$$= \underline{\underline{105929.43 \text{ mm}^4}}$$

$$I_{xxx2} = \frac{bd^3}{12} + A_2h_2^2$$

$$= \frac{50 \times (20)^3}{36} \times \frac{1}{2} \times 50 \times 20 \times 18 \cdot 19^2$$

$$= \underline{\underline{176549.16 \text{ mm}^4}}$$

$$I_{c_{xx}} = 656237.5 - 268247.664 +$$

$$105929.43 + 176549.16$$

$$I_{c_{xx}} = \underline{\underline{670468.426 \text{ mm}^4}}$$

IMP
* Forces 30 kN, 20 kN, 25 kN, 40 kN
all concurrent at origin and are
directed through the points
 $A = (2, 1, 6)$, $B = (4, -2, 5)$, $C = (-3, -2, 1)$,
 $D = (5, 1, -2)$. Determine the resultant
forces.
 $O = (0, 0, 0)$

$$\text{unit vector of OA} = \frac{\text{position vector of OA}}{\text{magnitude of position}}$$

$$= \frac{(x_A - x_0)\vec{i} + (y_A - y_0)\vec{j} + (z_A - z_0)\vec{k}}{\sqrt{2^2 + 1^2 + 6^2}}$$

$$= \frac{(2-0)\vec{i} + (1-0)\vec{j} + (6-0)\vec{k}}{\sqrt{41}}$$

$$= \frac{2\vec{i} + 1\vec{j} + 6\vec{k}}{\sqrt{41}}$$

$$= \frac{2\vec{i} + 1\vec{j} + 6\vec{k}}{\sqrt{41}} = \frac{2\vec{i} + 1\vec{j} + 6\vec{k}}{6.4} = \frac{0.31\vec{i} + 0.15\vec{j} + 0.93\vec{k}}{1}$$

$$\text{Force vector of OA} = 30 \times \left(\frac{2\vec{i}}{\sqrt{41}} + \frac{1\vec{j}}{\sqrt{41}} + \frac{6\vec{k}}{\sqrt{41}} \right)$$

$$= 30 \times (0.31\vec{i} + 0.15\vec{j} + 0.93\vec{k})$$

$$= 9.3\vec{i} + 4.5\vec{j} + 27.9\vec{k}$$

$$= \underline{\underline{9.3\vec{i} + 4.5\vec{j} + 27.9\vec{k}}}$$

$$\text{Unit of vector of OB} = \frac{\text{position vector of OB}}{\text{magnitude of position}}$$

$$= \frac{4\vec{i} - 2\vec{j} + 5\vec{k}}{\sqrt{45}} = \frac{4\vec{i}}{6.7} - \frac{2\vec{j}}{6.7} + \frac{5\vec{k}}{6.7}$$

$$= 0.59\vec{i} - 0.29\vec{j} + 0.74\vec{k}$$

Force vector of OB = $20 \times (0.59\vec{i} - 0.29\vec{j} + 0.74\vec{k})$

$$= 11.8\vec{i} - 5.8\vec{j} + 14.8\vec{k}$$

unit vector of OC = $\frac{-3\vec{i} - 2\vec{j} + 1\vec{k}}{\sqrt{14}}$

$$= \frac{-3\vec{i}}{\sqrt{14}} - \frac{2\vec{j}}{\sqrt{14}} + \frac{1\vec{k}}{\sqrt{14}}$$

$$= -0.80\vec{i} - 0.53\vec{j} + 0.26\vec{k}$$

Force vector of OC = $25 \times (-0.80\vec{i} - 0.53\vec{j} + 0.26\vec{k})$

$$= -20\vec{i} - 13.25\vec{j} + 6.5\vec{k}$$

unit vector of OD = $\frac{5\vec{i} + 1\vec{j} - 2\vec{k}}{\sqrt{30}}$

$$= \frac{5\vec{i}}{\sqrt{30}} + \frac{1\vec{j}}{\sqrt{30}} - \frac{2\vec{k}}{\sqrt{30}}$$

$$= 0.91\vec{i} + 0.18\vec{j} - 0.36\vec{k}$$

$$\text{Force vector of OD} = 40 \times (0.91\vec{i} + 0.18\vec{j} - 0.36\vec{k})$$

$$= \underline{\underline{36.4\vec{i} + 7.2\vec{j} - 14.4\vec{k}}}$$

$$R = \vec{F}_{OA} + \vec{F}_{OB} + \vec{F}_{OC} + \vec{F}_{OD}$$

$$= (9.3\vec{i} + 4.5\vec{j} + 27.9\vec{k}) + (11.8\vec{i} - 5.8\vec{j} + 14.8\vec{k})$$

$$+ (-20\vec{i} - 13.2\vec{j} + 6.5\vec{k}) + (36.4\vec{i} + 7.2\vec{j} - 14.4\vec{k})$$

$$= (9.3 + 11.8 - 20 + 36.4)\vec{i} + (4.5 - 5.8 - 13.2 + 7.2)\vec{j}$$

$$+ (27.9 + 14.8 + 6.5 - 14.4)\vec{k}$$

$$R = \underline{\underline{37.5\vec{i} - 7.3\vec{j} + 34.8\vec{k}}}$$

$$\text{Magnitude of } R = \sqrt{(37.5)^2 + (-7.3)^2 + (34.8)^2}$$

$$= \underline{\underline{51.68 \text{ Nm}}}$$

$$\theta_x = \cos^{-1} \left[\frac{R_x}{R} \right] = \cos^{-1} \left[\frac{37.5}{51.68} \right]$$

$$\theta_x = \underline{\underline{43.47^\circ}}$$

$$\theta_y = \frac{R_y}{R} \cos^{-1} \left[\frac{R_y}{R} \right] = \cos^{-1} \left[\frac{-7.35}{51.68} \right]$$

$$\theta_y = \underline{\underline{-48.17^\circ}}$$

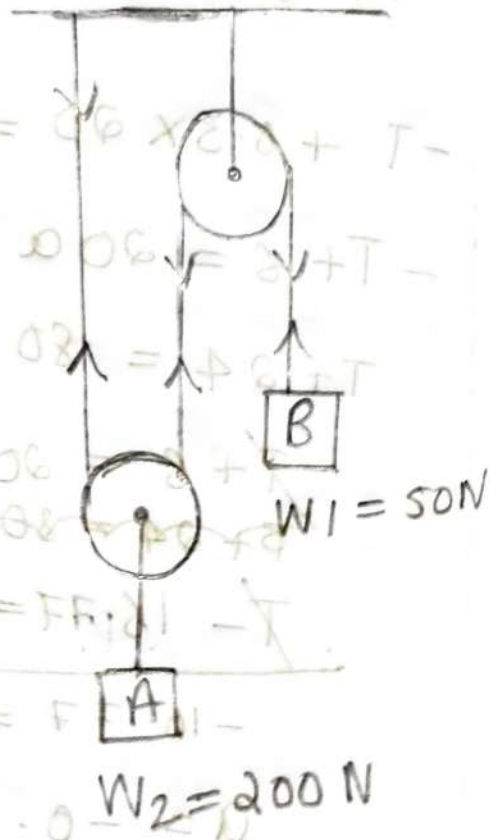
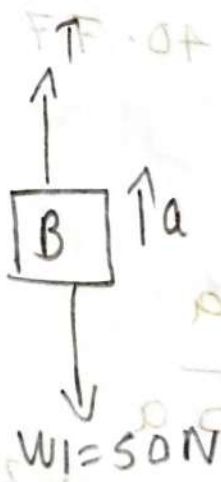
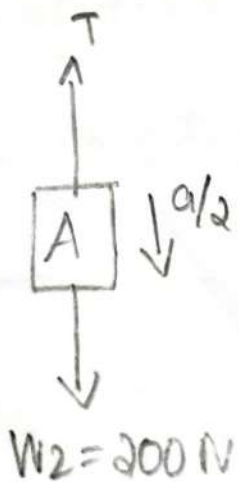
$$\theta_z = \cos^{-1} \left[\frac{R_z}{R} \right] = \cos^{-1} \left[\frac{34.8}{51.68} \right]$$

$$\theta_z = 47.67^\circ$$

3/2

* A system of frictionless pulleys carries two weights ~~at~~ hung by ~~ext~~ ~~inext~~ inextensible cords as shown in fig. Make calculations for the tension in the cords and acceleration of the weights. Proceed to work out the displacement and velocity of weight W_1 after 4 seconds from start. Presume that the system is released from rest.

→ W_1 moves upward
 W_2 moves downward



$$T - WB = m_B a_B$$
$$T - 50 = \frac{50}{9.81} \times a \text{ [upward motion of block B]}$$

$$T = 50 + \frac{50}{9.81} a \rightarrow \textcircled{1}$$

$$200 - T = \frac{200}{9.81} \times \frac{a}{2} \text{ [downward motion A]}$$

$$2T = 200 - \frac{100}{9.81} a$$

$$T = 100 - \frac{50}{9.81} a \rightarrow \textcircled{2}$$

From eq. ① and ②

$$50 + \frac{50}{9.81} a = 100 - \frac{50}{9.81} a$$

$$\frac{100}{9.81} a = 50$$

$$a = \frac{50 \times 9.81}{100}$$

$$a = \underline{\underline{4.905 \text{ m/s}^2}}$$

$$\text{acceleration of A} = \frac{4.905}{2} = \underline{\underline{2.4525 \text{ m/s}^2}}$$

$$\text{acceleration of B} = \underline{\underline{4.905 \text{ m/s}^2}}$$

$$T = 50 + \frac{50}{9.81} \times 4.905$$

$$\underline{\underline{T = 75 \text{ N}}}$$

$$v = u + at$$

$$v = 0 + (4.905 \times 4)$$

$$v = \underline{\underline{19.62 \text{ m/s}}}$$

$$s = ut + \frac{1}{2}at^2$$

$$s = 0 \times 4 + \frac{1}{2} \times 4.905 \times 4^2$$

$$s = \underline{\underline{39.24 \text{ m}}}$$

* The equation of motion of a particle moving in a straight line is given by $s = 18t + 3t^2 - 2t^3$, where (s) is in metres and (t) is in seconds. Find,

- i) velocity and acceleration ~~reaches~~ at start
- ii) time, when the particle reaches its maximum velocity
- iii) maximum velocity of the particle.

$$\rightarrow s = 18t + 3t^2 - 2t^3$$

i) Differentiating w.r.t t .

$$\frac{ds}{dt} = 18 + 6t - 6t^2$$

substitute $t=0$, $v = 18 + 6t - 6t^2$

$$v = 18 + 6 \times 0 - 6 \times 0$$

$$v = 18 \text{ m/s}$$

Again differentiate w.r.t t .

$$\frac{d^2s}{dt^2} = 6 - 12t, \text{ substitute } t=0$$

$$a = 6 - 12 \times 0$$

$$a = 6 \text{ m/s}^2$$

ii) Differentiate velocity equation,

$$v = 18 + 6t - 6t^2$$

$$\frac{dv}{dt} = 6 - 12t$$

$$\text{consider } 6 - 12t = 0$$

$$t = \frac{1}{2}$$

$$\underline{t = 0.5 \text{ seconds}}$$

iii) substitute $t = 0.5$ in ~~$\frac{dv}{dt}$~~ ds/dt

$$\frac{ds}{dt} = 18 + 6t - 6t^2$$

$$v = 18 + (6 \times 0.5) - 6 \times (0.5)^2$$

$$\underline{v = 19.5 \text{ m/s}}$$

* A train, starting from rest, is uniformly accelerated. The acceleration at any instant is $\frac{10}{v+1} \text{ m/s}^2$, where (v) is the velocity of the train in m/s at the instant. Find the distance, in which the train will attain a velocity of 35 km/h .

$$\rightarrow a = \frac{10}{v+1}$$

$$\text{Rearranging, } v \cdot \frac{dv}{ds} = \frac{10}{v+1}$$

$$a = v \cdot \frac{dv}{ds}$$

$$v(v+1)dv = 10 ds \rightarrow \textcircled{1}$$

$$[v^2 + v]dv = 10 ds$$

Integrating both sides,

$$\frac{v^3}{3} + \frac{v^2}{2} = 10s + C_1 \rightarrow \textcircled{2}$$

C_1 - first constant of integration.

substituting the values of $s=0$ and $v=0$ in eq. $\textcircled{2}$.

substitute $C_1=0$ in eq. $\textcircled{2}$

$$\frac{v^3}{3} + \frac{v^2}{2} = 10s$$

$$2v^3 + 3v^2 = 60s \rightarrow \textcircled{3}$$

$$1 \text{ hr} = 60 \text{ min}$$

$$1 \text{ min} = 60 \text{ sec}$$

$$v = \frac{36 \times 1000}{60 \times 60}$$

$$v = 10 \text{ m/s}$$

Now, distance travelled by the train, substituting

$$v = 36 \text{ km-p.h or } 10 \text{ m/s in eq. } \textcircled{3}$$

$$2 \times (10)^3 + 3(10)^2 = 60s$$

$$2000 + 300 = 60s$$

$$s = \frac{2300}{60}$$

$$\underline{\underline{s = 38.3 \text{ m}}}$$

IMP

* A body moving with SHM as velocity is of 10 m/s and 4 m/s at 2 and 4 m distance from the mean position. Find the amplitude and time period of the body.

$$\Rightarrow V_1 = 10 \text{ m/s} \quad x_1 = 2 \text{ m}$$

$$r = ?$$

$$V_2 = 4 \text{ m/s} \quad x_2 = 4 \text{ m}$$

$$T = ?$$

$$V_1 = \omega \sqrt{r^2 - x_1^2} \rightarrow \textcircled{1} \quad V_2 = \omega \sqrt{r^2 - x_2^2} \rightarrow \textcircled{2}$$

Divide $\textcircled{1} \div \textcircled{2}$

$$\frac{V_1}{V_2} = \frac{\omega \sqrt{r^2 - x_1^2}}{\omega \sqrt{r^2 - x_2^2}} = \frac{10}{4} = \frac{\sqrt{r^2 - x_1^2}}{\sqrt{r^2 - x_2^2}}$$

$$\frac{100}{16} = \frac{r^2 - x_1^2}{r^2 - x_2^2}$$

$$\frac{100}{16} = \frac{r^2 - 2^2}{r^2 - 4^2}$$

$$\frac{100}{16} = \frac{r^2 - 4}{r^2 - 16}$$

$$(r^2 - 16) 100 = (r^2 - 4) 16$$

$$100r^2 - 1600 = 16r^2 - 64$$

$$100r^2 - 16r^2 = -64 + 1600$$

$$r^2 [100 - 16] = 1536$$

$$r^2 = \frac{1536}{84}$$

$$r = 4.27 \text{ m}$$

$$v_i = \omega \sqrt{r^2 - x^2} = \omega \sqrt{4.27^2 - 2^2}$$

$$10 = \omega \times 3.77$$

$$\omega = \frac{10}{3.77}$$

$$\omega = 2.65 \text{ rad/s}$$

$$t_p = \frac{2\pi}{\omega} = \frac{2 \times 3.14}{2.65}$$

$$t_p = \underline{\underline{2.37 \text{ s}}}$$

* A body is vibrating with SHM of amplitude 150 mm & frequency 3 cps. Calculate the max. velocity & acceleration of the body.

$$\omega = 3 \text{ cps (multiply } \times 2\pi = \omega)$$

$$\rightarrow r = 150 \text{ mm}$$

$$r = 0.15 \text{ m}$$

$$\omega = 2\pi \nu = 2 \times 3.14 \times 3$$

$$\omega = \underline{\underline{18.84 \text{ rad/s}}}$$

$$V_{\text{max}} = r\omega = 0.15 \times 18.84$$

$$V_{\text{max}} = \underline{\underline{2.83 \text{ m/s}}}$$

$$a_{\text{max}} = -r\omega^2$$


$$a_{\text{max}} = -0.15 \times 18.84^2$$

$$a_{\text{max}} = \underline{\underline{-53.74 \text{ m/s}^2}}$$

VIMAL JYOTHI ENGINEERING COLLEGE, CHEMPERI

DEPARTMENT OF ELECTRICAL & ELECTRONICS ENGINEERING

TUTORIAL LOG REGISTER 2021-2025 ADMISSIONS (S2)

Sl. No	Date	Time	Name of	Batch	Topic	Signature of	Absentees	Proof Material Folder
1	29/4/22	12.10 pm	Ankita Sebastian	Full class	Flowchart & algorithm of linear search and bubble sort		nil	https://drive.google.com/drive/folders/1K5uHFr36g6kf9yASHg2wmXxmyEM6wEul?usp=sharing
2	6-5-22	12.10 pm	Ankita Sebastian	Full class	Program to write simple programs		nil	
3	27/5/22	12.10 pm	Ankita Sebastian	Full class	sort		nil	

evaluate $\int_C \frac{\cos \pi z}{z-2} dz$ where C is $|z|=3$

$$z-2=0$$

$$z=2$$

(the integrand $\frac{\cos \pi z}{z-2}$ is analytic at all points except at $z=2$.)

at $z=2$ $|z|=|2|$, $\sqrt{2^2} = 2 < 3$

$\therefore z=2$ lies inside C .

By Cauchy integral formula $\int_C \frac{f(z)}{z-a} dz = 2\pi i f(a)$

$$\int_C \frac{\cos \pi z}{z-2} dz = 2\pi i f(2)$$

$$= 2\pi i \cos 2\pi$$

$$= 2\pi i (1)$$

$$= \underline{\underline{2\pi i}}$$

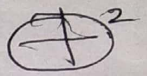
$|z|=3$ circle with
center $(0,0)$, $r=3$

$$|z|=3$$

$$\sqrt{x^2+y^2}=3$$

$$x^2+y^2=9$$

$$\sqrt{x^2+y^2}=3$$



Q) Evaluate $\int_C \frac{e^z}{z+1} dz$, C is $|z+1| = \frac{1}{2}$

$$z+1=0$$

$$z=-1$$

~~is~~ inside

$$z=-1$$

$z=-1$ is inside the circle $|z+1| = \frac{1}{2}$

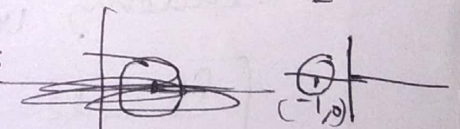
By Cauchy integral th

$$\therefore \int_C \frac{e^z}{z+1} dz = \int_C 2\pi i f(-1)$$

$$= 2\pi i e^{-1}$$

$$= \underline{\underline{2\pi i e^{-1}}}$$

$|z+1| = \frac{1}{2}$ circle with
center $(-1,0)$ & radius $\frac{1}{2}$



at $z=-1$

$$|z+1| = |-1+1| = 0 < \frac{1}{2}$$

$$\int_C \frac{f(z)}{z-a} dz = 2\pi i f(a)$$

a) Evaluate $\int_C \frac{e^z}{z} dz$ where C is $|z|=1$.

$$z=0$$

$$\text{at } z=0 \quad |z|=|0|=0 < 1$$

$\therefore z=0$ lies inside C

By C-I Theorem

$$\int_C \frac{f(z)}{z-a} dz = 2\pi i f(a)$$

$$|a+ib| = \sqrt{a^2+b^2}$$

$$\int_C \frac{e^z}{z} dz = 2\pi i f(0) = 2\pi i e^0 = 2\pi i \quad \begin{aligned} &|+2| = |2+i| \\ &= \sqrt{2^2+1^2} \\ &= \sqrt{5} < 1 \end{aligned}$$

a) Evaluate $\int_C \frac{e^{-2z}}{z+i} dz$ where $|z+2| = 10$

$$z+i=0$$

$$z=-i$$

$$\text{at } z=i$$

$$|z+2| = |-i+2| = |2-i| = \sqrt{4+1} = \sqrt{5} < 10$$

$\therefore z=i$ lies inside C

By C-I-f

$$\int_C \frac{f(z)}{z-a} dz = 2\pi i f(a)$$

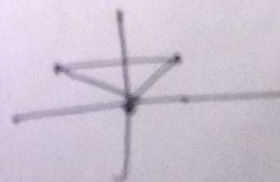
$$\int_C \frac{e^{-2z}}{z+i} dz = 2\pi i f(-i) = \underline{\underline{2\pi i e^{+2i}}}$$

b) Evaluate $\int_C \frac{\tan z}{z-i} dz$ where C is a triangle with

vertices $0, 1+i, 1+2i$

$$z-i=0$$

$z=i$ lies inside C . $(1+2i)$
 $(-1+2i)$



$$\int_C \frac{\tan z}{z-i} dz = 2\pi i f(i) = \underline{\underline{2\pi i \tan i}}$$

$$Q) \text{ Evaluate } \int_C \frac{\sin \pi z}{z-1} dz \text{ where } C \text{ is } |z| = \frac{1}{2}$$

$$\text{at } z=1 \quad z-1=0 \quad z=1$$

$$|z| = |1| = 1 > \frac{1}{2}$$

$z=1$ lies outside C

\therefore By Cauchy integral form

$$\int_C \frac{\sin \pi z}{z-1} dz = 0$$

$$Q) \text{ Evaluate } \int_C \frac{\cot z}{z+i} dz \text{ where } C \text{ is } |z+2|=1$$

$$z+i=0$$

$$z = -i$$

$$\text{at } z = -i$$

$$|z+2| = |-i+2| = |2-i| = \sqrt{4+1} = \sqrt{5} > 1$$

$z = -i$ ^{lies} is outside the circle $|z+2|=1$

\therefore By C.I.T

$$\int_C \frac{\cot z}{z+i} dz = 0$$

$$\int_C \frac{\sin \pi z^2}{(z-1)^3} dz = \frac{2\pi i}{2!} f''(1)$$

$$= \pi i \times -2\pi$$

$$= \underline{\underline{-2\pi^2 i}}$$

$$f(z) = \sin \pi z^2$$

$$f'(z) = \cos \pi z^2 \times 2z\pi$$

$$f''(z) = \frac{d}{dz} [\cos \pi z^2]$$

$$2\pi [-\sin \pi z^2 \times 2\pi z + \cos \pi z^2]$$

$$f''(1) = 2\pi (-\sin \pi \times 2\pi + \cos \pi)$$

$$2\pi(0 - 1) = \underline{\underline{-2\pi}}$$

Q) Evaluate $\int_C \frac{e^z}{z^3} dz$ where C is $|z|=1$.

$$z^3 = 0 \Rightarrow z = 0$$

$$|z| = |0| = 0 < 1$$

$z=0$ inside C

By C.I.F.

$$\int_C \frac{f(z)}{(z-a)^n} dz = \frac{1}{(n-1)!} f^{(n-1)}(a)$$

$$\int_C \frac{e^z}{z^3} dz = \frac{1}{2!} 2\pi i f''(0)$$

$$= \pi i f''(0)$$

$$= \underline{\underline{\pi i}}$$

$$f(z) = e^z$$

$$f'(z) = e^z$$

$$f''(z) = e^z$$

$$f''(0) = e^0 = 1$$

Q) Evaluate $\int_C \frac{\cos^2 \pi z}{(z-2)^3} dz$ where C is $|z|=1$

$$(z-2)^3 = 0 \Rightarrow z = 2$$

at $z=2$ $|z|=|2|=2 > 1$

$\therefore z=2$ lies outside C . By C.I.F

$$\int_C \frac{\cos^2 \pi z}{(z-2)^3} dz = \underline{\underline{0}}$$

Q) Evaluate $\int_C \frac{e^{2z}}{(z-2)^2} dz$ where C is $|z|=3$.

$$(z-2)^2 = 0 \Rightarrow z-2=0$$

$$\Rightarrow z=2$$

$$|z|=|2|=2 < 3$$

$z=2$ inside 'C'

$$\int_C \frac{e^{2z}}{(z-2)^2} dz =$$

$$\int_C \frac{f(z)}{(z-a)^n} dz = \frac{2\pi i}{(n-1)!} \frac{d^{n-1}}{dz^{n-1}} (f(a))$$

By C.T.F

$$\int_C \frac{f(z)}{(z-a)^n} dz = \frac{2\pi i}{(n-1)!} f^{(n-1)}(a) \quad \text{if 'a' inside}$$

$$\int_C \frac{e^{2z}}{(z-2)^2} dz = \frac{2\pi i}{1!} f'(2)$$

$$= 2\pi i \cdot 2e^4$$

$$= \underline{\underline{4\pi i e^4}}$$

$$f(z) = e^{2z}$$

$$f'(z) = 2e^{2z}$$

Q) Evaluate $\int_C \frac{\sin \pi z^2}{(z-1)^3} dz$ where C is $|z|=2$

$$(z-1)^3 = 0 \Rightarrow (z-1)=0 \Rightarrow z=1$$

$$\text{at } z=1 \Rightarrow |z|=|1|=1 < 2$$

$\therefore z=1$ lies inside C .

$$\text{By C.T.F} \quad \int_C \frac{f(z)}{(z-a)^n} dz = \frac{2\pi i}{(n-1)!} \frac{d^{n-1}}{dz^{n-1}} (f(a)) \quad \text{if 'a' inside}$$



S5 AEI

Vimal Jyothi Engineering College, Chemperi, Kannur Dist., Kerala

20

	1 8:30 - 9:30 AM	2 9:30 - 10:30 AM	3 10:45 - 11:45 AM	4 11:45 AM - 12:45 PM	LB 12:45 - 1:30 PM	5 1:30 - 2:30 PM	6 2:30 - 3:30 PM
<i>Monday</i>	AET301 CONTROL SYSTEMS <i>Mrs Jinsa Mathew</i>	AET305 COMPUTER ARCHITECTURE AND EMBEDDED SYSTEMS Tutorial ✓ <i>Mr Shinu MM</i>	AET303 INDUSTRIAL INSTRUMENTATION <i>Mrs Reshma KV</i>	AE331 AIC and Instrumentation lab <i>Mrs Reshma KV / Mrs Jinsa Mathew</i>		AE331 AIC and Instrumentation lab <i>Mrs Reshma KV / Mrs Jinsa Mathew</i>	
<i>Tuesday</i>	AET303 INDUSTRIAL INSTRUMENTATION <i>Mrs Reshma KV</i>	AET305 COMPUTER ARCHITECTURE AND EMBEDDED SYSTEMS <i>Mr Shinu MM</i>	AET301 CONTROL SYSTEMS <i>Mrs Jinsa Mathew</i>	AEL333 EMBEDDED SYSTEMS LAB <i>Mr Shinu MM / Mrs Shamy A</i>		AEL333 EMBEDDED SYSTEMS LAB <i>Mr Shinu MM / Mrs Shamy A</i>	
<i>Wednesday</i>	AET305 COMPUTER ARCHITECTURE AND EMBEDDED SYSTEMS <i>Mr Shinu MM</i>	HUT310 MANAGEMENT FOR ENGINEERS <i>Ms Laly James</i>	AET301 CONTROL SYSTEMS <i>Mrs Jinsa Mathew</i>	AET307 ANALOG INTEGRATED CIRCUITS <i>Mrs Shamy A</i>		AET303 INDUSTRIAL INSTRUMENTATION <i>Mrs Reshma KV</i>	AET307 ANALOG INTEGRATED CIRCUITS <i>Mrs Shamy A</i>
<i>Thursday</i>	AET307 ANALOG INTEGRATED CIRCUITS <i>Mrs Shamy A</i>	AET303 INDUSTRIAL INSTRUMENTATION Tutorial ✓ <i>Mrs Reshma KV</i>	AET305 COMPUTER ARCHITECTURE AND EMBEDDED SYSTEMS <i>Mr Shinu MM</i>	HUT310 MANAGEMENT FOR ENGINEERS <i>Ms Laly James</i>		MCN301 DISASTER MANAGEMENT <i>Dr Justin sunil Dhas</i>	Minor/Honor <i>Mrs Jinsa Mathew</i>
<i>Friday</i>	AET307 ANALOG INTEGRATED CIRCUITS Tutorial ✓ <i>Mrs Shamy A</i>	HUT310 MANAGEMENT FOR ENGINEERS <i>Ms Laly James</i>	AET301 CONTROL SYSTEMS Tutorial ✓ <i>Mrs Jinsa Mathew</i>	MCN301 DISASTER MANAGEMENT <i>Dr Justin sunil Dhas</i>		Minor/Honor	Minor/Honor

VIMAL JYOTHI ENGINEERING COLLEGE CHEMPERI
DEPARTMENT OF ELECTRONICS & INSTRUMENTATION
TUTORIAL CLASS DETAILS- S5 AEI

SUBJECT: AET301: Control system
 Name of Faculty: Ms. Jina Mathew

Sl.No:	Date	Day	Topics	Details of class work	Link of Recorded Video/Class work	Students Attendance
1	11/26/2021	Friday	Mechanical Translational system modeling	Mechanical Translational system modeling- determine the transfer function	https://drive.google.com/file/d/1BN8zP-x0zeflAha_4su5Bisr194Zsk/view?usp=sharing	No. of students present: 18
2	12/3/2021	Friday	Block diagram reduction	Finding Transfer function by block diagram reduction	https://drive.google.com/file/d/1BN8zP-x0zeflAha_4su5Bisr194Zsk/view?usp=sharing	No. of students present: 19
3	12/6/2021	Friday	Signal Flow Graph	Determination of transfer function by masons formula	https://drive.google.com/file/d/18MBmVT9XA5WUMH-dIB3eE3iO7hZicudo/view?usp=sharing	No. of students present: 19
4	12/17/2021	Friday	Time domain specifications & Static & Dynamic Errors	Determination of time domain specification of given system, determination of static & dynamic errors of the system for a given input	https://drive.google.com/file/d/18MBmVT9XA5WUMH-dIB3eE3iO7hZicudo/view?usp=sharing	No. of students present: 19
5	01/07/2022	Friday	Root locus	Stability analysis of the system by using RH method	https://drive.google.com/file/d/1Ba1e5Kool3Xf8dCTGAgAlu3dwdl5afRy/view?usp=sharing	No. of students present: 17
6	01/14/2022	Friday	Root Locus	Plot the root locus of the given system	https://drive.google.com/file/d/1Ba1e5Kool3Xf8dCTGAgAlu3dwdl5afRy/view?usp=sharing	No. of students present: 19
7	01/21/2022	Friday	Bode Plot	Bode plots with frequency analysis and determine gain margin & phase margin	https://drive.google.com/file/d/1Ba1e5Kool3Xf8dCTGAgAlu3dwdl5afRy/view?usp=sharing	No. of students present: 17
8	02/04/2022	Friday	State model	State space representation of electrical system	https://drive.google.com/file/d/1Ba1e5Kool3Xf8dCTGAgAlu3dwdl5afRy/view?usp=sharing	No. of students present: 18
9	03/02/2022	Tuesday	State space represent	State space representation of a system, from differential equation, from transfer function etc.	https://drive.google.com/file/d/1Ba1e5Kool3Xf8dCTGAgAlu3dwdl5afRy/view?usp=sharing	No. of students present: 18

Staff: *Jina Mathew*

VIMAL JYOTHI ENGINEERING COLLEGE CHEMPERI
DEPARTMENT OF ELECTRONICS & INSTRUMENTATION
TUTORIAL CLASS DETAILS- S5 AEI

SUBJECT: AET303 Industrial Instrumentation

Name of Faculty: Ms.RESHMA K V

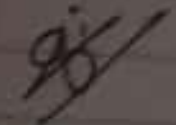
Sl.No:	Date	Day	Topics	Details of class work	Link of Recorded Video/Class work	Students Attendance
1	25/11/21	Thursday	Linearization techniques of thermistor	Discussion	https://drive.google.com/drive/folders/12UVdIFl5pjMHObGBanjim0tl-iQggHad?usp=sharing	No: of students present: 16
2	09/12/21	Thursday	Differential pressure transducer, flapper nozzle principle	Discussion	https://drive.google.com/drive/folders/1W2b-pCdszJHpC_6l9gdOksqPQF4l6g8j?usp=sharing	No: of students present: 20
3	06/01/22	Thursday	Angular Momentum type, Impeller Turbine Flow meter, twin turbine flow meter	Discussion	https://drive.google.com/drive/folders/1lmhfedTTZ7UIPYDhw-AgXh-FbXE0JXDc?usp=sharing	No: of students present: 19
4	27/1/22	Thursday	Level measurement-revision	Question paper discussion	https://drive.google.com/file/d/1tZntuDfMecVDbTikbkILzyjhdujF7A0e/view?usp=sharing	No: of students present: 20
5	03/02/22	Thursday	flow and Level measurement-revision	Question paper discussion	https://drive.google.com/file/d/1g6ntukqMR6JGMWPaGw5BcJJcUJUGWARB/view?usp=sharing	No: of students present: 20

VIMAL JYOTHI ENGINEERING COLLEGE CHEMPERI
DEPARTMENT OF ELECTRONICS & INSTRUMENTATION
TUTORIAL CLASS DETAILS- S5 AEI

SUBJECT: AET305:CAAES

Name of Faculty: Mr. Shinu M M

Sl.No:	Date	Day	Topics	Details of class work	Link of Recorded Video/Class work	Students Attendance
1	22/11/2021	MONDAY	Pin configuration	REVISION	https://drive.google.com/file/d/1XoWSgMDY1sQYr6_6e6JTVbF6JDkNDsjm/view?usp=sharing	18
2	29/11/2021	MONDAY	Addressing Modes	REVISION	https://drive.google.com/file/d/1XeGDnx3KO2rKnA34RFxScU_PqWsDnpdt/view?usp=sharing	17
3	07/12/2021	MONDAY	Interfacing of DAC	REVISION	https://drive.google.com/file/d/1h8MySqi6_sprE4JIVCcZh2YxVSj_Vgyq/view?usp=sharing	17
4	13/12/2021	MONDAY	PROGRAMMING	TEST	https://drive.google.com/file/d/14r1rEJWreZAEfeGmn8Mu1uqR7_e30Yvl/view?usp=sharing	17
5	03/01/2022	MONDAY	Functional units of a computer	REVISION	https://drive.google.com/file/d/1bVPPY_FTlYeB3hP2fyc2c7VSj6ZSleW_/view?usp=sharing	18
6	31/01/2022	MONDAY	Use of Pointers	REVISION	https://drive.google.com/file/d/1qyNaMKlafEhVRQijUtgDm4BTzr2fhnfb/view?usp=sharing	18



Staff:

DEPARTMENT OF ELECTRONICS & INSTRUMENTATION
TUTORIAL CLASS DETAILS- S5 AEI

SUBJECT: AET307: AIC

Name of Faculty: Ms. Shamy A

Sl.No:	Date	Day	Tipics	Details of class work	Link of Recorded Video/Class work	Students Attendance
1	3/12/2021	FRIDAY	ANALYSIS OF PRACTICAL OP AMP AMPLIFIER	test	https://drive.google.com/file/d/1rTHKO3CH3dsfY5-mGwc8r-aQkbo6caa_/view?usp=sharing	12
2	10/12/2021	FRIDAY	ANALYSIS OF DIDFFERENTIAL AMPLIFIR	test	https://drive.google.com/file/d/1TosLLufli7Pn0wBCDF5fGq5yo3JIFyBi/view?usp=sharing	14
3	7/1/2022	FRIDAY	DESIGN OF OPAMP AMPLIFIER	test	https://drive.google.com/file/d/113AWEbknPAPE2opMdGnK6if4QAfo4NnV/view?usp=sharing	12
4	14/1/2022	FRIDAY	555 TIMER ANALYSIS AND DESIGN	test	https://drive.google.com/file/d/14pUm-pPNKydn_cvXvUO0gQ6ia6VB3CMo/view?usp=sharing	18
5	21/1/2022	FRIDAY	ANALYSIS OF FILTER	test	https://drive.google.com/file/d/1zQiwvS_r4zjmSJ9GQI6XqePFqwEm6Tau/view?usp=sharing	17

Staff: 



AY 2021-22 S6 AEI

Vimal Jyothi Engineering College, Chempiperi, Kannur Dist., Kerala

	1	2	3	4	5	6
Mo	AET306 Power Electronics TUT Ms. Jyothi Joseph	AET304 Process Dynamics and Control Dr. G. Gnan Devadhas	HUT300 INDUSTRIAL ECONOMICS & FOREIGN TRADE Dr. Justin samil Dhas	AEL332 Power Electronics Lab		Mr. Prabir Jaiswal / H
	AET306 Power Electronics Ms. Jyothi Joseph	AET302 DIGITAL SIGNAL PROCESSING Dr. Jayesh George	AET302 DIGITAL SIGNAL PROCESSING Dr. Jayesh George	AET342 Biomedical Instrumentation Ms. Jina Mathew	AET306 Power Electronics Ms. Jyothi Joseph	AET308 Comprehensive Course Work Ms. Jina Mathew
Tu	AET342 Biomedical Instrumentation Ms. Jina Mathew	AET304 Process Dynamics and Control Dr. Jayesh George	HUT300 INDUSTRIAL ECONOMICS & FOREIGN TRADE Dr. Justin samil Dhas	AED334 Miniproject		
We	HUT300 INDUSTRIAL ECONOMICS & FOREIGN TRADE Dr. Justin samil Dhas	AET302 DIGITAL SIGNAL PROCESSING Dr. Jayesh George	AET302 DIGITAL SIGNAL PROCESSING Dr. Jayesh George	AET304 Process Dynamics and Control Dr. G. Gnan Devadhas	AET306 Power Electronics Ms. Jyothi Joseph	AET442 Biomedical Instrumentation Ms. Jina Mathew
Th	AET342 Biomedical Instrumentation Ms. Jina Mathew	AET306 Power Electronics Ms. Jyothi Joseph	AET304 Process Dynamics and Control TUT Dr. G. Gnan Devadhas	AET302 DIGITAL SIGNAL PROCESSING TUT Dr. Jayesh George	AET304 Process Dynamics and Control Dr. G. Gnan Devadhas	HUT300 INDUSTRIAL ECONOMICS & FOREIGN TRADE Dr. Justin samil Dhas
Fr	AET342 Biomedical Instrumentation Ms. Jina Mathew	AET304 Process Dynamics and Control TUT Dr. G. Gnan Devadhas	AET304 Process Dynamics and Control TUT Dr. G. Gnan Devadhas	AET302 DIGITAL SIGNAL PROCESSING TUT Dr. Jayesh George	AET304 Process Dynamics and Control Dr. G. Gnan Devadhas	HUT300 INDUSTRIAL ECONOMICS & FOREIGN TRADE Dr. Justin samil Dhas
Sa	Special Timetable					

VIMAL JYOTHI ENGINEERING COLLEGE CHEMPERI
DEPARTMENT OF ELECTRONICS & INSTRUMENTATION
TUTORIAL CLASS DETAILS- S6 AEI

SUBJECT:		AET302	Digital Signal Processing			
Name of Faculty:		Dr Jayesh George				
SLNo:	Date	Day	Topics	Details of class work	work/proof	Students Attendance
1	29/04/2022	Fri	DFT	Problems on DFT	Class note	20
2	6/5/2022	Fri	DFT	Properties of DFT Problems	Class note	20
3	20/05/2022	Fri	FIR filter	windows	Class note	17
4	24/06/2022	Fri	IIR Filter	Design of IIR filter	Class note	20
5	1/7/2022	Fri	Realization	form II	Class note	18

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VIMAL JYOTHI ENGINEERING COLLEGE CHEMPERI
DEPARTMENT OF ELECTRONICS & INSTRUMENTATION
TUTORIAL CLASS DETAILS- S6 AEI

SUBJECT:		AET304	IProcess Dynamics and Control			
Name of Faculty:		Dr. G Glan Devadhas				
Sl.No:	Date	Day	Tipics	Details of class work	Link of Recorded Video/Class work/proof	Students Attendance
1	29/04/2022	Fri	Mathematical Modeling	model of level	Class note	20
2	6/5/2022	Fri	Process Characteristics	constant and	Class note	20
3	01/06/2022	Fri	Controller design	P,P+I,P+I+D	Class note	17

VIMAL JYOTHI ENGINEERING COLLEGE CHEMPERI
DEPARTMENT OF ELECTRONICS & INSTRUMENTATION
TUTORIAL CLASS DETAILS- S6 AEI

SUBJECT:	AET342	Biomedical Instrumentation				
Name of Faculty:	Ms. Jinsa Mathew					
Sl.No	Date	Day	Tipics	Details of class work	Link of Recorded Video/Class work/proof	Students Attendance
	29/04/2022	Friday	Cardio vacular system	Cardio vascular	what-is-the-cardiovascular-system-	20 students present
	5/4/2022	Thursday	Human Respiratory system	Human Respiratory	ct=j&q=&esrc=s&source=video&cd=	20 students present
	13/05/2022	Friday	Electrical system of Heart	functioning of	rct=j&q=&esrc=s&source=video&c	18 students
					https://youtu.be/TnFoJ7Hhi-M	
	20/05/2022	friday	ECG	functioning of ECG	https://youtu.be/FThXJUFWUrw	19 students
	27/05/2022	friday	EMG	machine	https://youtu.be/XMizSSOejg0	18 students
		Staff:				

VIMAL JYOTHI ENGINEERING COLLEGE CHEMPERI
DEPARTMENT OF ELECTRONICS & INSTRUMENTATION
TUTORIAL CLASS DETAILS- S6 AEI

SUBJECT:		AET306:Power Electronics				
Name of Faculty		Ms. Jyothi Joseph				
Sl.No:	Date	Day	Topic	Details of class work	Link of Recorded Video/Class work/proof	Students Attendance
1	29/04/2022	Friday	dynamic characteristics	class note	https://drive.google.com/file/d/11C0RPZ5GPRpKi5sLGYnyYo8I31b5Aron/view?usp=sharing	17 nos present
2	16/05/2022	Monday	Snubber circuits	class note		13 nos present
3	31/05/2022	Tuesday	Single phase Controlled rectifiers	class note		18 nos present

TUTORIAL CLASS ATTENDANCE SHEET

DATE & TIME 25/11/21		SUBJECT AET303 INDUSTRIAL INSTRUMENTATION	FACULTY Reshma k v
LIST OF STUDENTS			
SL NO.	PRN	NAME	Present/Absent
1	VML19AE001	Adwaith Pradeep	A
2	VML19AE003	Aljo John	P
3	VML19AE004	Anamika C	P
4	VML19AE005	Anjo Mathew	P
5	VML19AE006	Anusree K	P
6	VML19AE007	Aswin J Prasad	P
7	VML19AE008	Aswin Thomas	P
8	VML19AE009	Devaprakash	P
9	VML19AE010	Jibin P B	P
10	VML19AE012	Joyel Joseph	P
11	VML19AE013	Justin George	P
12	VML19AE014	Kashyap K	A
13	VML19AE015	Mahesh P G	A
14	VML19AE016	Mohammed Raheel	A
15	VML19AE017	Nashla K P	P
16	VML19AE018	Paulson Edwin Kunnath Parambil	A
17	VML19AE019	Prabin Baby	P
18	VML19AE020	Salvin Jose K	P
19	VML19AE021	Sreehari T V	P
20	VML19AE022	Veda K C	P
21	LVML19AE023	Dileep C	P

PORTION COVERAGE

Topics covered	Linearization techniques of thermistor https://drive.google.com/file/d/1MN7KV-U5hV9V7MrJIS2o6ooQsIQUJINW/view?usp=sharing
Total students present	16
List of absentees	Adwaith Pradeep, Mahesh P G, Mohammed Raheel Kashyap K, Paulson Edwin Kunnath Parambil
Signature of faculty	RESHMA K V

Disadvantages of Wires RTD

- Low sensitivity
- Higher cost than thermocouple
- No point sensing
- Affected by Shock and Vibration
- Requires 3 or 4 wire operations

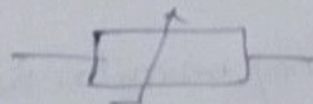
Application

- Air Conditioning and Refrigeration servicing
- Food processing
- Stoves and grills
- Textile production
- Plastic processing
- Petrochemical processing
- Micro electronics
- Air, gas and liquid temp measure

Thermistor (Application: thermistor, thermistor compensation)

Thermistors or thermal resistors are semiconductor type resistance thermometer. They have very high sensitivity, but highly non-linear characteristics.

- The resistance of the thermistor decrease with the increase in temp. This is the main principle behind thermistor.
- The high sensitivity



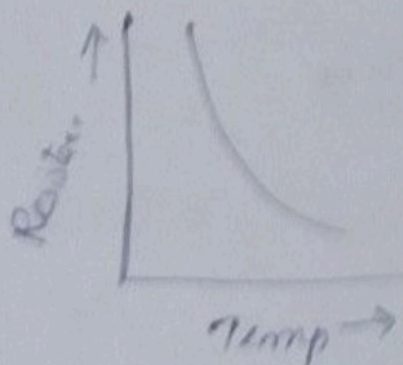
$$R_T = R_0 e^{\beta \left(\frac{1}{T} - \frac{1}{T_0} \right)}$$

R_T - Resistance at temp T (K)
 R_0 - Resistance at Temp T_0 (K)
 T_0 - Refer temp normally 25°C

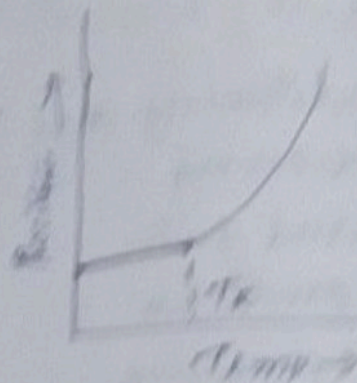
β is constant. Its value is decided by the chara of the material, the nominal value is taken 4000

- Thermistors are composed of a standard mixture of metal oxides, such as manganese, nickel, cobalt, copper, and uranium. Their resistance range from 10^3 to $10^6 \Omega$ and they are available in wide variety of shapes

Range - 100° to $300^\circ C$



NTC Chart



PTC Chart

Voltage/Current
Conversion to appropriate units

PTC

- PTC thermistors increase their resistance as the temp rises. The relationship b/w resistance and temp is linear

PTC Uses

- PTC thermistors used in fuses for circuit protection
- Timing device in televisions

NTC

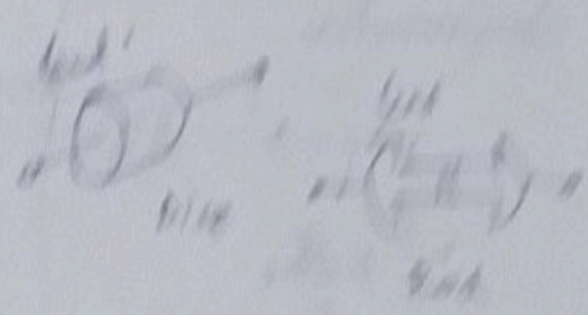
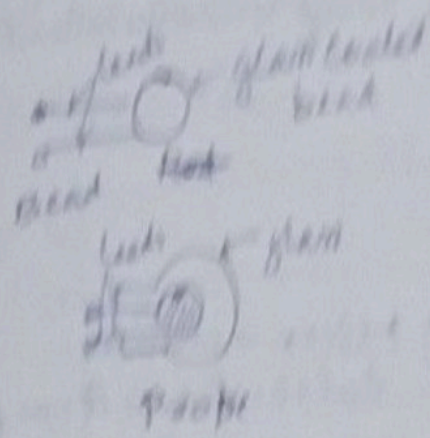
Uses

1. Current limiters and temp monitors in digital thermals and automobiles

Types

The resistors are available in different forms

1. bead type a) 4 lead type b) disc c) probe



The small size of the sensing element makes it suitable for measurement of temperature at a point

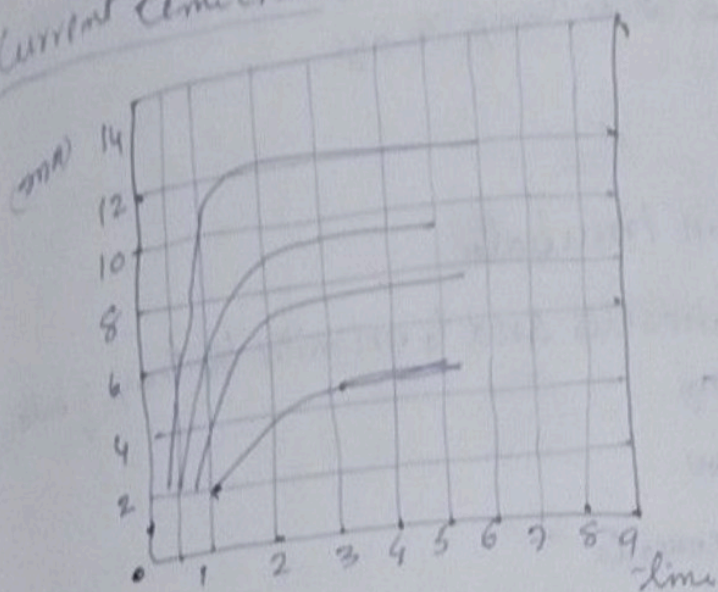
Construction of thermistor

- Basically in thermistor, 2 or more semiconductor powder are mixed with a binder to form a slurry
- After getting the slurry from the previous process, laminations of that slurry is formed over the lead wires
- For drying process purpose, it has to put into a SiC furnace. During this process that slurry (metallic oxides) will shrink
- processed metallic oxides is sealed by glass or epoxy resin

- Bead — 0.15mm to 1.25mm
- Probe — 2.5mm (about)
- Disc — (2.5mm to 25mm)
- cloud of washer —

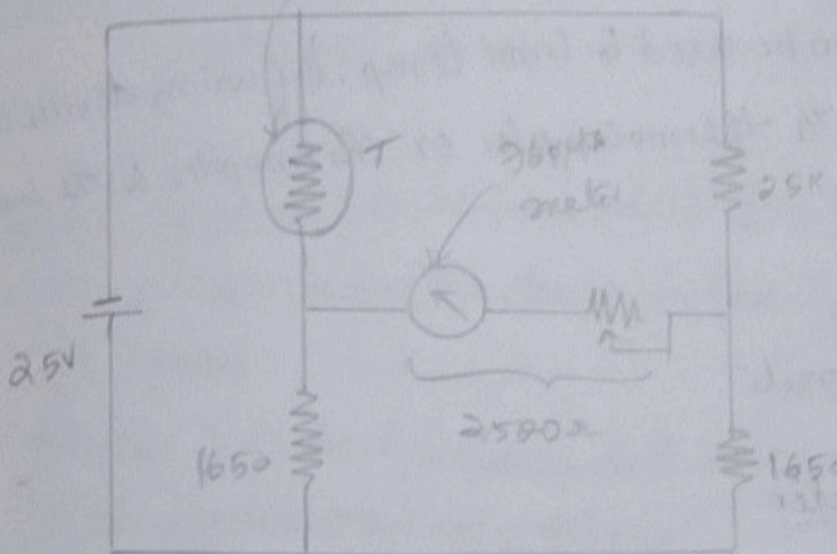
Small amount of Voltage applied when heat supplied and heat dissipation equal and equilibrium reached

Current Time Chara



Linearization technique of Thermist

500Ω @ 25°C



$R_1 = \frac{1}{\alpha} \frac{T}{25}$
 $R_1 = 1650 \frac{T}{25}$
 $R_1 R_4 = R_2 R_3$
 $\frac{R_1}{R_2} = \frac{R_3}{R_4}$

The series configuration requires a voltage excitation

Advantages of thermistor

- Small size and low cost
- Comparative large change in resistance for a given change in temp
- Fast response over a narrow temp range

Limitations thermistors

- The resistance versus temp chara is highly non-linear
- Not suitable over a wide temp range

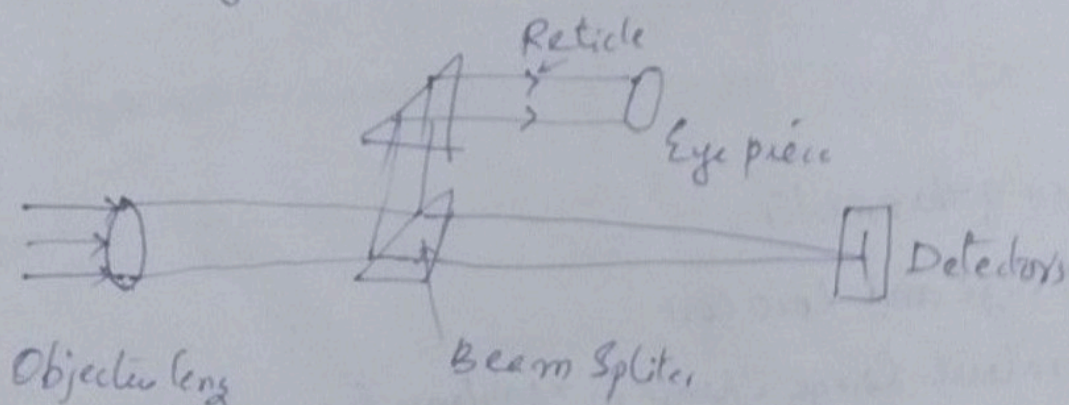
Thermistor Applications

- Monitor the temp of an incubator
- Modern digital thermostats and to monitor the temp of battery packs while charging
- Automotive applications
- Low-temp measurements
- Over-current limiting devices in power supply ckt

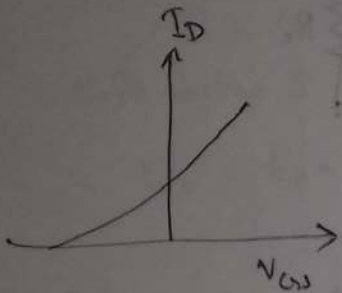
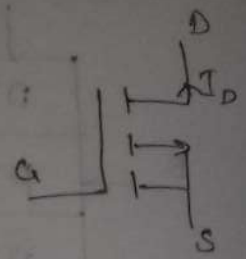
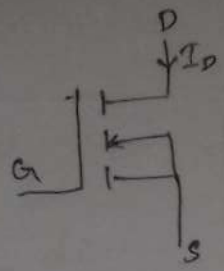
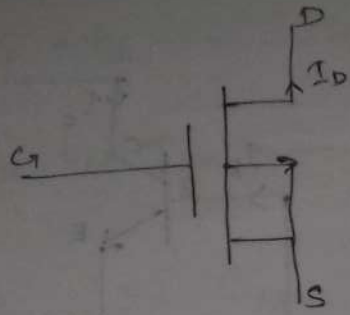
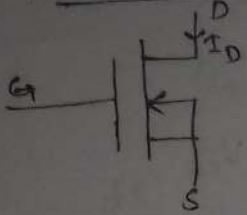
Pyrometers

- Radiation can be used to sense temp, by using devices called pyrometer, with thermocouples or thermopiles as the sensing element
- Radiation
- Optical pyrometer

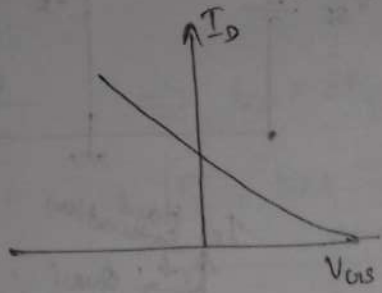
Radiation pyrometer



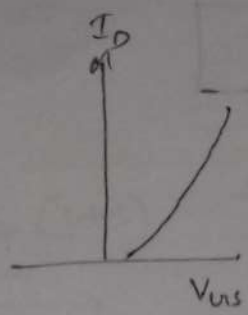
Power MOSFET



n-channel depletion



p-channel depletion



n-channel enhancement

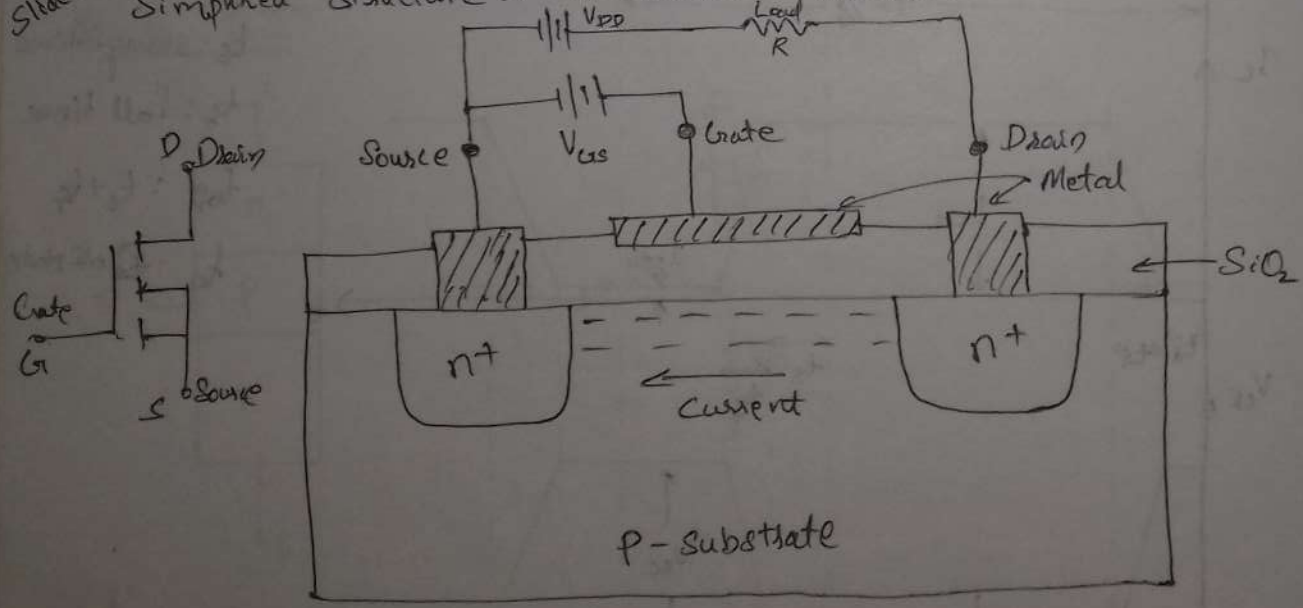


p-channel enhancement

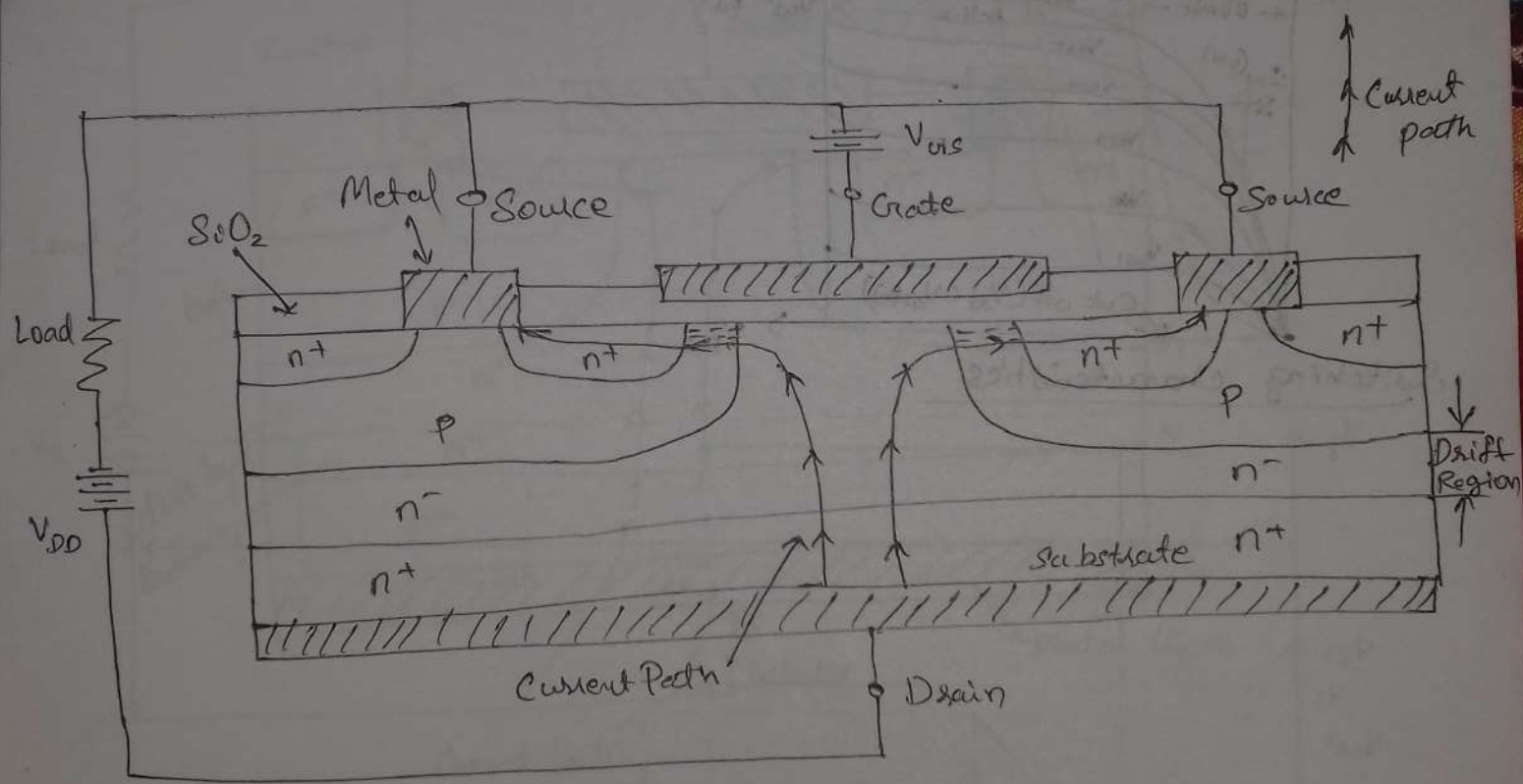
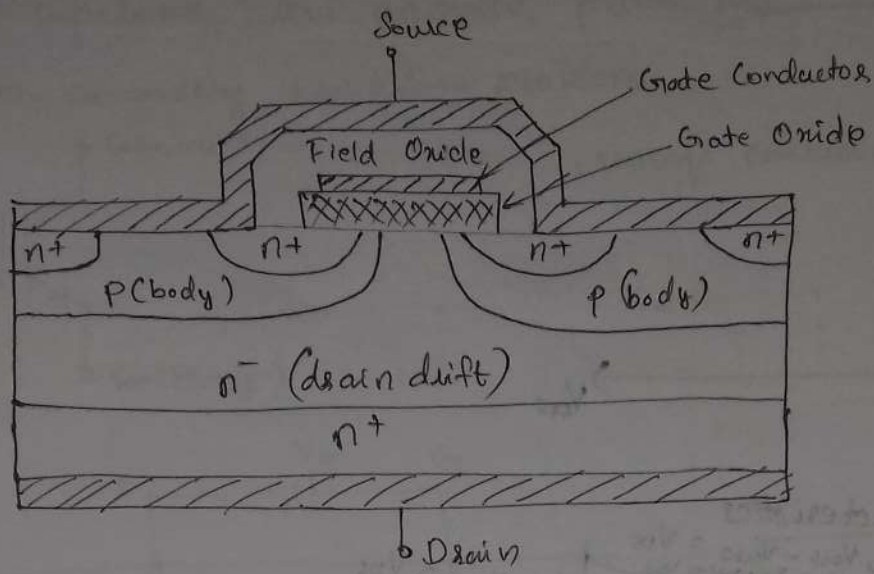
- Arrow indicates the direction of electron flow
- Voltage controlled device
- Unipolar device
- n-channel enhancement type is commonly use due to higher mobility of electron.
- Low power high frequency application

Slide No: 68

Simplified structure of n-channel MOSFET



n-channel diffused mos power MOSFET

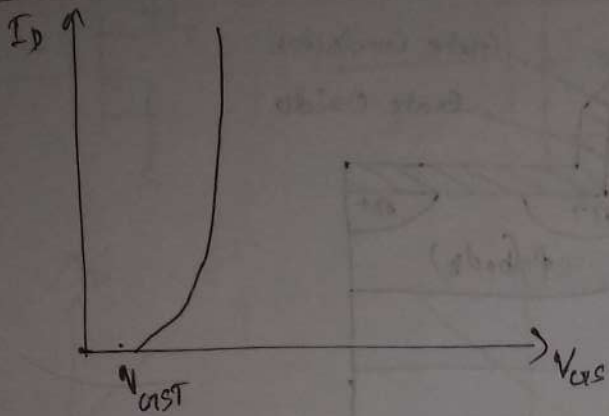


Characteristics

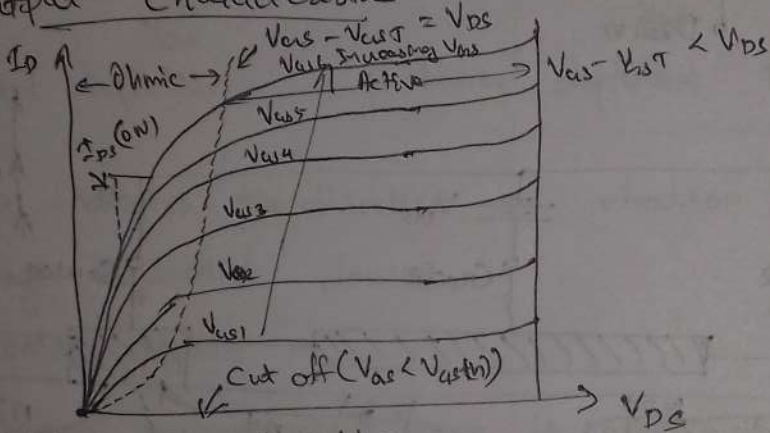
- Static Characteristics
- 1) Transfer Characteristics
 - 2) Output Characteristics

Dynamic characteristics - switching characteristics (Turn on / Turn off)

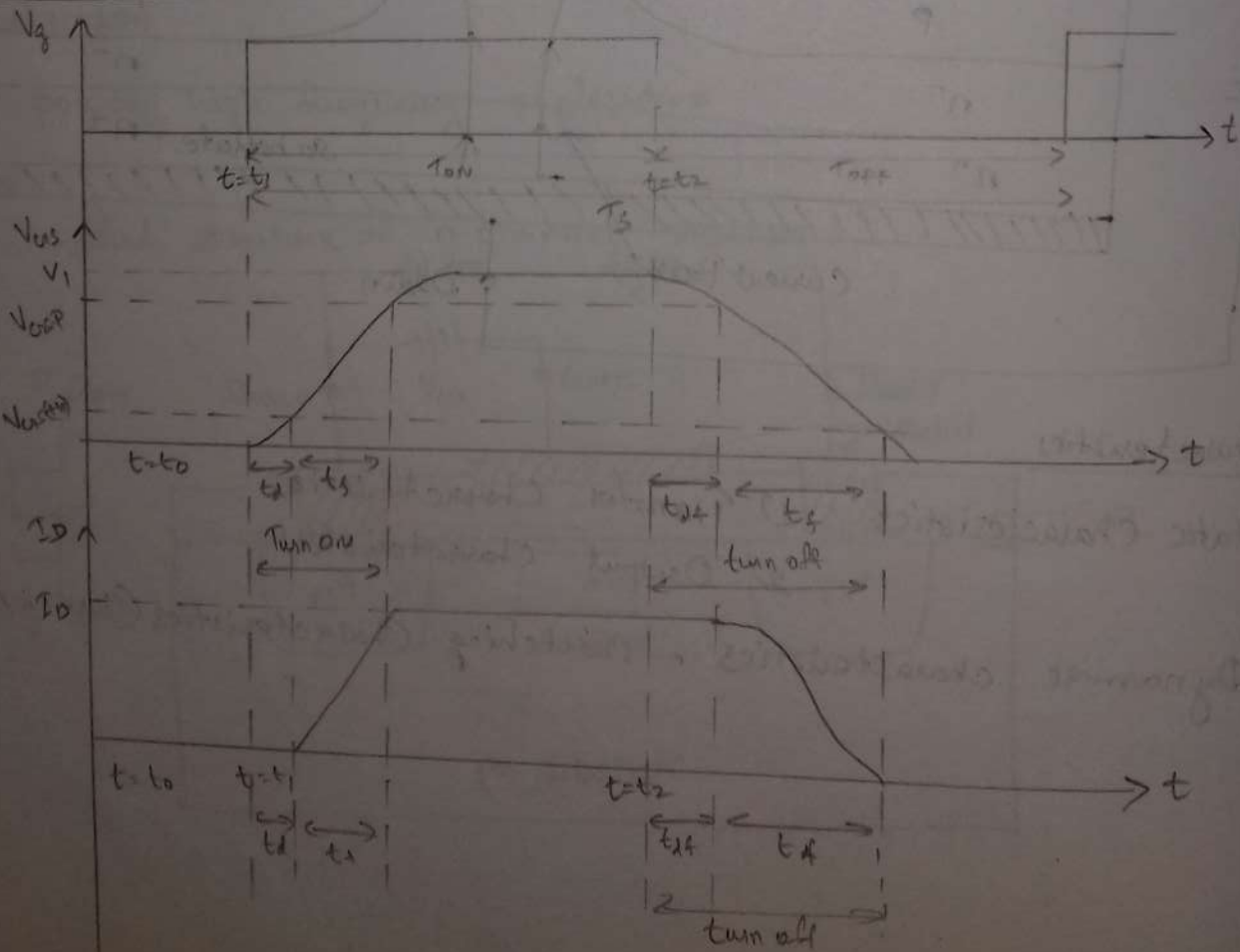
Transfer characteristics



Output characteristics



Switching characteristics



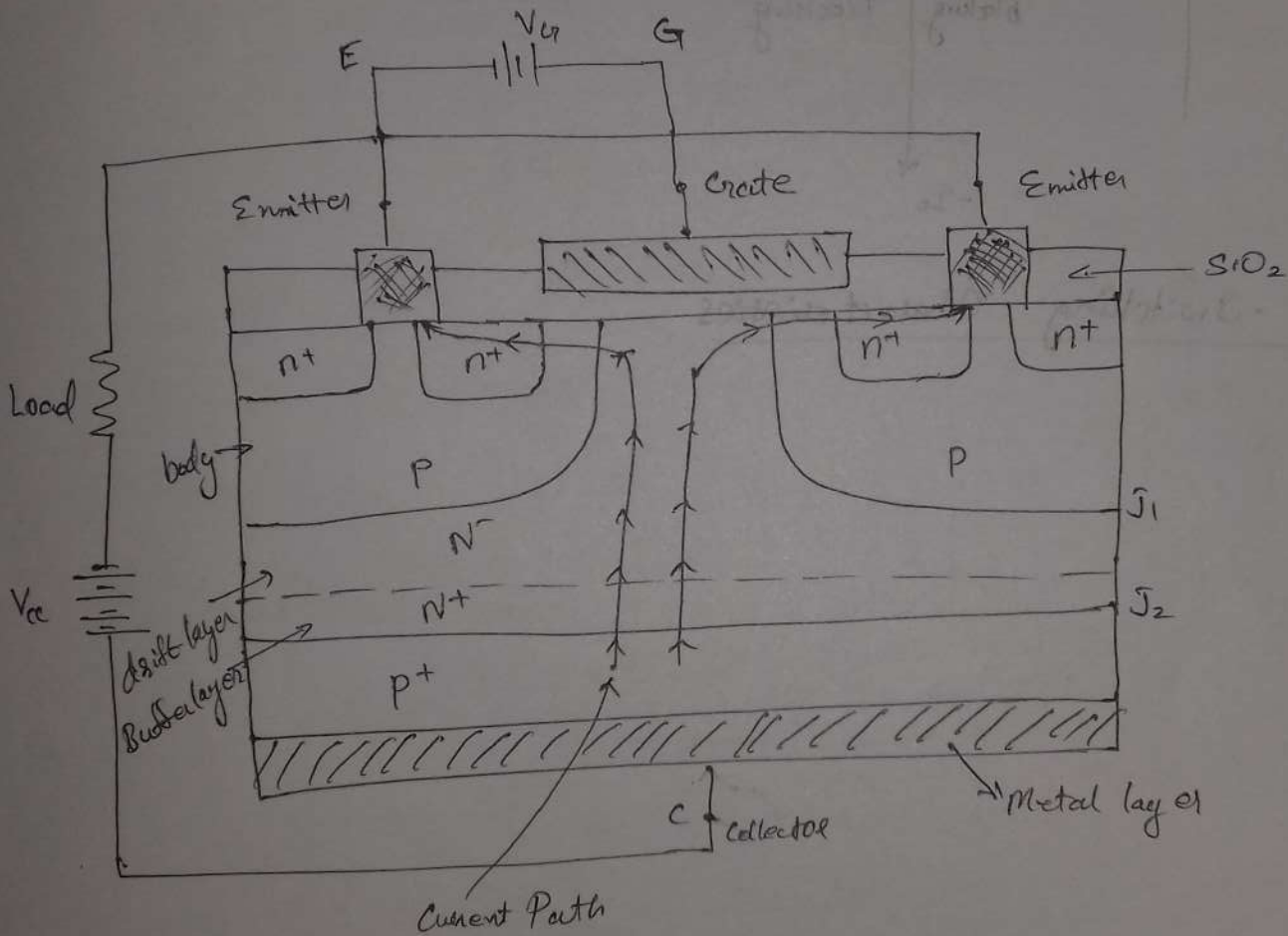
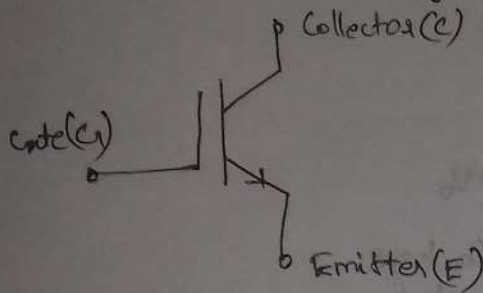
IGBT

29/04/2022

High input impedance, low on state power loss

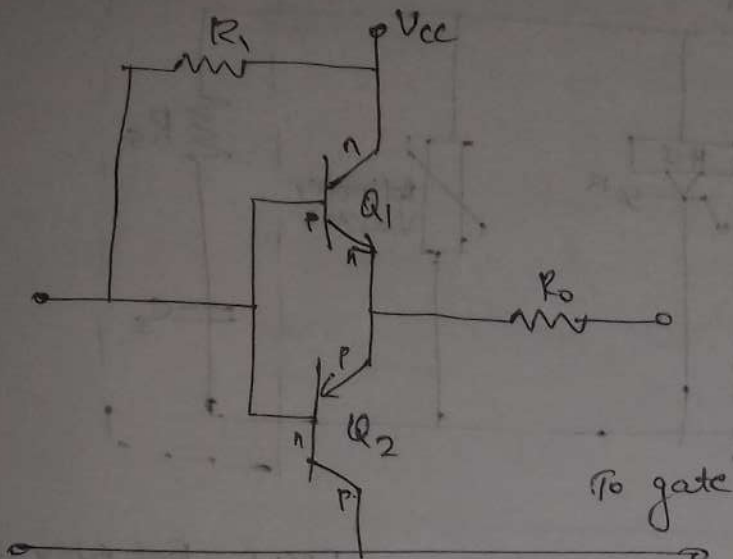
Free from secondary breakdown problem

• Voltage controlled device



MOSFET gate control circuit

16/5/22

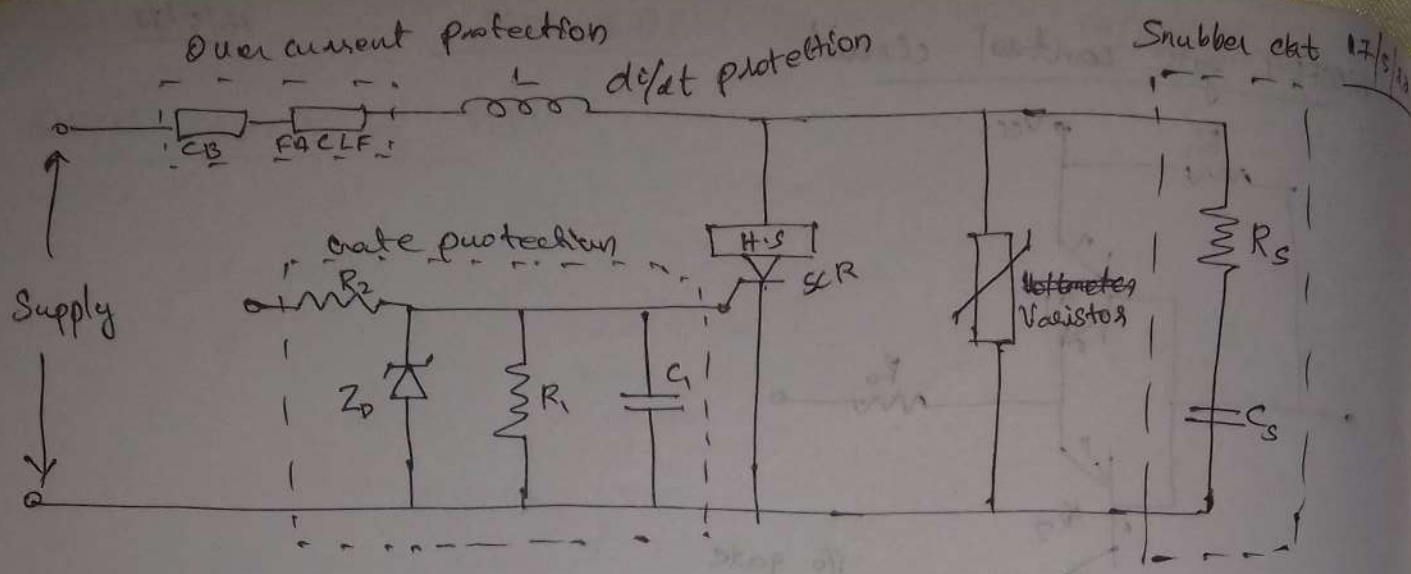


Totem-pole gate driver ckt

(npn, pnp) transistor pair offers low i_{fz} impedance and operating ~~at~~ in linear region.

Snubber circuit

- Snubber circuit are capable of reducing ~~and~~ ^{or} eliminating voltage and current spikes.
- For limiting di/dt and dV/dt
- Shaping load line to keep it within safe operating area.
- To reduce the total switching losses.
- Reducing EMI by damping voltage.
- Transferring power dissipation from switch to a resistor or useful load.
- "Mainly for power dissipation reduction"

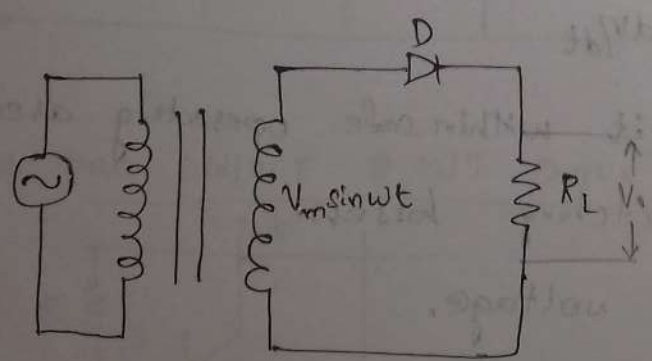


FACLF - Fast Acting Fuse

- 1) Overcurrent
- 2) di/dt
- 3) dv/dt
- 4) Gate protection
- 5) Temperature

Diode Rectifier

Single Phase Half Wave Rectifier



$$V_{avg} = \frac{1}{T} \int_0^T V dt$$

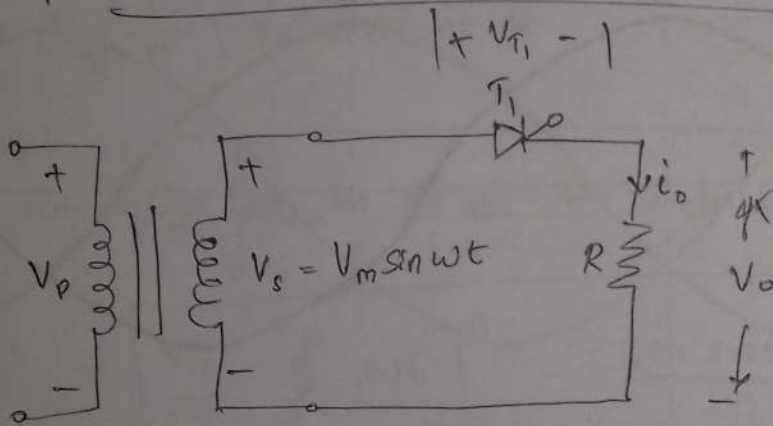
RMS → Root Mean Square

$$V_{rms} = \sqrt{\frac{1}{T} \int_0^T V^2 dt}$$

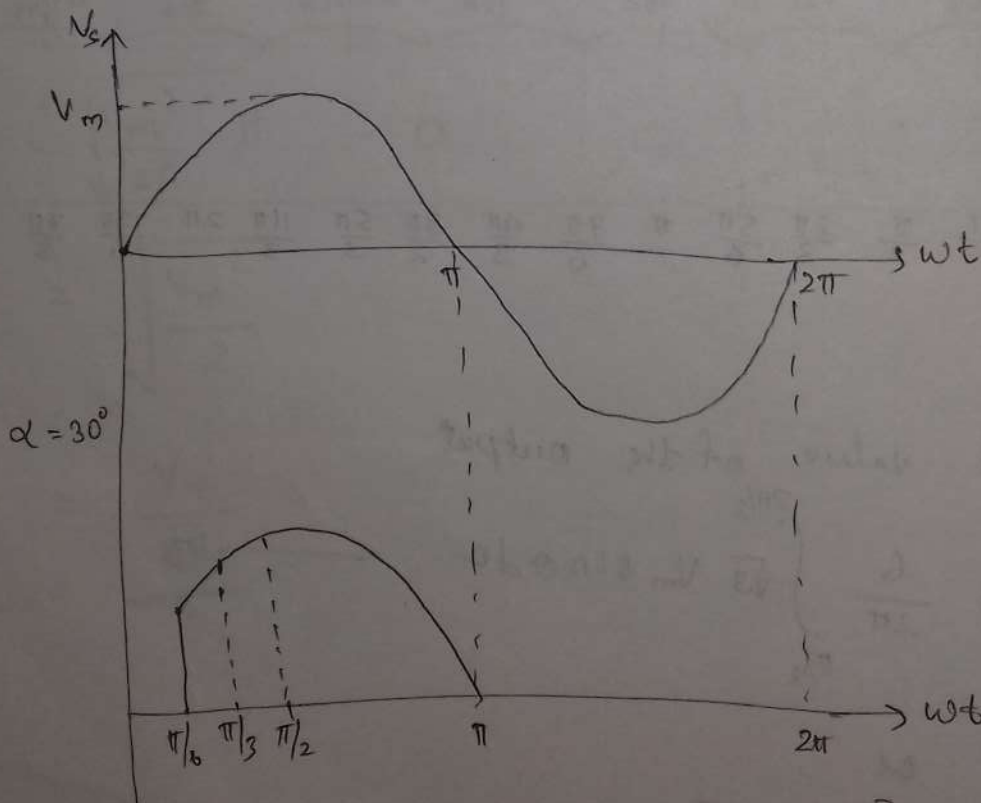
$$V_{rms} = V_m \sqrt{\frac{3}{2} + \frac{9\sqrt{3}}{4\pi}} = 1.655 V_m$$

Phase Controlled Rectifier

single phase Half wave ~~Rectifier~~ Controlled Rectifier with R load

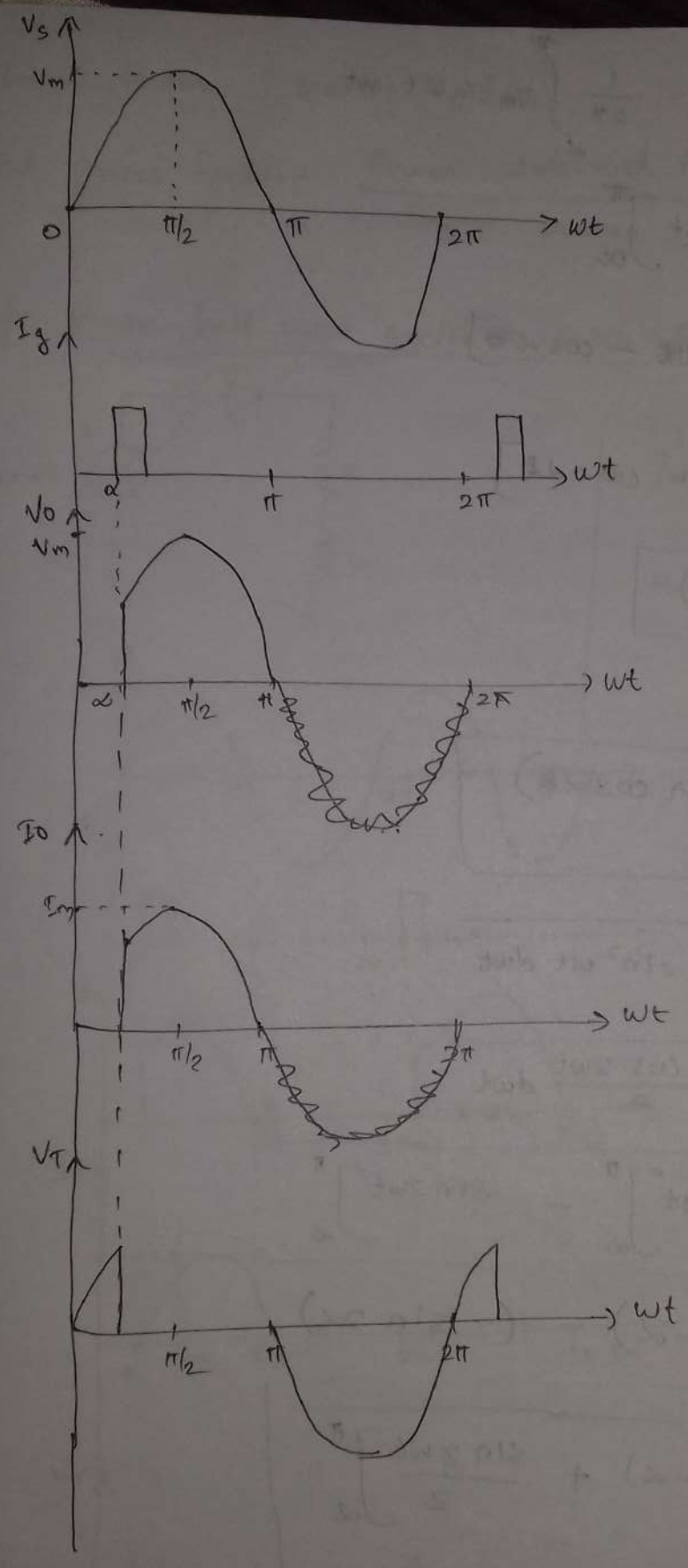


Thyristor should be forward biased
Gate signal should be provided



$$V_{dc} = \frac{1}{T} \int_0^T V_o dt = \frac{1}{2\pi} \int_{\alpha}^{\pi} V_m \sin \omega t d\omega t$$

27/05/2020



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d biased
rovided

dust

$$V_{dc} = \frac{1}{T} \int_0^T v dt = \frac{1}{2\pi} \int_{\alpha}^{\pi} V_m \sin \omega t dt$$

$$= \frac{-V_m}{2\pi} \left[\cos \omega t \right]_{\alpha}^{\pi}$$

$$= \frac{-V_m}{2\pi} \left[\cos \pi - \cos \alpha \right]$$

$$= \frac{-V_m}{2\pi} \left[-1 - \cos \alpha \right]$$

$$V_{avg} = \frac{V_m(1 + \cos \alpha)}{2\pi}$$

$$I_{avg} = \frac{V_o}{R}$$

$$I_{avg} = \frac{V_m}{2\pi R} (1 + \cos \alpha)$$

$$V_{rms} = \sqrt{\frac{1}{2\pi} \int_{\alpha}^{\pi} V_m^2 \sin^2 \omega t dt}$$

$$= \sqrt{\frac{V_m^2}{2\pi} \int_{\alpha}^{\pi} \frac{1 - \cos 2\omega t}{2} dt}$$

$$= \sqrt{\frac{V_m^2}{4\pi} \left[\omega t - \frac{\sin 2\omega t}{2} \right]_{\alpha}^{\pi}}$$

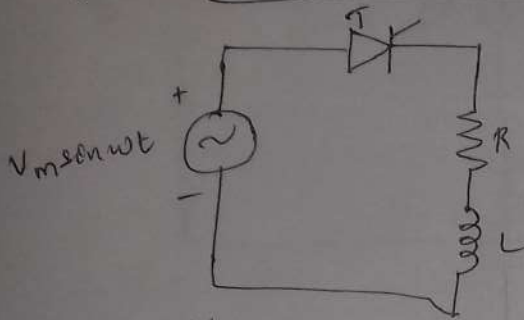
$$= \sqrt{\frac{V_m^2}{4\pi} \left((\pi - \alpha) - \left(-\frac{\sin 2\alpha}{2} \right) \right)}$$

$$V_{rms} = \frac{V_m}{2\sqrt{\pi}} \sqrt{(\pi - \alpha) + \frac{\sin 2\alpha}{2}}$$

Input Power $P(VA) = V_s I_{rms}$

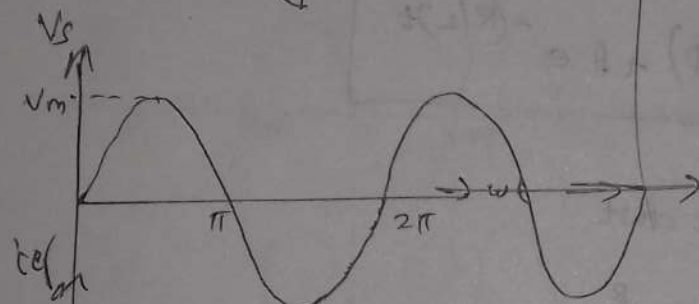
Input power factor = $\frac{\text{Power delivered to load}}{\text{Input power}}$

Single phase half wave rectifier with RL load



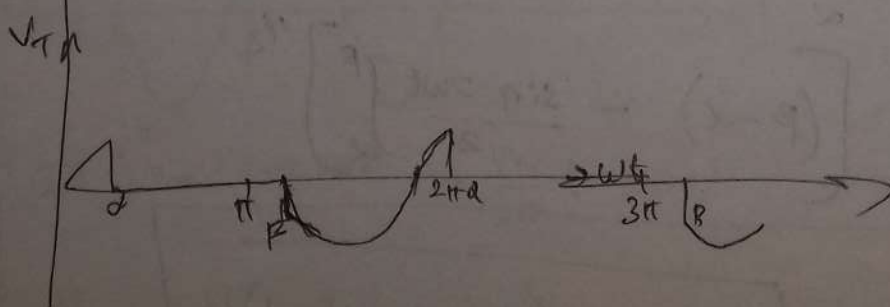
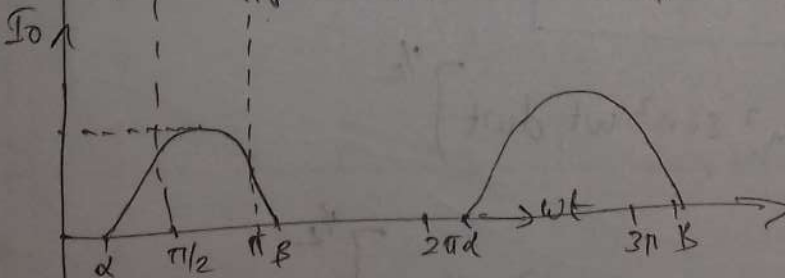
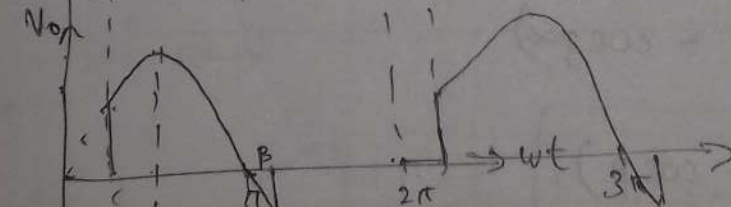
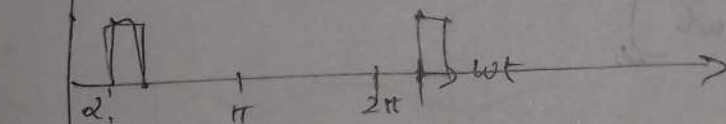
Latching current: Minimum current to turn on

Holding current: Minimum current, ~~to~~ no to turn off the ~~of~~ systems



α : triggering angle
 β : extinction angle

$\gamma = \beta - \alpha = \text{conduction angle}$



$$I = \frac{V_m}{Z} \sin(\omega t - \phi)$$

$$Z = \sqrt{R^2 + X^2}$$

$$V_s = V_m \sin \omega t$$

$I_0 = I_s + I_t$ → Input current + transient current

$$V_m = Ri_0 - L \frac{di_0}{dt}$$

$$0 = Ri_t - L \frac{di_t}{dt}$$

$$i_t = A e^{-(R/L)t}$$

$$I_0 = \frac{V_m}{Z} \sin(\omega t - \phi) + A e^{-(R/L)t}$$

$$V_{avg} = \frac{1}{2\pi} \int_{\alpha}^{\beta} V_m \sin \omega t \, d\omega t$$

$$= \frac{V_m}{2\pi} [-\cos \omega t]_{\alpha}^{\beta}$$

$$= -\frac{V_m}{2\pi} (\cos \beta - \cos \alpha)$$

$$V_{avg} = \frac{V_m}{2\pi} (\cos \alpha - \cos \beta)$$

$$V_{rms} = \left[\frac{1}{2\pi} \int_{\alpha}^{\beta} V_m^2 \sin^2 \omega t \, d\omega t \right]^{1/2}$$

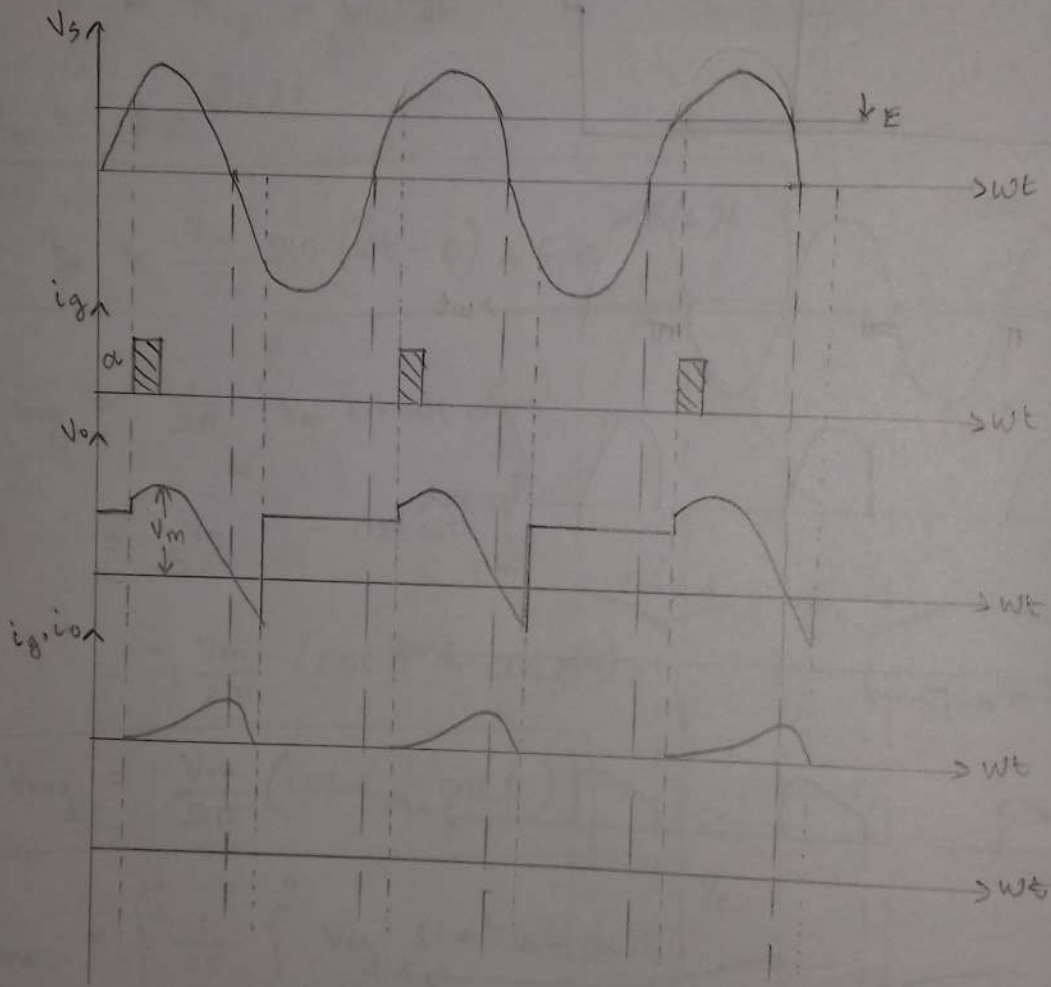
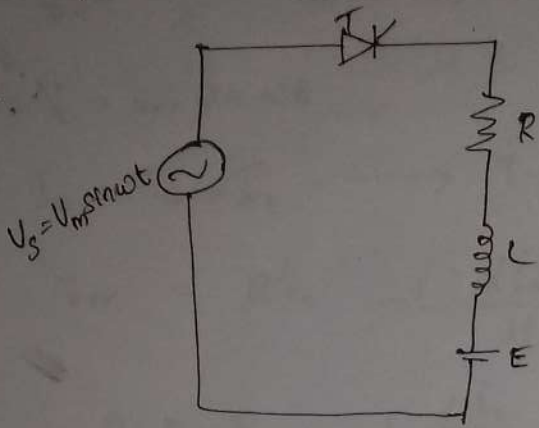
$$= \left[\frac{V_m^2}{2\pi \times 2} \int_{\alpha}^{\beta} (1 - \cos 2\omega t) \, d\omega t \right]^{1/2}$$

$$= \frac{V_m}{2\sqrt{\pi}} \left[(\beta - \alpha) - \frac{\sin 2\omega t}{2} \right]_{\alpha}^{\beta} \Bigg|^{1/2}$$

$$V_{rms} = \frac{V_m}{2\sqrt{\pi}} \sqrt{(\beta - \alpha) - \frac{1}{2} (\sin 2\beta - \sin 2\alpha)}$$

single phase half wave controlled with REL load

31/05/2022

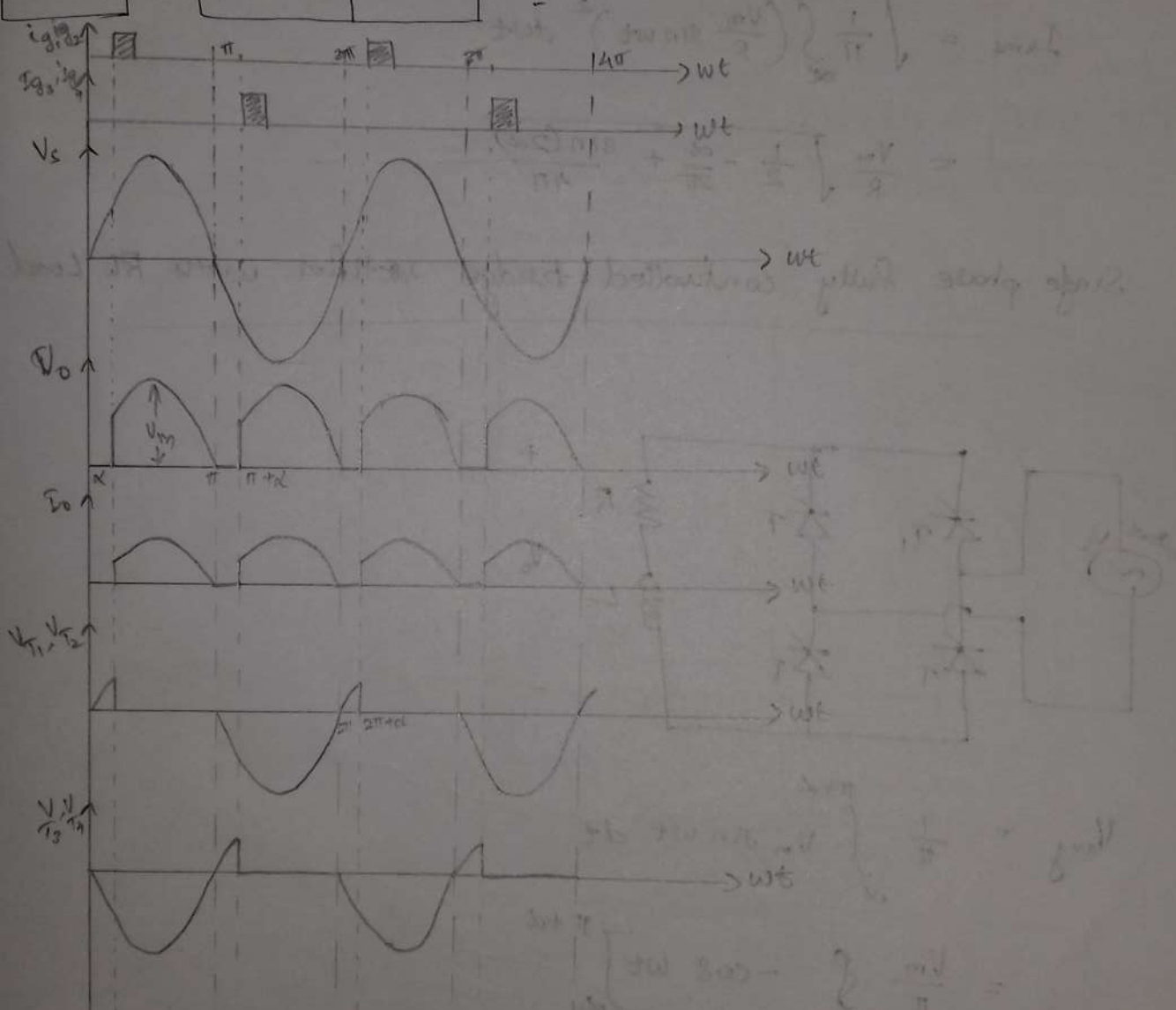
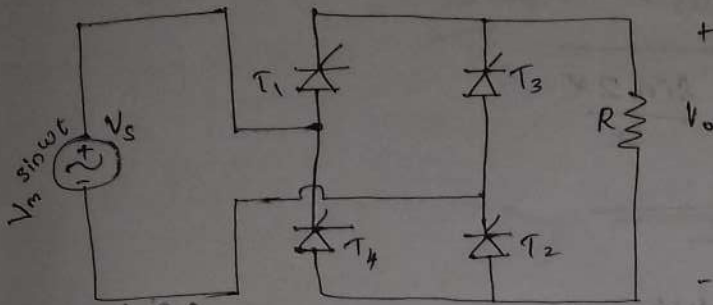


$$V_m \sin \omega t = Ri_o + L \frac{di_o}{dt} + E$$

$$V_o = \frac{1}{2\pi} \int_{\alpha}^{\beta} V_m \sin \omega t d\omega t + E (2\pi + \alpha - \beta)$$

$$I_o = \frac{1}{2\pi R} [V_m (\cos \alpha + \cos \theta_1) - E (\pi - (\theta_1 + \alpha))]$$

Single phase fully controlled bridge rectifier with R Load



$$V_o = \frac{1}{2\pi} \int_{\alpha}^{\pi} 2 V_m \sin \omega t \, d\omega t$$

$$V_o = \frac{V_m}{\pi} (1 + \cos \alpha)$$

$$V_{rms} = \left[\frac{1}{\pi} \int_{\alpha}^{\pi} V_m^2 \sin^2 \omega t \, d\omega t \right]^{1/2} = \left[\frac{V_m^2}{2\pi} \left((\pi - \alpha) + (1 + \cos 2\alpha) \right) \right]^{1/2}$$

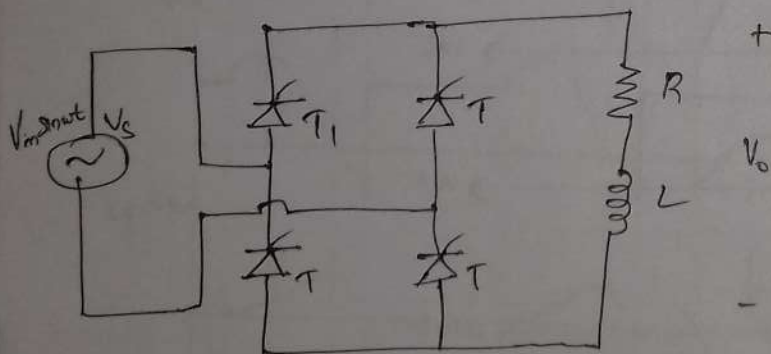
$$= \sqrt{\frac{V_m^2}{2\pi} \int_{\alpha}^{\pi} (1 - \cos 2\omega t) d\omega t}$$

$$= \frac{V_m}{\sqrt{2\pi}} \sqrt{(\pi - \alpha) + \frac{\sin 2\alpha}{2}}$$

$$I_{\text{rms}} = \sqrt{\frac{1}{\pi} \int_{\alpha}^{\pi} \left(\frac{V_m}{R} \sin \omega t\right)^2 d\omega t}$$

$$= \frac{V_m}{R} \sqrt{\frac{1}{2} - \frac{\alpha}{2\pi} + \frac{\sin(2\alpha)}{4\pi}}$$

Single phase fully controlled bridge rectifier with RL Load



$$V_{\text{avg}} = \frac{1}{\pi} \int_{\alpha}^{\pi + \alpha} V_m \sin \omega t dt$$

$$= \frac{V_m}{\pi} \int_{\alpha}^{\pi + \alpha} -\cos \omega t dt$$

$$= \frac{V_m}{\pi} [-\cos(\pi + \alpha) + \cos \alpha]$$

$$= \frac{V_m}{\pi} [-(-\cos \alpha) + \cos \alpha]$$

$$= \frac{2V_m}{\pi} \cos \alpha$$

$$\text{OFF time} = \frac{\pi - \alpha}{\omega} \text{ sec}$$

Network Theory - Jithin James.

	Day 1	Day 2	Day 3	Day 4	Day 5	Day 6
	3/11/21	10/11/21	17/11/21	24/11/21	1/12/21	8/12/21
1 Adil .K	AB	AB	AB	AB	AB	AB
2 Ajay .K.P	Adil	Adil	Adil	Adil	Adil	Adil
3 Akhil .M.A	Adil	Adil	Adil	Adil	Adil	Adil
4 Akshai Mohan	Adil	AB	Adil	Adil	Adil	Adil
5 Akshay .M	Adil	Adil	Adil	Adil	Adil	Adil
6 Alan Sunny	Adil	Adil	Adil	Adil	Adil	Adil
7 Alan Joe Prince	Adil	Adil	Adil	Adil	Adil	Adil
8 Anargh .K	Adil	Adil	Adil	AB	Adil	Adil
9 Aswin .T.S	Adil	Adil	Adil	Adil	Adil	Adil
10 Aswin Vinod .C	Adil	Adil	Adil	Adil	Adil	Adil
11 Ayana .P.V	Adil	Adil	Adil	Adil	Adil	Adil
12 Dipraj .M	Adil	Adil	Adil	Adil	Adil	Adil
13 Hiranand .T	Adil	Adil	Adil	Adil	Adil	Adil
14 Joyal Saji	AB	Adil	Adil	Adil	Adil	AB
15 Jude Tomon George	Adil	Adil	Adil	Adil	Adil	Adil
16 Kevin Saji	Adil	Adil	Adil	Adil	Adil	Adil
17 Kuan .K.V	Adil	Adil	AB	Adil	Adil	Adil
18 Mornal .C. Pradeep	Adil	Adil	Adil	Adil	Adil	Adil
19 Muhammed Sahl	Adil	Adil	Adil	Adil	Adil	Adil
20 Revanth .P.V.K	Adil	Adil	Adil	Adil	Adil	Adil
21 Tom Jessan	Adil	Adil	Adil	Adil	Adil	Adil
22 Vyshnav .K.	Adil	Adil	Adil	Adil	Adil	Adil
23 Jithin James	Jithin	Jithin	Jithin	Jithin	Jithin	Jithin

S3 AEI

24 Partial Differential Eqn & Complex Analysis - Vineetharool

		Day 1	Day 2	Day 3	Day 4	Day 5	Abraham
		4/11/21	11/11/21	18/11/21	25/11/21	2/12/21	9/12/21
1	Adil . K	AB	AB	AB	AB	AB	AB
2	Ajay . K.P	Adil	Adil	Adil	Adil	Adil	Adil
3	Akhil . M.A	Adil	Adil	Adil	Adil	Adil	Adil
4	Akshas Mohan	AB	Akshay	Akshay	Akshay	Akshay	Akshay
5	Akshay . M	Akshay	Akshay	Akshay	Akshay	Akshay	Akshay
6	Alan Sunny	Akshay	Akshay	Akshay	Akshay	Akshay	Akshay
7	Alan Joe Prince	Adil	Adil	Adil	Adil	AB	Adil
8	Anargh . K	Adil	Adil	Adil	Adil	AB	Adil
9	Aswin . T.S	Adil	Adil	AB	Adil	Adil	Adil
10	Aswin Vinod . C	Aswin	Aswin	Aswin	Aswin	Aswin	Aswin
11	Ayana . P.V	Ayana	Ayana	Ayana	Ayana	Ayana	Ayana
12	Dipinraj . M	Dipin	Dipin	Dipin	Dipin	Dipin	Dipin
13	Hemadep . T	Hemadep	Hemadep	Hemadep	Hemadep	Hemadep	Hemadep
14	Joyal Saji	Joyal	Joyal	Joyal	Joyal	Joyal	AB
15	Jude Tomon George	Jude	Jude	Jude	Jude	Jude	Jude
16	Kevin Saji	Kevin	Kevin	Kevin	Kevin	Kevin	Kevin
17	Kuam . K.V	Adil	Adil	Adil	Adil	Adil	Adil
18	Manil . C. Pradeep	Manil	AB	Manil	Manil	Manil	Manil
19	Muhammed Sahl	Sahl	Sahl	Sahl	Sahl	Sahl	Sahl
20	Revanth . P.V.K	Revanth	Revanth	Revanth	Revanth	Revanth	Revanth
21	Tom Jessan	Tom	Tom	Tom	Tom	Tom	Tom
22	Vyshnav . K.	Vyshnav	Vyshnav	Vyshnav	Vyshnav	Vyshnav	Vyshnav
	Vineetharool	Vino	Vino	Vino	Vino	Vino	Vino

Logic Circuit Design - Dr. Roshini T.V.

		Day 1	Day 2	Day 3	Day 4	Day 5	Day 6
		5/11/21	12/11/21	19/11/21	26/11/21	3/12/21	10/12/21
1	Adil.K	AB	AB	AB	AB	AB	AB
2	Ajay.K.P	AB	AB	AB	AB	AB	AB
3	Akhil.M.A	AB	AB	AB	AB	AB	AB
4	Akshas Mohan	AB	AB	AB	AB	AB	AB
5	Akshay.M	AB	AB	AB	AB	AB	AB
6	Alan Sunny	AB	AB	AB	AB	AB	AB
7	Alan Joe Prince	AB	AB	AB	AB	AB	AB
8	Anaagh.K	AB	AB	AB	AB	AB	AB
9	Aswin T.S	AB	AB	AB	AB	AB	AB
10	Aswin Vinod.C	AB	AB	AB	AB	AB	AB
11	Ayana P.V	AB	AB	AB	AB	AB	AB
12	Dipusaj.M	AB	AB	AB	AB	AB	AB
13	Hirandeep.T	AB	AB	AB	AB	AB	AB
14	Joyal Saji	AB	AB	AB	AB	AB	AB
15	Jude Tomon George	AB	AB	AB	AB	AB	AB
16	Kevin Saji	AB	AB	AB	AB	AB	AB
17	Kuian.K.V	AB	AB	AB	AB	AB	AB
18	Morial.C.Pradeep	AB	AB	AB	AB	AB	AB
19	Muhammed Sahl	AB	AB	AB	AB	AB	AB
20	Revanth P.V.K	AB	AB	AB	AB	AB	AB
21	Tom Jessan	AB	AB	AB	AB	AB	AB
22	Vyshnav.K.	AB	AB	AB	AB	AB	AB
	Dr. Roshini T.V	Roshi	Roshi	Roshi	Roshi	Roshi	Roshi

Solid State Devices - Sudhassana Vijayan

		Day 1	Day 2	Day 3	Day 4	Day 5	Day 6
		5/11/21	12/11/21	19/11/21	26/11/21	3/12/21	10/12/21
1	Adil . K	AB	AB	AB	AB	AB	AB
2	Ajay . K . P						
3	Akshil . M . A						
4	Akshar Mohan						
5	Akshay . M						
6	Alem Sunny						
7	Alen Joe Ponce		AB				
8	Anargh . K						
9	Aswin . T . S						
10	Aswin Vinod . C						
11	Ayana . P . V						
12	Dipusraj . M						
13	Hirandeep . T						
14	Joyal Saji				AB		
15	Jude Tomon George						
16	Kevin Saji						
17	Kuram . K . V						
18	Monial . C . Pradeep						
19	Muhammed Sahl .					AB	
20	Revanth . P . V . K						
21	Tom Jessan	AB					
22	Vyshnav . K						
	Sudhassana Vijayan						

Probability & Numerical Methods - Dominic N Thomas.

	Day 1 4/1/22	Day 2 11/1/22	Day 3 18/1/22	Day 4 25/1/22	Day 5 1/2/22	Day 6 8/2/22
1 Adil. K						
2 Ajay. K.P	P	P	P	P	P	P
3 Akhil. M.A	P	P	P	P	P	P
4 Akshar Mohan.	P	P	P	AB	P	P
5 Akshay. M.	P	P	P	P	P	P
6 Alan Sunny	P	P	P	P	P	P
7 Alan Joe Prince	P	P	P	P	P	P
8 Anargh. K	P	P	P	P	P	P
9 Aswini T.S	P	P	P	P	P	P
10 Aswin Vinod. C	P	P	P	P	P	P
11 Ayana. P.V	P	P	P	P	P	P
12 Dipiraj. M	P	AB	P	P	P	P
13 Hirandeep. T	P	P	P	P	P	P
14 Joyal Saji	P	P	P	P	P	P
15 Jude Tomon George	P	P	P	P	P	P
16 Kevin Saji	P	P	P	P	P	AB
17 Kuran K.V	P	P	P	P	P	P
18 Mrinal. C. Pradeep	P	P	P	P	P	P
19 Muhammed Sahl	P	P	P	P	P	P
20 Revanth P.V.K	P	P	AB	P	P	P
21 Tom Jessan	P	P	P	P	P	P
22 Vyshnav. K.	P	P	P	P	P	P

Dominic. N. Thomas

Dm

Dm

Dm

Dm

Dm

Dm

32 Signals & Systems - Vinod J. Thomas.

	Day 1 5/1/22	Day 2 12/1/22	Day 3 19/1/22	Day 4 26/1/22	Day 5 2/2/22	Day 6 9/2/22
1. Adil . K	/	/	/	/	/	/
2. Ajay . K.P	/	/	/	/	/	/
3. Akhil . M.A	/	/	/	/	/	/
4. Akshas Mohan	/	/	/	/	/	/
5. Akshay . M	/	/	/	/	Ab	/
6. Alan Sunny	/	/	/	/	/	/
7. Alan Joe Ponce	Ab	/	/	/	/	/
8. Anagh . k	/	/	/	/	/	/
9. Aswin T.S	/	/	/	/	/	/
10. Aswin Vinod . C	/	/	/	Ab	/	/
11. Ayana . P.V	/	/	/	/	/	/
12. Dipuraj . M	/	/	/	/	/	/
13. Hirandeep . T	/	Ab	/	/	/	/
14. Jeyal Saij	/	/	/	/	/	/
15. Jude Jomon George	/	/	/	/	/	/
16. Kevin Saij	/	/	/	/	/	Ab
17. Kiran . K.V	/	/	/	/	/	/
18. Manial . C. Pradeep	/	/	Ab	/	/	/
19. Muhammed Sahl.	/	/	/	/	/	/
20. Revanth P.V.K	/	/	/	/	/	/
21. Tom Jessan	/	/	/	/	/	/
22. Vyshnav . k	/	/	/	/	/	/
Vinod . J. Thomas	<u>Vin</u>	<u>Vin</u>	<u>Vin</u>	<u>Vin</u>	<u>Vin</u>	<u>Vin</u>

Day 7	Day 8	Day 9	Day 10	Day 11	Day 12	Day 13	Day 14	Day 15
16/2/22	23/2/22	2/3/22	9/3/22	16/3/22	23/3/22	30/3/22	6/4/22	13/4/22

/	/	/	/	/	/	/	/	/
/	AB	/	/	AB	/	/	/	/
/	/	/	/	/	/	/	/	AB
/	/	/	/	/	/	/	/	/
/	/	/	/	/	AB	/	/	/
/	/	/	/	/	/	/	/	/
/	/	AB	/	/	/	/	/	/
/	/	/	/	/	/	/	/	/
/	/	/	/	/	/	/	AB	/
/	/	/	/	/	/	/	/	/
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/	/	/	/	/	/	/	/	/
/	/	/	AB	/	/	/	/	/
/	/	/	/	/	/	AB	/	/
/	/	/	/	/	/	/	/	/
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/	/	/	/	/	/	/	/	/
/	/	/	/	/	/	/	/	/
/	/	/	/	/	/	/	/	/
AB	/	/	/	/	/	/	/	/
/	/	/	/	/	/	/	/	/

Vin Vin Vin Vin Vin Vin Vin Vin Vin

Electrical Measurements & Measuring Instruments - Dhanoj. M.

	Day 1 5/1/22	Day 2 12/1/22	Day 3 19/1/22	Day 4 26/1/22	Day 5 2/2/22	Day 6 9/2/22
1 Adil.k	/	/	/	/	/	/
2 Ajay.k.P	/	/	/	/	/	/
3 Akhil.M.A	/	/	/	AB	/	/
4 Akshar Mohan	AB	/	/	/	/	/
5 Akshay.M	/	/	/	/	/	/
6 Alan Sunny	/	/	/	/	/	/
7 Alan Joe Prince	/	/	/	/	/	/
8 Anargh.k	/	/	/	/	/	/
9 Aswin T.S	/	/	/	/	/	/
10 Aswin Vinod.C	/	/	/	/	/	/
11 Ayana.P.V	/	/	AB	/	/	/
12 Dipuraj.M	/	/	/	/	/	/
13 Hisandeep.T	/	/	/	/	/	/
14 Jyoti Saji	/	/	/	/	/	/
15 Jude Jomon George	/	/	/	/	/	/
16 Kevin Saji	/	/	/	/	/	/
17 Kunal K.V	/	/	/	/	/	/
18 Mural.C. Pradeep.	/	/	/	/	/	/
19 Muhammed Sahl-	/	/	/	/	/	/
20 Revanth P.V.k	/	/	/	/	/	/
21 Tom Jessan	/	/	/	/	/	/
22 Vyshtnav.k	/	AB	/	/	/	/

Dhanoj.M

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Day 7	Day 8	Day 9	Day 10	Day 11	Day 12	Day 13	Day 14	Day 15
16/2/22	23/2/22	2/3/22	9/3/22	16/3/22	23/3/22	30/3/22	6/4/22	13/4/22

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/	/	/	Ab	/	/	Ab	/	/
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/	/	/	/	/	Ab	/	/	/
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Ab	/	/	/	/	/	/	/	/
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/	/	/	/	/	/	/	Ab	/
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36 Analog Circuits - Shrinu.M.M.

	Day 1 9/1/22	Day 2 14/1/22	Day 3 21/1/22	Day 4 28/1/22	Day 5 4/2/22	Day 6 11/2/22
1. Adil . k	/	/	/	/	/	/
2. Aray . K.P	/	/	/	/	/	/
3. Akhil . M.A	/	/	/	/	/	/
4. Akshas Mohan	AB	/	/	/	/	/
5. Akshay . M	/	/	/	/	/	/
6. Alan Sunny	/	/	/	/	/	/
7. Alan Joe Prince	/	/	/	/	AB	/
8. Anasgh . k	/	/	/	/	/	/
9. Aswin T.S	/	/	AB	/	/	/
10. Aswin Vinod . C	/	/	/	/	/	/
11. Ayana . P.V	/	/	/	/	/	/
12. Dipusaj . M	/	/	/	/	/	/
13. Hisandeep . T	/	/	/	/	/	/
14. Joyal Saji	/	/	/	/	/	/
15. Jude Tomon George	/	/	/	/	/	/
16. Kevio Saji	/	/	/	/	/	/
17. Keran K.V	/	/	/	/	/	/
18. Manial . C . Pradeep	/	/	/	/	/	/
19. Muhammed Sahl	/	/	/	AB	/	/
20. Revanth P.V.k	/	/	/	/	/	/
21. Tom Jessan	/	/	/	/	/	/
22. Vyshtnav . k	/	/	/	/	/	/

Shrinu . M . M .

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Day 7	Day 8	Day 9	Day 10	Day 11	Day 12	Day 13	Day 14	Day 15
18/2/22	25/2/22	4/3/22	11/3/22	18/3/22	25/3/22	1/4/22	8/4/22	15/4/22

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/	/	/	/	/	/	/	AB	/
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/	/	/	/	/	/	/	/	AB
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/	/	/	/	/	AB	/	/	/
/	/	/	/	/	/	AB	/	/

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Timestamp	Name of the faculty	Department of the Faculty	Course code	Course Name	Date	Starting Time	Topic	Number of students registered	Number of students Attended	Sample work done by students	Duration
11-8-2022 14:02:35	DIVYA THOMAS	ASH	MAT201	PARTIAL DIFFERENT	16-09-2022	1:02:00 PM	SOLUTION OF PDE	14	12	https://drive.google.com/open?id=17Rmp1B_JVYspV1NyPJFxp5jFNpniFBJ3	1:00:00
11-8-2022 14:04:05	DIVYA THOMAS	ASH	MAT201	PDE	30-09-2022	1:02:00 PM	CHARPITS	14	14	https://drive.google.com/open?id=13WhjHtBE0fvc1VBiADZRC7wuY0zjOhPO	1:00:00
11-8-2022 14:06:41	DIVYA THOMAS	ASH	MAT201	PDE	21-10-2022	1:00:00 PM	WAVE EQUATION	14	4	https://drive.google.com/open?id=17GacwVYw8dMvgnLuwGtbGU1z2mxico7x	1:00:00
11-8-2022 14:08:01	DIVYA THOMAS	ASH	MAT201	PDE	28-10-2022	1:00:00 PM	WAVE EQUATION	14	14	https://drive.google.com/open?id=1iISXWArnzTc61A0DaOEVs6vhbe1d0iB	1:00:00
11-8-2022 14:17:01	DIVYA THOMAS	ASH	MAT201	PDE	04-11-2022	1:00:00 AM	HEAT EQUATION	14	14	https://drive.google.com/open?id=1zVUVaYvTnPqJSHjXs2Q2FCydvC0IjnJe	1:00:00
11-9-2022 11:23:12	SHINU MM	AEI	ECT205	NETWORK THEORY	22-09-2022	9:00:00 AM	MESH ANALYSIS	14	13	https://drive.google.com/open?id=1m-M6FMGmAALJz4SQa7B3SNnaZGpTRkIE	1:00:00
11-9-2022 11:27:50	SHINU MM	AEI	ECT205	NETWORK THEORY	13-10-2022	9:00:00 AM	MESH ANALYSIS	14	13	https://drive.google.com/open?id=1ViuHf64nOtRp13U6q84OYw-lyq1eUFb-	1:00:00
11-9-2022 14:33:36	SHINU MM	AEI	ECT205	NETWORK THEORY	20-10-2022	9:00:00 AM	THEVENIN THEOREM	14	14	https://drive.google.com/open?id=1k4xs4YjKy-4H78z1nEjZoi7vg2D8gVr	1:00:00
11-9-2022 14:36:14	Reshma K V	EI	ECT203	LOGIC CIRCUIT DESI	16-09-2022	11:10:00 AM	Binary to Octal and oc	14	13	https://drive.google.com/open?id=1AtMcfSXTxC2h8X3iYUalGsadM0CGJIMl	1:00:00
11-9-2022 14:37:35	SHINU MM	AEI	ECT 205	NETWORK THEORY	27-10-2022	9:00:00 AM	LT	14	14	https://drive.google.com/open?id=1H7X71LZZ3QIGh6Ss2ZN1SuyfSUJ52BAi	1:00:00
11-9-2022 14:39:54	Reshma K V	EI	ECT203	LOGIC CIRCUIT DES	30-09-2022	11:10:00 AM	Addition using 2's Com	14	14	https://drive.google.com/open?id=1e7zvzGx8WK9G7HL2OO9RCNCZLHTkgJ	1:00:00
11-9-2022 14:41:53	Reshma K V	EI	ECT203	LOGIC CIRCUIT DESI	21-10-2022	11:10:00 AM	Non-canonical SOP for	14	14	https://drive.google.com/open?id=1BIHRgqd9_e_WECAY7ABvfvqYNFeMmVR	1:00:00
11-9-2022 14:44:13	RESHMA KK V	EI	ECT 203	LOGIC CIRCUIT DES	28-10-2022	11:10:00 AM	K-Map	14	14	https://drive.google.com/open?id=1TQU_1UZwJlw3T	1:00:00
11-9-2022 22:47:32	SHAMYA A	AEI	ECT 201	SOLID STATE DEVICI	13-09-2022	10:00:00 AM	concept of effective ma:	14	12	https://drive.google.com/open?id=1TfWkr0SY9fVapSVVH0	1:00:00

11-9-2022 22:49:26	SHAMYA A	AEI	ECT201	SOLID STATE DEVIC	28-09-2022	10:00:00 AM	EINSTEIN RELATION	14	13	https://drive.google.com/open?id=12TYOonb-1QaFTY1vWkwEzw9JYn0ZAv4i	1:00:00
11-20-2022 19:49:28	Reshma K V	EI	ECT 203	LOGIC CIRCUIT DESI	11-11-2022	11:10:00 AM	Multiplexer	14	13	https://drive.google.com/open?id=1EZ2ODMANrdwh9cvyH7z0VGPZWNJAomdZ	1:00:00
11-20-2022 19:51:23	Reshma K V	EI	ECT 203	LOGIC CIRCUIT DESI	18-11-2022	11:10:00 AM	Decoders	14	12	https://drive.google.com/open?id=1ydjmJSzyELNOxHXk7SmtWCEHEVjDBqV_	1:00:00
1-12-2023 14:47:10	DIVYA THOMAS	ASH	MAT201	PDE AND COMPLEX /	16-09-2022	1:00:00 PM	SOLUTION OF PDE	14	14	https://drive.google.com/open?id=1RngqvVY6FvcBAfTS4B5Cyyv6RnkGaZSEp	1:00:00
1-12-2023 14:50:45	DIVYA THOMAS	ASH	MAT201	PDE AND COMPLEX /	30-09-2022	12:00:00 PM	CHARPITS METHOD	14	14	https://drive.google.com/open?id=19nik5vTAbs9zhZMX4IdwtKkgXVV6EVLx	1:00:00
1-12-2023 14:53:53	DIVYA THOMAS	ASH	MAT 201	PDE AND COMPLEX /	21-10-2022	1:00:00 PM	WAVE EQUATION	14	5	https://drive.google.com/open?id=1IFYMMrdai_TNZde-e9G147rrScwxs1wC	1:00:00
1-12-2023 14:56:14	DIVYA THOMAS	ASH	MAT201	PDE AND COMPLEX /	28-10-2022	1:00:00 PM	WAVE EQUATION	14	13	https://drive.google.com/open?id=1GRk_0sByVL_tlxFU6CISfNhpBTo4IqHG	1:00:00
1-12-2023 15:00:16	DIVYA THOMAS	ASH	MAT201	PDE AND COMPLEX /	04-11-2022	1:00:00 PM	HEAT EQUATION	14	14	https://drive.google.com/open?id=1SAX6Nqhv3598gyZorR2528KDTIcGnhHgZ	1:00:00
1-12-2023 15:03:01	DIVYA THOMAS	ASH	MAT201	PDE AND COMPLEX /	18-11-2022	1:00:00 PM	ANALYTIC FUNCTION	14	12	https://drive.google.com/open?id=1Vvm7w15gGltPdI_MHVxpNbvzB8HO_MpAG	1:00:00
1-12-2023 15:05:17	DIVYA THOMAS	ASH	MAT201	PDE AND COMPLEX /	25-11-2022	1:00:00 PM	TAYLOR SERIES	14	10	https://drive.google.com/open?id=1GVB3_x_99lq9dVu5n5YK32nEmpSjTQcn	1:00:00
1-12-2023 15:07:49	DIVYA THOMAS	ASH	MAT201	PDE& COMPLEX ANL	21-02-2022	1:00:00 PM	COMPLEX INTEGRAT	14	13	https://drive.google.com/open?id=1PHbm3XXo2Lk65nyxPdV3sEHoxbDFtjS	1:00:00
1-12-2023 15:09:58	DIVYA THOMAS	ASH	MAT201	PDE&COMPLEX ANAI	16-12-2022	1:00:00 PM	COMPLEX INTEGRAT	14	9	https://drive.google.com/open?id=1A8lic7Dc5bxqah5RjCGygn9Fsu90zt	1:00:00
1-21-2023 0:11:47	shamya A	EIE	ECT 201	SOILD STATE DEVUC	11-10-2022	11:10:00 AM	CONTACT POTENTIA	14	14	https://drive.google.com/open?id=1HPABsz533-Oz3w623SSSgO-KiErgT3-j	1:00:00
1-21-2023 0:15:25	SHAMYA A	EIE	ECT201	SOLID STATE DEVIC	05-01-2023	9:00:00 AM	IMP QUESTIONS ANS	14	7	https://drive.google.com/open?id=1nrzg1CxcXPWCgRjll0BAb-tE1FRz8B3N	2:00:00
1-23-2023 15:16:13	RESHMA K V	EI	ECT 203	LOGIC CIRCUIT DESI	25-11-2022	11:10:00 AM	PIPO	14	13	https://drive.google.com/open?id=1nrzg1CxcXPWCgRjll0BAb-tE1FRz8B3N	1:00:00

1-23-2023 15:18:30	RESHMA K V	EI	ECT 203 LO	LOGIC CIRCUIT DESI	16-12-2022	11:10:00 AM	NAND in TTL and CMC	14	14	https://drive.google.com/open?id=1HYhE2o-WDbTOmW7JM2EfJL7dXnHCT9Yh	1:00:00
1-23-2023 15:20:50	RESHMA K V	EI	ECT 203	LOGIC CIRCUIT DESI	02-12-2022	11:10:00 AM	TTL	14	14	https://drive.google.com/open?id=1vkmTM5f40rgC3ps07Q0prqnkmyJ0HZtE	1:00:00

25/11/22

Types of Registers in digital electronics

- shift registers are categorized into types majorly by their mode of operation, either serial or parallel.

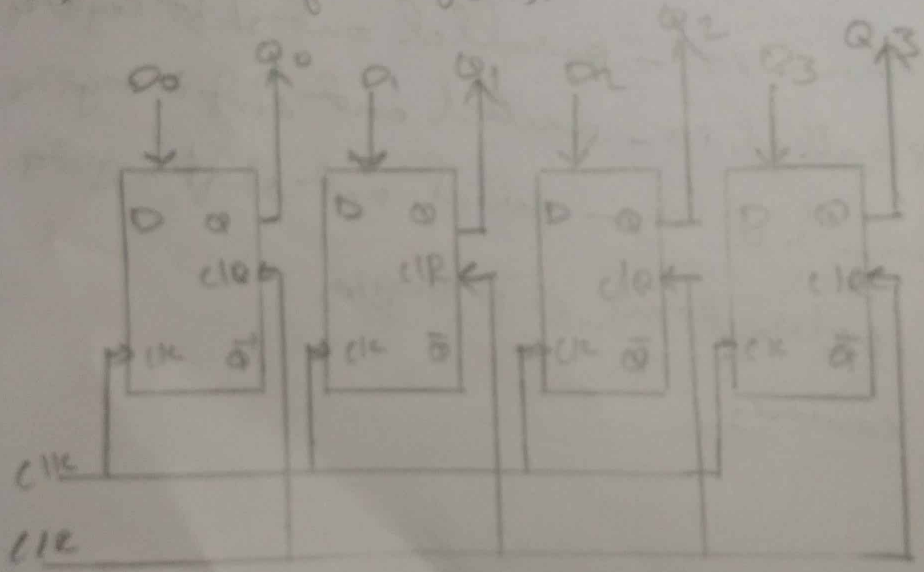
Types:-

- ① serial in - serial out shift registers
- ② serial in - parallel out shift registers
- ③ parallel in - parallel out shift registers
- ④ parallel in - serial out shift registers
- ⑤ bidirectional shift registers
- ⑥ counters

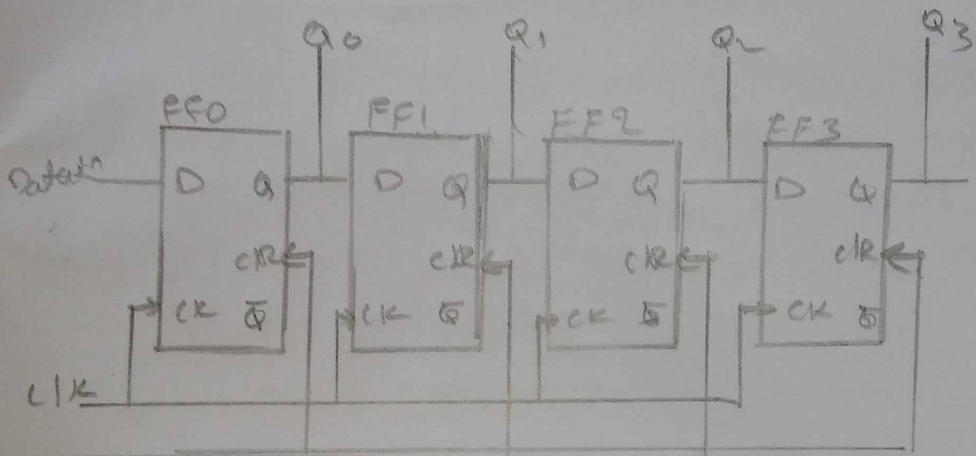
25/11/22

Parallel in - parallel out shift registers

For parallel in - parallel out shift registers, the output data across the parallel output appear simultaneously as the input data is fed. This type of shift registers is also called as P I P O shift registers.



4 bit serial in - parallel out shift registers



CLR Table shows how data is shifted out of serial in - parallel out serial

clear	FF0	FF1	FF2	FF3
1001	0	0	0	0
	1	0	0	0
	0	1	0	0
	0	0	1	0
	1	0	0	1

Timestamp	Name of the faculty	Department of the Faculty	Course code	Course Name	Date	Starting Time	Duration	Topic	Number of students registered	Number of students Attended	Sample work done by students
6-17-2023 11:36:41	Vineethamol Abraham	ASH	MAT204	Probability,Random prc	13-02-2023	11:10:00 AM	12:00:00	Binomial distribution	14	10	https://drive.google.com/open?id=18x463EpMnuJgBxarpXYMw16O9QhEkFFJ
6-17-2023 11:40:02	Vineethamol Abraham	ASH	MAT 204	Probability,Random prc	27-02-2023	11:10:00 AM	12:10:00	Poisson distribution	14	5	https://drive.google.com/open?id=1VQ3RiwcY6MgDn7_90VKxlgmMEltrEwOL
6-17-2023 11:42:39	Vineethamol Abraham	ASH	MAT 204	Probability,Random prc	20-03-2023	11:10:00 AM	12:00:00	Joint PDF	14	13	https://drive.google.com/open?id=129qml6-hodnJ811Fu_yg1mSaZnmtwTrt
6-17-2023 11:44:25	Vineethamol Abraham	ASH	MAT 204	Probability,Random prc	27-03-2023	11:10:00 AM	12:10:00	Central limit theorem	14	12	https://drive.google.com/open?id=18HdMRHRBWzgzYpZlc8j2ii7chV2v_KcBHf
6-17-2023 11:46:26	Vineethamol Abraham	ASH	MAT 204	Probability,Random prc	03-04-2023	11:10:00 AM	12:00:00	WSS Process	14	14	https://drive.google.com/open?id=1qY5cfT8F0UJmDLNOBkKfChvikNFI49
6-17-2023 11:48:23	Vineethamol Abraham	ASH	MAT 204	Probability,Random prc	10-04-2023	11:10:00 AM	12:10:00	Autocorrelation	14	7	https://drive.google.com/open?id=1Xkj-mW62lp5AcktJDAx3zsgDB7FiR
6-17-2023 11:52:08	Vineethamol Araham	ASH	MAT 204	Probability,Random prc	05-06-2023	11:10:00 AM	12:00:00	Newton's Forward diffe	14	13	https://drive.google.com/open?id=1e1rqLqMQkECIJc8xi9but49ct7gYM_ICMhSffI
6-19-2023 14:43:38	Jinsa Mathew	EIE	ECT204	Signals and systems	09-02-2023	9:00:00 AM	1:00:00	Signal operations	14	11	https://drive.google.com/open?id=1QGXPyd_WpGkFgg5hIG0E0b9IAPjA
6-19-2023 14:46:05	Jinsa Mathew	EIE	ECT204	Signals and Systems	16-02-2023	9:00:00 AM	1:00:00	Energy & power eignsl	14	11	https://drive.google.com/open?id=1DPk1x66ggSwsQx536Spisz9hL135wv5a8x
6-19-2023 14:48:32	Jinsa Mathew	EIE	ECT204	Signals and Systems	02-03-2023	1:00:00 AM	1:00:00	Response of system, c	14	5	https://drive.google.com/open?id=1DPk1x66ggSwsQx536Spisz9hL086j_yO

6-19-2023 14:50:38	Jinsa Mathew	EIE	ECT204	Signals and Systems	30-03-2023	9:00:00 AM	1:00:00	Fourier transform	14	11	https://drive.google.com/open?id=15SGcbuc kbeus2_h1tWwVv-qXUcTsPPR09
6-19-2023 14:53:13	Jinsa Mathew		ECT204	Signals and Systems	13-04-2023	9:00:00 AM	1:00:00	Laplace transform	14	12	https://drive.google.com/open?id=1XPfZkla WJdBkHSgmXNOIM m3zlZfNZiOP
6-19-2023 14:55:19	Jinsa Mathew	EIE	ECT204	Signals and Systems	27-04-2023	9:00:00 AM	1:00:00	LTI system analysis	14	10	https://drive.google.com/open?id=19zIWd8lx IZU8xPL0DD6kXN4H0 MJzIbBX
6-19-2023 14:57:42	Jinsa Mathew	EIE	ECT204	Signals and Systems	01-06-2023	9:00:00 AM	1:00:00	DTFT- frequency respo	14	9	https://drive.google.com/open?id=1DIR3t43 BNrIrDTeDtllfcPVNI- HEOAv4
6-19-2023 15:00:13	Jinsa Mathew	EIE	ECT204	Signals and Systems	08-06-2023	9:00:00 AM	1:00:00	DTFT reponse of syste	14	14	https://drive.google.com/open?id=1DpXJMS- KH1tj5EeLHVFMym4 AE3ER9wg
6-19-2023 15:01:38	Jinsa Mathew	EIE	ECT204	Signals and Systems	15-06-2023	9:00:00 AM	1:00:00	Inverse z transform	14	14	https://drive.google.com/open?id=1QDQWb LcDOKL7JEoOgl39Ka Z5qERv-Q1N
6-19-2023 21:28:13	Reshma k V	EI	AET206	Measurements and Ins	06-02-2023	9:00:00 AM	1:00:00	principles of measurem	14	10	https://drive.google.com/open?id=1RJFmeH pBubmhUG8yFL4H1yr PldOzbDOJ
6-19-2023 21:30:46	Reshma K V	EI	AET206	Measurements and Ins	13-02-2023	9:00:00 AM	1:00:00	errors in measurement:	14	6	https://drive.google.com/open?id=1oDflgQl8 51KYCWn7z17vklUSx ZrgybSs
6-19-2023 21:44:08	Reshma K V	EI	AET206	Measurements and Ins	27-03-2023	9:00:00 AM	1:00:00	Accelerometers, piezo	14	12	https://drive.google.com/open?id=1TRMzWF lrWd1ByT8yQ1THyHi ws0E1OrX7
6-19-2023 21:45:50	Reshma K V	EI	AET206	Measurements and Ins	05-06-2023	9:00:00 AM	1:00:00	CRO	14	13	https://drive.google.com/open?id=1blTtyfTE RplRvuf3wrOv1vWpJy m_3GqM
6-19-2023 21:47:07	Reshma K V	EI	AET206	Measurements and Ins	12-06-2023	9:00:00 AM	1:00:00	X-Y Plotter	14	8	https://drive.google.com/open?id=1JUdoftwi 7Du0lrE9QEinypl1wH uErQ9e

6-22-2023 18:34:45 SHINU MM	AEI	ECT202	ANALOG CIRCUIT	03-04-2023	10:00:00 AM	1:00:00	MODULE 4	14	13	https://drive.google.com/open?id=1x0rpByUDjnZ6_GyHfnI9zdAAwHu87ZfW
6-22-2023 18:36:27 SHINU MM	AEI	ECT202	ANALOG CIRCUIT	10-04-2023	2:00:00 PM	1:00:00	MODULE 4	14	7	https://drive.google.com/open?id=11YrOOItSiZGqbU14jVCB9JyprEFTCDWn
6-22-2023 18:39:49 SHINU MM	AEI	ECT202	ANALOG CIRCUIT	05-06-2023	2:00:00 AM	1:00:00	MODULE 3	14	12	https://drive.google.com/open?id=1LXKqDvoDVfcL67OvAi19I1MOVqSTbbZ7

Q) The I/P, O/P of a causal LTI s/m is described by
 the diff eqn $\frac{d^2 y(t)}{dt^2} + 3 \frac{dy(t)}{dt} + 2y(t) = x(t)$
 i) Find the frequency response $H(\omega)$
 ii) Find the impulse response $F^{-1}(H(\omega))$
 iii) Find the response of the s/m when i/p = $e^{-t}u(t)$

\Rightarrow given that $\frac{d^2 y(t)}{dt^2} + 3 \frac{dy(t)}{dt} + 2y(t) = x(t)$

i) taking F.T

$$(j\omega)^2 Y(\omega) + 3(j\omega) Y(\omega) + 2Y(\omega) = X(\omega)$$

$$Y(\omega) [(j\omega)^2 + 3(j\omega) + 2] = X(\omega)$$

$$\therefore H(\omega) = \frac{Y(\omega)}{X(\omega)} = \frac{1}{(j\omega)^2 + 3(j\omega) + 2}$$

ii) ~~the~~ impulse response = $F^{-1}(H(\omega))$

$$= \frac{1}{(j\omega+1)(j\omega+2)} = \frac{A}{j\omega+1} + \frac{B}{j\omega+2}$$

$$A = \frac{1}{j\omega+2} \Big|_{j\omega=-1} = -1$$

$$B = \frac{1}{j\omega+1} \Big|_{j\omega=-2} = -1$$

$$\therefore H(\omega) = \frac{1}{j\omega+1} - \frac{1}{j\omega+2} = 0$$

$$h(t) = F^{-1} \left[\frac{1}{j\omega+1} - \frac{1}{j\omega+2} \right] = e^{-t} u(t) - e^{-2t} u(t)$$

3) $x(t) = te^{-t}u(t)$

$$X(\omega) = \frac{1}{(j\omega+1)^2}$$

$$\therefore Y(\omega) = H(\omega) \cdot X(\omega) = \frac{1}{(j\omega+1)(j\omega+2)} \cdot \frac{1}{(j\omega+1)^2}$$

$$= \frac{A}{(j\omega+1)} + \frac{B}{(j\omega+2)} + \frac{C}{(j\omega+1)^2} + \frac{D}{(j\omega+1)} = \frac{1}{(j\omega+1)^3(j\omega+2)}$$

$$C = \frac{1}{(j\omega+1)(j\omega+2)} \Big|_{j\omega=-1} = \dots = \frac{A}{(j\omega+1)^3} + \frac{B}{(j\omega+1)^2} + \frac{C}{j\omega+1} + \frac{D}{j\omega+2}$$

$$A = \frac{1}{j\omega+2} \Big|_{j\omega=-1} = \frac{1}{-1+2} = 1$$

$$B = \frac{d}{d\omega} \left[\frac{1}{j\omega+2} \right] \Big|_{j\omega=-1} = \frac{-1}{(j\omega+2)^2} \Big|_{j\omega=-1} = -1$$

$$C = \frac{d^2}{d\omega^2} \left[\frac{1}{j\omega+2} \right] = \frac{d}{d\omega} \left[\frac{-1}{(j\omega+2)^2} \right] = - \left[\frac{-2(j\omega+2)^{-3}} \right] = \frac{+2(j\omega+2)^{-3}} \Big|_{j\omega=-1}$$

$$= \frac{2 \times -1 + 4}{(-1+2)^3} = \frac{2}{1} = 2$$

$$\therefore Y(\omega) = \frac{1}{(j\omega+1)^3} + \frac{-1}{(j\omega+1)^2} + \frac{2}{j\omega+1} + \frac{1}{j\omega+2}$$

$$y(t) = F^{-1}[Y(\omega)]$$

$$= \frac{1}{2} e^{-t} u(t) - t e^{-t} u(t) + 2e^{-t} u(t) + e^{-2t} u(t)$$

Q) Consider a causal LTI s/m with impulse response $h(t) = e^{-4t} u(t)$ find the o/p of the s/m for an i/p $x(t) = 3e^{-t} u(t)$

\Rightarrow given that $h(t) = e^{-4t} u(t)$
 $H(\omega) = FT[h(t)] = FT[e^{-4t} u(t)]$
 $= \frac{1}{j\omega + 4}$

$x(t) = 3e^{-t} u(t)$
 $\therefore X(\omega) = FT[3e^{-t} u(t)] = \frac{3}{j\omega + 1}$

$Y(\omega) = X(\omega) \cdot H(\omega)$
 $= \frac{3}{j\omega + 1} \cdot \frac{1}{j\omega + 4}$
 $= \frac{A}{j\omega + 1} + \frac{B}{j\omega + 4}$

$A = \frac{3}{j\omega + 4} \Big|_{j\omega = -1} = 1$ $B = \frac{3}{j\omega + 1} \Big|_{j\omega = -4} = -1$

$Y(\omega) = \frac{1}{j\omega + 1} - \frac{1}{j\omega + 4}$

$Y(t) = F^{-1}[Y(\omega)] = F^{-1}\left[\frac{1}{j\omega + 1} - \frac{1}{j\omega + 4}\right]$
 $= e^{-t} u(t) - e^{-4t} u(t)$

Q) using F.T find the diff eqn description for the s/m having impulse response $h(t) = [3e^{-3t} - 2e^{-2t}] u(t)$

\Rightarrow given $h(t) = [3e^{-3t} - 2e^{-2t}] u(t)$ on taking F.T on both side of eqn

$H(\omega) = \frac{3}{j\omega + 3} - \frac{2}{j\omega + 2} = \frac{3(j\omega + 2) - 2(j\omega + 3)}{(j\omega + 3)(j\omega + 2)}$
 $= \frac{3j\omega + 6 - 2j\omega - 6}{(j\omega)^2 + 5j\omega + 6} = \frac{j\omega}{(j\omega)^2 + 5j\omega + 6}$

$\frac{Y(\omega)}{X(\omega)} = \frac{j\omega}{(j\omega)^2 + 5j\omega + 6}$

$[j\omega^2 + 5j\omega + 6] X(\omega) = j\omega Y(\omega)$
 $(j\omega)^2 Y(\omega) + 5j\omega Y(\omega) + 6Y(\omega) = j\omega X(\omega)$
 Taking inverse F.T

$\frac{d^2 y(t)}{dt^2} + 5 \frac{dy(t)}{dt} + 6y(t) = \frac{d}{dt} x(t)$

Q) Consider a LTI s/m with frequency response $H(\omega) = \frac{1}{j\omega + 3}$ for a particular i/p $x(t)$ the s/m is observed to produce the o/p $y(t) = e^{-t} u(t) - e^{-2t} u(t)$ determine $x(t)$

\Rightarrow given $H(\omega) = \frac{1}{j\omega + 3}$

$y(t) = e^{-t} u(t) - e^{-2t} u(t)$

$Y(\omega) = \frac{1}{j\omega + 1} - \frac{1}{j\omega + 2} = \frac{j\omega + 2 - (j\omega + 1)}{(j\omega + 1)(j\omega + 2)} = \frac{1}{(j\omega + 1)(j\omega + 2)}$

we know $Y(\omega) = H(\omega) \cdot X(\omega)$

$X(\omega) = \frac{Y(\omega)}{H(\omega)} = \frac{1}{j\omega + 1} - \frac{1}{j\omega + 2} = \frac{A}{j\omega + 1} - \frac{B}{j\omega + 2}$ Here $H(\omega) = \frac{1}{j\omega + 3}$
 $X(\omega) = \frac{Y(\omega)}{H(\omega)}$

$A = \frac{1}{j\omega + 2} \Big|_{j\omega = -1} = 1$ $B = \frac{1}{j\omega + 1} \Big|_{j\omega = -2} = -1$

$$= \frac{\frac{1}{j\omega+1} - \frac{1}{j\omega+2}}{\frac{1}{j\omega+3}} = \frac{(j\omega+2) - (j\omega+1)}{(j\omega+1)(j\omega+2)} = \frac{(j\omega+2) - (j\omega+1)}{(j\omega+1)(j\omega+2)} \cdot \frac{j\omega+3}{j\omega+3}$$

$$= \frac{(j\omega+2)(j\omega+3) - (j\omega+1)(j\omega+3)}{(j\omega+1)(j\omega+2)}$$

$$= \frac{j\omega^2 + 3j\omega + 6 - j\omega^2 - 3j\omega - 3}{(j\omega+1)(j\omega+2)} = \frac{j\omega+3}{(j\omega+1)(j\omega+2)}$$

$$= \frac{A}{j\omega+1} + \frac{B}{j\omega+2}$$

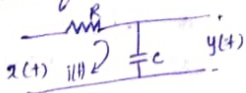
$$A = \frac{j\omega+3}{j\omega+2} \Big|_{j\omega=-1} = 2 \quad ; \quad B = \frac{j\omega+3}{j\omega+1} \Big|_{j\omega=-2} = -1$$

$$x(\omega) = \frac{2}{j\omega+1} - \frac{1}{j\omega+2}$$

$$x(t) = F^{-1}[x(\omega)] = F^{-1}\left[\frac{2}{j\omega+1} - \frac{1}{j\omega+2}\right]$$

$$= 2e^{-t}u(t) - e^{-2t}u(t)$$

a) Find the frequency response of RC network showing by plot the magnitude & phase response of RC=1, also find the impulse response of the circuit.



$$\Rightarrow x(t) - Ri(t) - \int i(t) dt = 0$$

$$x(t) = Ri(t) + \int i(t) dt \quad (1)$$

$$I(\omega) = \frac{1}{j\omega}$$

$$y(t) = \int i(t) dt \quad (2)$$

$$F\{1\} \Rightarrow X(\omega) = RI(\omega) + \int \frac{I(\omega)}{j\omega} \quad (3)$$

$$F\{2\} \Rightarrow Y(\omega) = \int \frac{I(\omega)}{j\omega} \quad (4)$$

$$(3) \Rightarrow X(\omega) = \left[R + \frac{1}{j\omega C}\right] I(\omega)$$

$$Y(\omega) = \frac{1}{j\omega C} I(\omega)$$

$$H(\omega) = \frac{Y(\omega)}{X(\omega)} = \frac{\frac{1}{j\omega C} I(\omega)}{\left[R + \frac{1}{j\omega C}\right] I(\omega)} = \frac{\frac{1/j\omega C}{j\omega RC + 1}}{j\omega RC} = \frac{1}{j\omega RC + 1}$$

$$h(t) = F^{-1}[H(\omega)] = F^{-1}\left[\frac{1}{1 + j\omega RC}\right] = F^{-1}\left[\frac{1}{RC(j\omega + 1/RC)}\right]$$

$$= F^{-1}\left[\frac{1/RC}{j\omega + 1/RC}\right] = \frac{1}{RC} e^{-(1/RC)t} u(t)$$

When RC=1

$$h(t) = e^{-t}u(t)$$

$$H(\omega) = \frac{1}{1 + j\omega RC}$$

$$RC=1, H(\omega) = \frac{1}{1 + j\omega}$$

$$|H(\omega)| = |H(\omega)| \angle H(\omega)$$

$$|H(\omega)| = \frac{1}{\sqrt{1^2 + \omega^2}} = \frac{1}{\sqrt{1 + \omega^2}}$$

$$\angle H(\omega) = 0 - \tan^{-1}(\omega)$$



AY 2022-23 S7 AEI

Vimal Jyothi Engineering College, Chemperi, Kannur Dist., Kerala

	1	2	3	4	5	6
Mo	AET401 COMMUNICATION ENGINEERING Ms.Shamya A	AET423 SCADA AND DISTRIBUTED CONTROL TUT Mr.Dhanoj Mohan	AET423 SCADA AND DISTRIBUTED CONTROL Mr.Dhanoj Mohan	OPEN ELECTIVE Mr.Binil Kumar K / Mr. Shaminmuth K K / Mr. Joy James / Mr. Appu Kurian / Dr.P Sridharan / Dr.S Christopher Ezhil Singh / Mr. Mejo M Francis / Ms. MANJU M. Ms.Sudharsana Vijayan	OPEN ELECTIVE Mr.Binil Kumar K / Mr. Shaminmuth K K / Mr. Joy James / Mr. Appu Kurian / Dr.P Sridharan / Dr.S Christopher Ezhil Singh / Mr. Mejo M Francis / Ms. MANJU M. Ms.Sudharsana Vijayan	MCN401 INDUSTRIAL SAFETY ENGINEERING Ms.Jinsa Mathew
Tu	AEQ413 SEMINAR Ms.Reshma K V / b / Dr.G.Glan Devadhas			OPEN ELECTIVE Mr.Binil Kumar K / Mr. Shaminmuth K K / Mr. Joy James / Mr. Appu Kurian / Dr.P Sridharan / Dr.S Christopher Ezhil Singh / Mr. Mejo M Francis / Ms. MANJU M. Ms.Sudharsana Vijayan	OPEN ELECTIVE Mr.Binil Kumar K / Mr. Shaminmuth K K / Mr. Joy James / Mr. Appu Kurian / Dr.P Sridharan / Dr.S Christopher Ezhil Singh / Mr. Mejo M Francis / Ms. MANJU M. Ms.Sudharsana Vijayan	AET401 COMMUNICATION ENGINEERING TUT Ms.Shamya A
We	AED415 PROJECT PHASE I Mr.Dhanoj Mohan / Ms.Jinsa Mathew			AED415 PROJECT PHASE I Mr.Dhanoj Mohan / Ms.Jinsa Mathew		
Th	MCN401 INDUSTRIAL SAFETY ENGINEERING Ms.Jinsa Mathew	AET423 SCADA AND DISTRIBUTED CONTROL Mr.Dhanoj Mohan	AET401 COMMUNICATION ENGINEERING Ms.Shamya A	MCN401 INDUSTRIAL SAFETY ENGINEERING Ms.Jinsa Mathew	AET423 SCADA AND DISTRIBUTED CONTROL Mr.Dhanoj Mohan	AET401 COMMUNICATION ENGINEERING Ms.Shamya A
Fr	AET401 COMMUNICATION ENGINEERING Ms.Shamya A	MCN401 INDUSTRIAL SAFETY ENGINEERING TUT Ms.Jinsa Mathew	AET423 SCADA AND DISTRIBUTED CONTROL Mr.Dhanoj Mohan	AEL411 PROCESS CONTROL LAB Ms.Reshma K V / Ms.Jinsa Mathew / a / Mr.Jolly Kuty		
Sa	Special Timetable			Special Timetable		

Timetable prepared by Dr Javesh George M, Associate Professor, ECE

Timestamp	Email Address	Course Name	Course Code	Name of faculty	Date of Class conducted	Time	Topic covered:	Details of tutorial work	No. of students present:	Absentees details:	Details of tutorial sample:
	jinsamathew@vjec.ac.in	Industrial Safety Engineering	MCN401	Jinsa Mathew	9/30/2022	10:00:00 AM	Safety Officer-responsibilities, authority	Discussed about Safety Officer-responsibilities, authority	18	Sreehari, Joyel Joseph	https://drive.google.com/file/d/1BpanZyur9I7-33hu0mhrxXE-oXFxSaHF/view?usp=share_link
	jinsamathew@vjec.ac.in	Industrial Safety Engineering	MCN401	Jinsa Mathew	10/28/2022	10:00:00 AM	Housekeeping, Responsibility of management and employees,	Discussed Housekeeping, Responsibility of management and employees, M	20	Nil	https://drive.google.com/file/d/1BpanZyur9I7-F1dRQW687GMMvIVlydn4131ahttps://drive.google.com/file/d/1BpanZyur9I7-
	shamyasanthosh@vjec.ac.in	COMMUNICATION ENGINEERING	AET401	SHAMYA A	9/29/2022	3:10:00 PM	AM MODULATION ANALYSIS AND ITS NUMERICALS	MODULATION ANALYSIS AND ITS NUMERICALS	16		https://drive.google.com/open?id=1aBYAwZ7mbX4yF06qs2GdQT4yDkCjSMVzj
	shamyasanthosh@vjec.ac.in	COMMUNICATION ENGINEERING	AET 401	SHAMYA A	10/13/2022	3:10:00 PM	FREQUENCY MODULATION	PROBLEM EXPLANATION	19		https://drive.google.com/open?id=1_wuqn-wDFOzdlxJbJjEym9R1v83D9IGMR
	shamyasanthosh@vjec.ac.in	communication engineering	aet41	shamya A	12/8/2022	3:10:00 PM	PSD of BPSK	Revised the topic	18		https://drive.google.com/open?id=1y8ZW8BTcORy2OhxgTW457T2BZQfoJEbdU
	shamyasanthosh@vjec.ac.in	communication engineering	AET401	shamya A	12/15/2022	9:00:00 AM	PSD and bandwidth of QPSK	revision	16		https://drive.google.com/open?id=1NOs4YW1XVKpNs2KiU6F2k4ybC6kBpQKV9

SS AET

Venat Jyothi Engineering College, Champen, Kannur Dist., Kerala

	1 9:00 - 10:00	2 10:00 - 11:00	3 11:10 - 12:10	4 1:00 - 2:00	5 2:00 - 3:00	6 3:10 - 4:10
Mo	AED 416 Project - Phase III			AED 416 Project - Phase III		
	Dr Gnan Devadhas / Mr Dhanoj Mohan / R / Mr Jollykutty Sebastian					
Tu	AET402 VLSI CIRCUIT DESIGN Ms Shamyra	AET476 Program Elective - IV (T) Mr Shinu	AET402 VLSI CIRCUIT DESIGN Ms Shamyra	AET476 Program Elective - IV Mr Shinu	AET468 Program Elective - V Ms Reshma K V	AET424 SOFT COMPUTING Ms Jinsa Mathew
We	AET468 Program Elective - V Ms Reshma K V	AET424 SOFT COMPUTING Ms Jinsa Mathew	AET468 Program Elective - V Ms Reshma K V	AET424 SOFT COMPUTING Ms Jinsa Mathew	AET476 Program Elective - IV Mr Shinu	AET402 VLSI CIRCUIT DESIGN Ms Shamyra
Th	AET402 VLSI CIRCUIT DESIGN Ms Shamyra	AET468 Program Elective - V Ms Reshma K V	AET476 Program Elective - IV Mr Shinu	AET424 SOFT COMPUTING Ms Jinsa Mathew	AET404 Comprehensive Course Viva Ms Reshma K V	
Fr	AED 416 Project - Phase III			AED 416 Project - Phase III		
	Dr Gnan Devadhas / Mr Dhanoj Mohan / R / Mr Jollykutty Sebastian					
Sa	Special Time table			Special Time table		

VIMAL JYOTHI ENGINEERING COLLEGE
DEPARTMENT OF EIE
S8 AEI- TUTORIAL CLASS DETAILS

Course Name:	Course Code:	Name of faculty:	Date of Class conducted:	Time:	Topic covered:	Details of tutorial work:	No. of students present:	Absentees details:	Details of tutorial sample:
Soft computing	AET424	Jinsa Mathew	2/8/2023	13:00	Neural network	Problem - with activation	19	VML19AE0	https://drive.google.com/u/0/open?usp=forms_web&id=14ZT8PSFjhh4HESc-14-Xai96RZTbpj9g
Soft Computing	AET424	Jinsa Mathew	3/15/2023	13:00	Fuzzy operation	Examples of fuzzy opera	18	VML19AE0	https://drive.google.com/u/0/open?usp=forms_web&id=1tHrfiQQ13HBQYI8MiLDvKpCB4V3pQFAK
Soft computing	AET424	Jinsa Mathew	3/22/2023	1:00	Fuzzy relation	Examples of fuzzy relatio	19	VML19AE0	https://drive.google.com/u/0/open?usp=forms_web&id=1sXWeHONLJ8_A2Ty8IXMBSI-YIXCO84HO
Soft Computing	AET424	Jinsa Mathew	3/8/2023	13:00	Bayes theorem	Calculation of probabilit	19	VML19AE0	https://drive.google.com/u/0/open?usp=forms_web&id=1YxlbYSA1sMJXQGRCS25MaxbhnfG7MQom
ROBOTICS AND INDUS	AET476	SHINU ,MM	4/4/2023	13:00	MODULE 1	discussion module 1	10	1	https://drive.google.com/u/0/open?usp=forms_web&id=1T6V5dYDVP6g1L8KHki4s56sdj8RqiwX
ROBOTICS AND INDUS	AET476	SHINU MM	5/10/2023	13:00	MODULE 2	Discussion module 2	20	0	https://drive.google.com/u/0/open?usp=forms_web&id=1q59Vjar_SpONj7pG8UfCwF4TtM8cuKP1

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Module - 2 tutorial 2

House Keeping

Housekeeping at work is an important as it is at home, Especially if you want a safe work place.

Poor house keeping may result in Employee injuries or even death, citations by the Occupational Safety and Health administration (OSHA). & even difficulty in securing future work.

Housekeeping rules: -

- ⇒ Everyone's responsibility
- ⇒ cleanup after yourself.
- ⇒ pickup trash and debris and dispose of it properly.
- ⇒ Dispose of Combustible and flammables properly.
- ⇒ Organize cables under desks.

Benefits

- ⇒ Reduced handling to ease the flow of materials
- ⇒ fewer tripping & slipping incidents
- ⇒ decreased fire hazards!

- ⇒ more effective use of space.
- ⇒ less janitorial work.

Elements of Effective housekeeping

Program

- ⇒ maintenance
- ⇒ Dust and dirt removal
- ⇒ Employee facilities.
- ⇒ Surfaces
- ⇒ Maintain light fixtures
- ⇒ Aisles and stairways
- ⇒ Spill control
- ⇒ Tool and Equipment.
- ⇒ Waste disposal.
- ⇒ Storage.

5S Concept of Housekeeping

1. Sort
2. Set in order
3. Shine
4. Standardize
5. Sustain.

Sort :-

means eliminating anything that is unnecessary for the Equipment to work properly.

2. Set in order: - Best way of Eliminating Point less Searching & having all the material necessary for functional production. ~~after~~
3. Shining: - means keeping everything so clean that it shines
4. Standardize: - means respecting the previous 3s.
5. Sustain: - after a period of 3 to 6 months the time has come to evaluate the situation

Benefits of 5S

- ⇒ Improved safety and of working Environment
- ⇒ Higher Equipment availability
- ⇒ Lower defect rates.
- ⇒ Reduced Costs
- ⇒ Reduce injury rates.
- ⇒ Increased productivity.
- ⇒ Improved Employee morale
- ⇒ Higher quality -

Advantages: -

- ⇒ Improve safety
- ⇒ Improve the working atmosphere & Environment
- ⇒ Improve the quality of work & products.
- ⇒ Enable efficient maintenance
- ⇒ Enhance your image & Customer trust.

	Day 1 17/8/2022	Day 2 24/8/2022	Day 3 31/8/2022	Day 4 7/9/2022	Day 5 14/9/2022	Day 6 21/9/2022
1 Adil. K	/	/	/	/	/	/
2 Ajay. K.P	/	/	/	/	/	/
3 Akhil M.A	/	/	/	/	/	/
4 Akshas Mohan	/	/	/	/	/	/
5 Akshay. M	/	/	/	/	/	/
6 Alan Sunny	/	/	/	/	/	/
7 Ales Joe Prince	/	/	AB	/	/	/
8 Anargh. K	/	/	/	/	/	/
9 Aswin T.S	/	/	/	/	/	/
10 Aswin Vinod. C	/	/	/	/	/	/
11 Ayana P.V	/	/	/	/	/	/
12 Dipraj. M	/	/	/	/	/	/
13 Hirandeep. T	/	/	/	AB	/	/
14 Joyal Saji	/	/	/	AB	/	/
15 Jude Tomon George	/	/	/	/	/	/
16 Kevin Saji	/	/	/	/	/	/
17 Kisan. K.V	/	/	/	/	/	/
18 Minal. C. Pradeep	/	/	/	/	/	/
19 Muhammed Sahl	/	/	/	/	/	/
20 Revanth. P.V.K	/	/	/	/	AB	/
21 Tom Jessan	/	/	/	/	/	/
22 Vyshnav. K	/	/	/	/	/	/

Reshma K.V.

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M.M. ...

Day 7	Day 8	Day 9	Day 10	Day 11	Day 12	Day 13	Day 14	Day 15
28/9/2022	5/10/2022	12/10/2022	19/10/2022	26/10/2022	2/11/2022	9/11/2022	16/11/2022	23/11/2022

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Pr Pr Pr Pr Pr Pr Pr Pr Pr

40 Computer Architecture & Embedded Sfrms - Shirin . M.M

	Day 1 18/8/22	Day 2 25/8/22	Day 3 1/9/22	Day 4 8/9/22	Day 5 15/9/22	Day 6 22/9/22
1. Adel . k	/	/	/	/	/	/
2. Aray . k . P	/	/	/	/	/	/
3. Akhil . M . A	/	/	/	/	/	/
4. Akshas Mohan	/	/	/	/	/	/
5. Akshay . M	/	/	/	/	/	/
6. Alan Sunny	AB	/	/	/	/	/
7. Ales Jee Prince	/	/	/	/	/	/
8. Anargh . k	/	/	/	/	AB	/
9. Aswin T . S	/	/	/	/	/	/
10. Aswin Vinod . C	/	/	/	/	/	/
11. Ayana . P . V	/	/	/	/	/	/
12. Dipraj . M	/	/	/	/	/	/
13. Hirandeep . T	/	/	/	/	/	/
14. Jeyal Saji	/	/	/	/	/	/
15. Jude Tomon George	/	/	/	/	/	/
16. Kevin Saji	/	AB	/	/	/	/
17. Kusan . K . V	/	/	/	/	/	AB
18. Mrinal . C . Pradeep	/	/	/	/	/	/
19. Muhammed Sahl	/	/	/	/	/	/
20. Revanth P . V . K	/	/	/	/	/	/
21. Tom Jessan	/	/	/	/	/	/
22. Vyshnav . k	/	/	AB	/	/	/
Shirin . M . M	<u>Shi</u>	<u>Shi</u>	<u>Shi</u>	<u>Shi</u>	<u>Shi</u>	<u>Shi</u>

Day 7	Day 8	Day 9	Day 10	Day 11	Day 12	Day 13	Day 14	Day 15
29/9/22	6/10/22	13/10/22	20/10/22	27/10/22	3/11/22	10/11/22	17/11/22	24/11/22
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<u>Sci</u>	<u>Sci</u>	<u>Sci</u>	<u>Sci</u>	<u>Sci</u>	<u>Sci</u>	<u>Sci</u>	<u>Sci</u>	<u>Sci</u>

	Day 1 18/8/22	Day 2 25/8/22	Day 3 1/9/22	Day 4 8/9/22	Day 5 15/9/22	Day 6 22/9/22
1. Adil . K						
2. Ajay . K . P	P	P	P	P	P	P
3. Akhil . M . A	P	P	P	P	P	P
4. Akshas Mohan	P	P	P	P	P	P
5. Akshay . M	P	P	P	P	P	P
6. Alan Sunny	AB	P	P	P	P	P
7. Alan Joe Porice	P	P	P	P	P	P
8. Anagh . K	P	P	P	P	P	P
9. Aswin T . S	P	P	P	P	P	P
10. Aswin Vinod . C	P	P	P	P	AB	P
11. Ayana . P . V	P	P	P	P	P	P
12. Dipraj . M	P	P	P	P	P	AB
13. Hirandeep . T	P	P	P	P	P	P
14. Joyal Saji	P	P	P	P	P	P
15. Jude Tomon George	P	P	P	P	P	P
16. Kevin Saji	P	AB	P	P	P	P
17. Kuan . K . V	P	P	P	P	P	P
18. Monial . C . Pradeep	P	P	P	P	P	P
19. Muhammed Sahl .	P	P	P	P	P	P
20. Revanthi P . V . K	P	P	P	P	P	P
21. Tom Jessan	P	P	P	P	AB	P
22. Vyskrav . K	P	P	AB	P	P	P

Dr. G. Gnan Devadhas.

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Day 7	Day 8	Day 9	Day 10	Day 11	Day 12	Day 13	Day 14	Day 15
29/9/22	6/10/22	13/10/22	20/10/22	27/10/22	3/11/22	10/11/22	17/11/22	24/11/22
P	P	P	P	P	P	P	P	AB
P	P	P	P	P	P	P	P	P
P	AB	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	AB	P	P	P
P	P	P	P	P	P	AB	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	AB	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
AB	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	AB	P	P	P	P	P	P	P
P	P	P	P	P	P	AB	P	P

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Analog Integrated ekts - Jinsa Mathew

	Day 1 18/8/22	Day 2 25/8/22	Day 3 1/9/22	Day 4 8/9/22	Day 5 15/9/22	Day 6 22/9/22
1 Adil. K						
2 Ajay. K. P	P	P	P	P	P	P
3 Akhil. M. A	P	P	P	P	P	P
4 Akshay Mohan	P	P	P	P	P	P
5 Akshay. M	P	P	P	P	P	P
6 Alan Sunny	AB	P	P	P	P	P
7 Alan Joe Prince	P	P	P	P	P	P
8 Anargh. K	P	P	P	P	P	P
9 Aswin T. S	P	P	P	P	P	P
10 Aswin Vinod. C	P	P	P	AB	P	P
11 Ayana. P. V	P	P	P	P	P	P
12 Dipuraj. M	P	P	P	P	P	AB
13 Hirandeep. T	P	P	P	P	P	P
14 Joyal Saji	P	P	P	P	P	P
15 Jude Tomon George	P	P	P	P	P	P
16 Kevin Saji	P	AB	P	P	P	P
17 Kuram K. V	P	P	P	P	P	P
18 Mrinal. C. Pradeep	P	P	P	P	P	P
19 Muhammed Sahl	P	P	P	P	P	P
20 Revanth P. V. K.	P	P	P	P	P	P
21 Tom Jesan	P	P	P	P	AB	P
22 Vyshnav. K.	P	P	AB	P	P	P

Jinsa Mathew

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Day 7	Day 8	Day 9	Day 10	Day 11	Day 12	Day 13	Day 14	Day 15
29/9/22	6/10/22	13/10/22	20/10/22	27/10/22	3/11/22	10/11/22	17/11/22	24/11/22
P	P	P	P	P	P	P	P	AB
P	P	P	P	P	P	P	P	P
P	AB	P	P	P	P	P	P	P
P	P	P	P	AB	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	AB	P	P
P	P	P	AB	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	AB	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	AB	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	P	P	P
P	P	P	P	P	P	AB	P	P

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Power Electronics - Prabin James

	Day 1 6/2/23	Day 2 13/2/23	Day 3 20/2/23	Day 4 27/2/23	Day 5 6/3/23	Day 6 13/3/23
1. Adil .k	/	/	/	/	/	/
2. Aray .k.P	/	/	/	/	/	/
3. Akhil .M.A	/	/	/	/	/	/
4. Akshas Mohan	AB	/	/	/	/	/
5. Akshay .M	/	/	/	/	/	/
6. Alan Sunny	/	/	/	/	/	/
7. Ales Joe Prince	/	/	/	/	AB	/
8. Anagh .k	/	AB	/	/	/	/
9. Aswin T.S	/	/	/	/	/	/
10. Aswin Vinod .C	/	/	/	/	/	/
11. Ayana .P.V	/	/	/	/	/	/
12. Dipraj .M	/	/	/	/	/	/
13. Hiandeep .T	/	/	/	/	/	/
14. Joyal Saji	/	/	AB	/	/	/
15. Jude Tomon George	/	/	/	/	/	/
16. Kevin Saji	/	/	/	/	AB	/
17. Kuan .k.V	/	/	/	/	/	/
18. Minal .C. Pradeep	/	/	/	/	/	/
19. Muhammed Sahl	/	/	/	/	/	/
20. Revanth .P.V.K	AB	/	/	/	/	/
21. Tom Jessan	/	/	/	/	/	/
22. Vyshnav .k.	/	/	/	/	/	/

Prabin James

~~Prabin~~ ~~Prabin~~ ~~Prabin~~ ~~Prabin~~ ~~Prabin~~ ~~Prabin~~

Day 7	Day 8	Day 9	Day 10	Day 11	Day 12	Day 13	Day 14	Day 15
20/3/23	27/3/23	10/4/23	17/4/23	24/4/23	8/5/23	15/5/23	22/5/23	5/6/23

/	/	/	/	AB	AB	/	/	/
/	/	/	/	/	/	/	/	/
/	/	/	/	/	/	/	/	/
/	/	/	/	AB	/	/	/	/
/	/	/	/	/	/	/	/	/
/	/	AB	/	/	/	/	/	/
/	/	/	/	/	AB	/	/	/
/	/	/	/	/	/	/	/	/
AB	/	/	/	/	/	/	/	/
/	/	/	/	/	AB	/	/	/
/	/	/	/	/	/	/	/	/
/	AB	/	/	/	/	/	/	/
/	/	/	AB	/	/	/	/	/
/	/	/	/	AB	AB	/	/	/
/	/	/	/	/	/	AB	/	/
/	/	/	/	/	/	/	/	/
/	/	AB	/	/	/	/	/	/
/	/	/	/	/	/	/	/	/

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Process Dynamics & Control - Dr. G. Ganu Devadhas

	Day 1 7/2/23	Day 2 14/2/23	Day 3 21/2/23	Day 4 28/2/23	Day 5 7/3/23	Day 6 14/3/23
1. Adil K	/	/	/	/	/	/
2. Ajay K.P	/	AB	/	/	/	/
3. Akhil M.A	/	/	/	/	/	/
4. Akshas Mohan	/	/	/	/	/	/
5. Akshay M	/	/	/	/	/	/
6. Alan Sunny	/	/	/	/	/	/
7. Alan Joe Prince	/	/	AB	AB	/	/
8. Anargh K	AB	/	/	/	/	/
9. Aswin T.S	/	/	/	/	/	/
10. Aswin Vinod C	/	/	/	/	/	/
11. Ayana P.V	/	/	/	/	/	/
12. Dipraj M	/	AB	/	/	/	/
13. Hirandeep T	/	/	/	/	AB	/
14. Jeyal Saji	/	/	AB	/	/	/
15. Jude Tomon George	AB	/	/	/	/	/
16. Kevin Saji	/	/	/	/	//	/
17. Kuan K.V	/	/	/	/	/	/
18. Moinal C. Pradeep	/	/	/	AB	/	/
19. Muhammed Sahl	/	/	/	/	/	/
20. Revanth P.V.K	/	/	/	/	/	AB
21. Tom Jessam	/	/	/	AB	/	/
22. Vyshnav K.	/	/	/	/	/	/

Dr. G. Ganu Devadhas

Digital Signal Processing - Dr. Jyoti Phadnis

Day 7	Day 8	Day 9	Day 10	Day 11	Day 12	Day 13	Day 14	Day 15
21/3/23	28/3/23	11/4/23	18/4/23	25/4/23	2/5/23	9/5/23	23/5/23	6/6/23
/	/	/	/	/	/	/	/	AB
/	/	/	/	/	/	AB	/	/
/	/	/	/	/	/	/	/	/
/	/	AB	AB	/	/	/	/	/
AB	/	/	/	/	/	/	/	/
/	/	/	/	/	/	AB	/	/
/	/	/	/	/	/	/	/	/
/	/	/	/	/	/	/	/	/
/	/	/	/	/	/	/	/	/
/	/	AB	AB	/	/	/	/	/
/	/	/	/	AB	AB	/	/	AB
/	/	/	/	/	/	/	/	/
AB	/	/	/	/	/	/	/	/
AB	/	/	/	/	/	AB	/	/
/	/	/	/	/	/	/	/	/
/	/	AB	/	/	/	/	/	/
/	/	/	/	/	/	/	/	/
/	/	/	/	/	/	/	AB	/
/	/	AB	AB	/	/	/	/	/

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Digital Signal Processing - Dr. Jayesh George

	Day 1 8/2/2023	Day 2 15/2/23	Day 3 22/2/23	Day 4 1/3/23	Day 5 8/3/23	Day 6 15/3/23
1. Adil - K	/	/	/	/	AB	/
2. Ajay - K.P	/	/	/	/	/	/
3. Akhil - M.A	AB	/	/	/	/	/
4. Akshas Mohan	/	/	/	AB	/	/
5. Akshay - M	/	AB	/	/	/	/
6. Alan Sunny	/	/	/	/	/	/
7. Alen Joe Prince	/	/	/	/	/	/
8. Anargh - K	/	/	/	/	/	/
9. Aswin T.S	/	/	/	/	/	/
10. Aswin Vinod - C	/	/	/	/	/	/
11. Ayana - P.V	/	/	AB	/	/	/
12. Dipuraj - M	AB	/	/	/	/	/
13. Hirandeep - T	/	/	/	/	/	/
14. Joyal Saji	/	/	/	/	/	AB
15. Jude Tomon	/	/	/	/	/	/
16. Kevin Saji	/	/	/	/	/	/
17. Kucam - K.V	/	/	/	/	/	/
18. Minal - C. Pradeep	AB	/	/	/	/	/
19. Muhammed Sahl	/	/	/	/	/	/
20. Revanth P.V.K	/	/	/	/	/	/
21. Tom Jessan	/	/	/	/	/	/
22. Vyshnav - K.	/	/	/	AB	/	/

Jayesh George

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Industrial Safety Engineering - Process Safety Management

DA F2

Day 7	Day 8	Day 9	Day 10	Day 11	Day 12	Day 13	Day 14	Day 15
22/3/23	29/3/23	12/4/23	19/4/23	26/4/23	10/5/23	17/5/23	24/5/23	7/6/23
/	/	/	/	/	/	/	/	/
/	/	/	/	/	/	/	AB	/
/	AB	/	/	/	/	/	/	/
/	/	/	/	/	AB	/	/	/
/	/	/	/	/	/	/	/	/
/	/	/	/	AB	/	/	/	/
/	/	/	/	/	/	/	/	AB
/	/	/	/	/	/	/	/	/
/	/	/	/	/	/	/	/	/
/	/	AB	/	/	/	/	/	/
/	/	/	/	/	/	/	AB	/
/	/	/	/	/	/	/	/	/
/	/	/	AB	/	/	/	/	/
/	AB	/	/	/	/	/	/	/
/	/	/	/	/	/	/	/	AB
/	/	/	/	/	AB	/	/	/
/	/	/	/	/	/	AB	/	/
/	/	/	/	/	/	/	/	/

~~Day 7~~ ~~Day 8~~ ~~Day 9~~ ~~Day 10~~ ~~Day 11~~ ~~Day 12~~ ~~Day 13~~ ~~Day 14~~ ~~Day 15~~

SL. NO.	NAME OF THE STUDENT	FACULTY
1	AARSHA ANIL	Ms. Derroll David
2	ALAN THOMAS	
3	ALANA ANCE JOHN	
4	AMRITHA PRADEEP	
5	ANN RIYA JAISON	
6	AUSTINE S MANUEL	
7	CAMAY JILLS	
8	CHANDHANA RAJEEVAN	
9	CHRISTEENA J ROSE	
10	DENI THOMAS	
11	DEVA NAIR	
12	HAMNA RAFEEQ	
13	JASHLIN S SIMON	
14	KIRAN PRASAD PP	
15	MARWA ABDUL RAZAK	
16	MAZIN MURSHID	
17	MOHAMMED ZAIN RAFEEQU	
18	NANDHAJ VIJAYAN	
19	NAVANEETHA P NAMBIAR	
20	RIDHA GAFOOR	
21	ROSE BENNY	
22	SHARON RAJISH JOSEPH	
23	SHYAMITH MANNAMBETH	
24	SNEHAL VINOD T	
25	SOURAV C	
26	STEPHIN LIJI	
27	THAHA MUHAMMED YASEEN	
28	THALHAH ANAS	
29	VAIBHAV RAJESH	
30	VAISHAKH P	
31	VISHNUPRIYA N	

Timestamp	Email Address	Name of the faculty	Subject Code	Subject Name	Date	Hour	Total Students	No. of absentees	Roll No. of absentees	Topic Covered	Sample work done by the students (1 MB max)	
6-12-2022 12:26:02	ambilimacse@vjec.ac	Ambilil M. A.	CST204	DBMS	10-05-2022		1	32	1	2 ER Diagram	https://drive.google.com/open?id=1e8B8nrg4L7yJhmkLzYcFyAooZYET	
6-12-2022 12:37:09	ambilimacse@vjec.ac	Ambilil M. A.	CST204	DBMS	28-05-2022		1	32	6	2,7,12,22,23,31	Relational Algebra	https://drive.google.com/open?id=1qRpb0Zc0Wedz8rG4KUCEK64zzy2
6-12-2022 12:38:26	ambilimacse@vjec.ac	Ambilil M. A.	CST204	DBMS	08-06-2022		1	32	6	2,6,12,16,22,28	SQL	https://drive.google.com/open?id=1w3HxJVwqoKfAAsPz2SP4FfaJb8eHj
6-12-2022 15:42:30	neenaphalgun@vjec.a	Neena V V	CST206	Operating System	20-05-2022		4	32	6	15,16,17,27,28,32	Process Creation	https://drive.google.com/open?id=1FVWXLJCEEdq9E8rabOzrjC8F6-RGw
6-12-2022 15:44:41	neenaphalgun@vjec.a	Neena V V	CST206	Operating System	27-05-2022		3	32	6	2,12,22,23,25,29	Process Scheduling	https://drive.google.com/open?id=1tqWwKlC3e8GJuzrWfVvVQuU8e9E
6-13-2022 11:07:15	abdulatheef@vjec.ac.i	Abdul Latheef	CST 202	Comouter organization	10-05-2022		6	31	1	2	shft register and bina	https://drive.google.com/open?id=17Zm9QpdcQWc4DMHc7471u8XNcmdb
6-13-2022 11:17:37	abdulatheef@vjec.ac.i	Abdul Latheef	CST 202	Computer organization	28-05-2022		6	32	13	2,7,11,12, 16,22,23,25,	status register	https://drive.google.com/open?id=1vFhgFFDPIRaa8fW1XjDxOwNB4n3L

VIMAL JYOTHI ENGINEERING COLLEGE, CEMPERI
DEPARTMENT OF CIVIL ENGINEERING
Tutorial Details- S3 CE (2022-26 BATCH)

Subject	Name of faculty	Date	No. of students present	Topics covered	Absent students details (if any)	Material details(google drive link)
CET201 MECHANICS OF SOLIDS	MIDHUN KRISHNAN	15/09/2023	27	Stress-strain diagram of mild steel, Factor of safety	NIL	
		06-10-2023	28	Temperature effects, temperature stress in composite bars, Shear stress and shear strain	NIL	
		07-10-2023	27	Modulus of rigidity, simple shear, punching shear	(Roll No: 2, Abhijith Salu)	
		13/10/2023	26	Instantaneous stress in bars due to gradual, sudden and impact loads	Roll No: 2 - Abhijith Salu, Roll No: 20 Sandra Chandran	
MAT201 PDE AND COMPLEX ANALYSIS	DIVYA THOMAS	11-09-2023	26	conjugate of complex function	12	
		18/9/23	26	real part and imaginary part	22	
		10-09-2023	25	conformal mapping	11,22,25	
CET 203 FLUID MECHANICS AND HYDRAULICS	ATHIRA RAJENDRAN	18/09/23	28	Gauge pressure vacuum pressure	NIL	https://drive.google.com/drive/folders/13UeYUj1S-T1WtLa_GFI_t4p9OZGwUSs?usp=sharing
		25/09/23	23	Pressure measurement	1,2,27,28	
		09/10/1023	28	Buoyancy	NIL	
		16/10/23	24	Metacentric height	8,11,22,23	

EET401: ADVANCED CONTROL SYSTEM

Date	Subject Code	Subject Name	Name of Faculty	Topics Covered	Roll number of students in each batch	Proof Material folder Link
11-8-23	EET401	ADVANCED CONTROL SYSTEM	ATHIRA M THOMAS	Introduction to state space and state model concepts, State equation of linear continuous time systems	1-31	https://drive.google.com/drive/folders/1uWqGL1reh8jXGnWJs3NaBdVvjQk1ySui?usp=sharing
16-8-23	EET401	ADVANCED CONTROL SYSTEM	ATHIRA M THOMAS	Examples of electrical circuits and dc servomotors	1-31	
22-8-23	EET401	ADVANCED CONTROL SYSTEM	ATHIRA M THOMAS	Controllable and observable companion forms	1-31	
23-8-23	EET401	ADVANCED CONTROL SYSTEM	ATHIRA M THOMAS	Diagonal Canonical forms	1-31	
14-9-23	EET401	ADVANCED CONTROL SYSTEM	ATHIRA M THOMAS	Computation of state transition matrix using Laplace transform and Cayley Hamilton method	1-31	
21-9-23	EET401	ADVANCED CONTROL SYSTEM	ATHIRA M THOMAS	Solution of time response of autonomous systems and forced systems	1-31	
30-9-23	EET401	ADVANCED CONTROL SYSTEM	ATHIRA M THOMAS	Phase variable form and Diagonal canonical form	1-31	
04-10-2023	EET401	ADVANCED CONTROL SYSTEM	ATHIRA M THOMAS	Computation of state transition matrix using Laplace transform and Cayley Hamilton method	1-31	
6-10-23	EET401	ADVANCED CONTROL SYSTEM	ATHIRA M THOMAS	Controllability & observability, Kalman's tests	1-31	
6-10-23	EET401	ADVANCED CONTROL SYSTEM	ATHIRA M THOMAS	Gilbert's and PBH tests,	1-31	